

ময়মনসিংহ পলিটেকনিক ইন্সটিটিউট

মেকানিক্যাল টেকনোলজি

**Practical on the subject of  
Mechatronics (67076)**

**Presented by –  
Inzamam ul Islam  
Workshop Super (Mechanical)**

Today's Exp. No. : 01

Name of the Experiment:

মেকাট্রনিক্স বিষয়ের বেসিক যন্ত্রাংশের  
পরিচিতি

Name of the Experiment: Construct a control system incorporating electrical, mechanical and electronic components.

# Sensors and Actuators

- **Sensor**

A device that converts an environmental condition into an electrical signal.

- **Actuator**

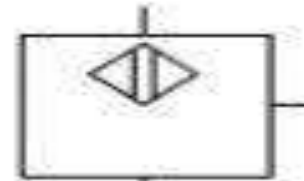
A device that converts a control signal (usually electrical) into mechanical action (motion).

(Taken together, sensors, actuators, controllers, and power supply form the basic elements of a control system.)

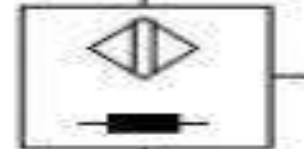
# *Block symbols for Proximity sensors*

## Block symbols for proximity sensors

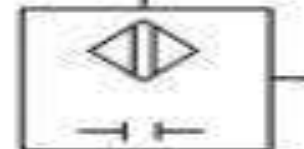
proximity sensor, general



proximity sensor, inductive



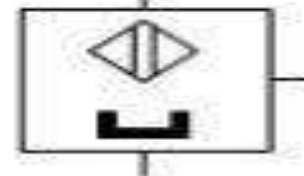
proximity sensor, capacitive



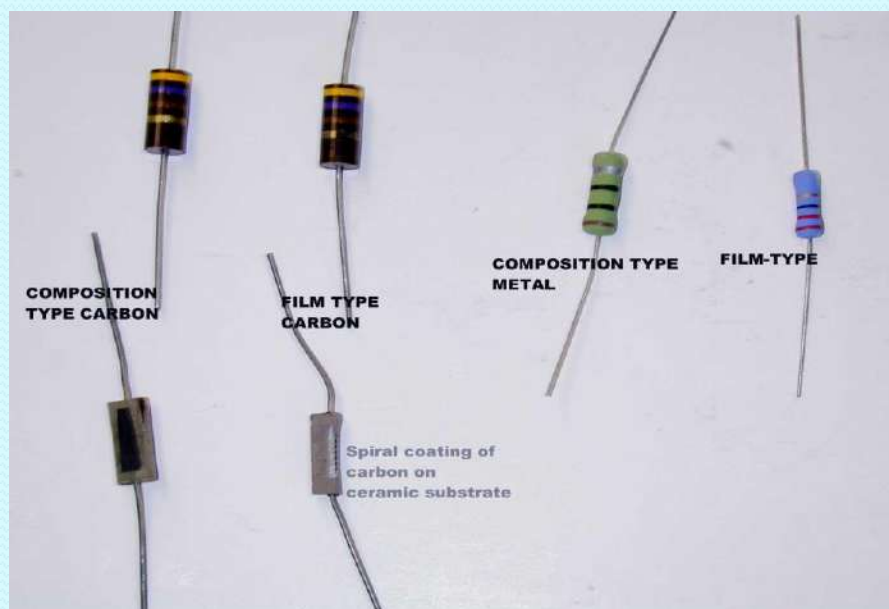
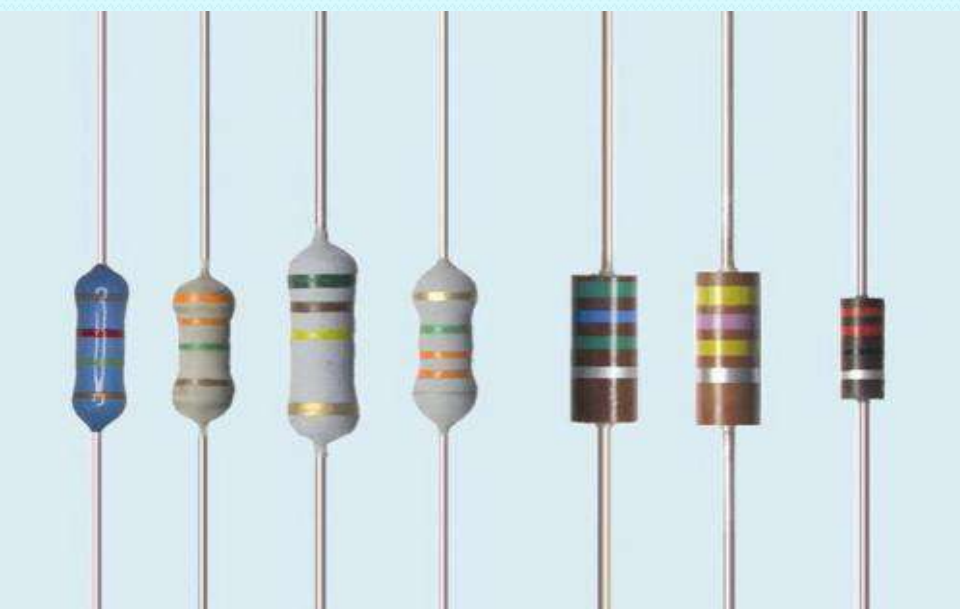
proximity sensor, optical



proximity sensor, magnetic



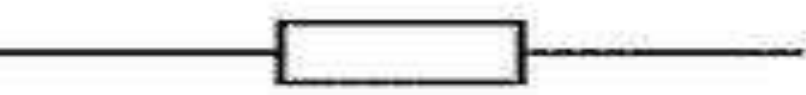
# ❖ রেজিস্টারের চিত্র



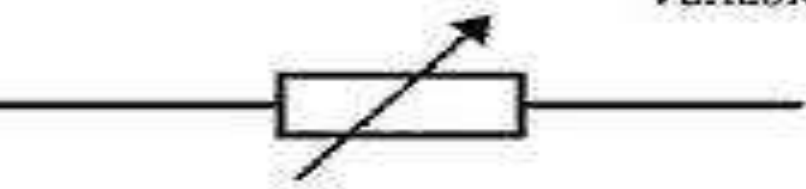
# ❖ রেজিস্টারের প্রতিক

## Resistor circuit symbols

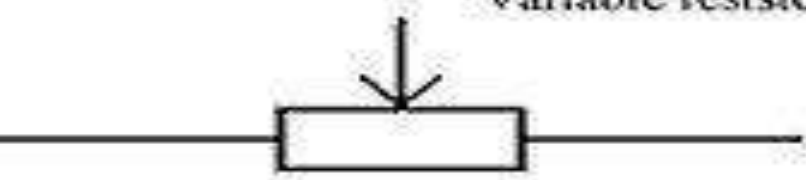
Fixed value resistor



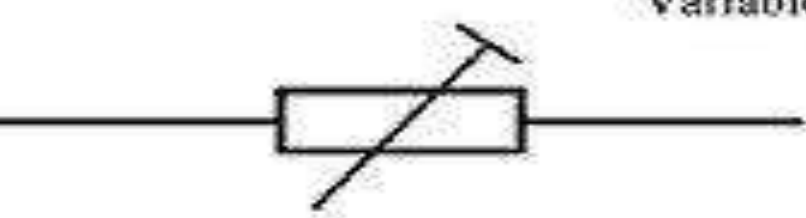
Variable resistor - Rheostat



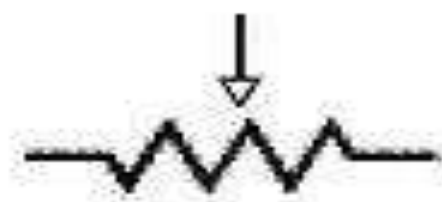
Variable resistor - Potentiometer



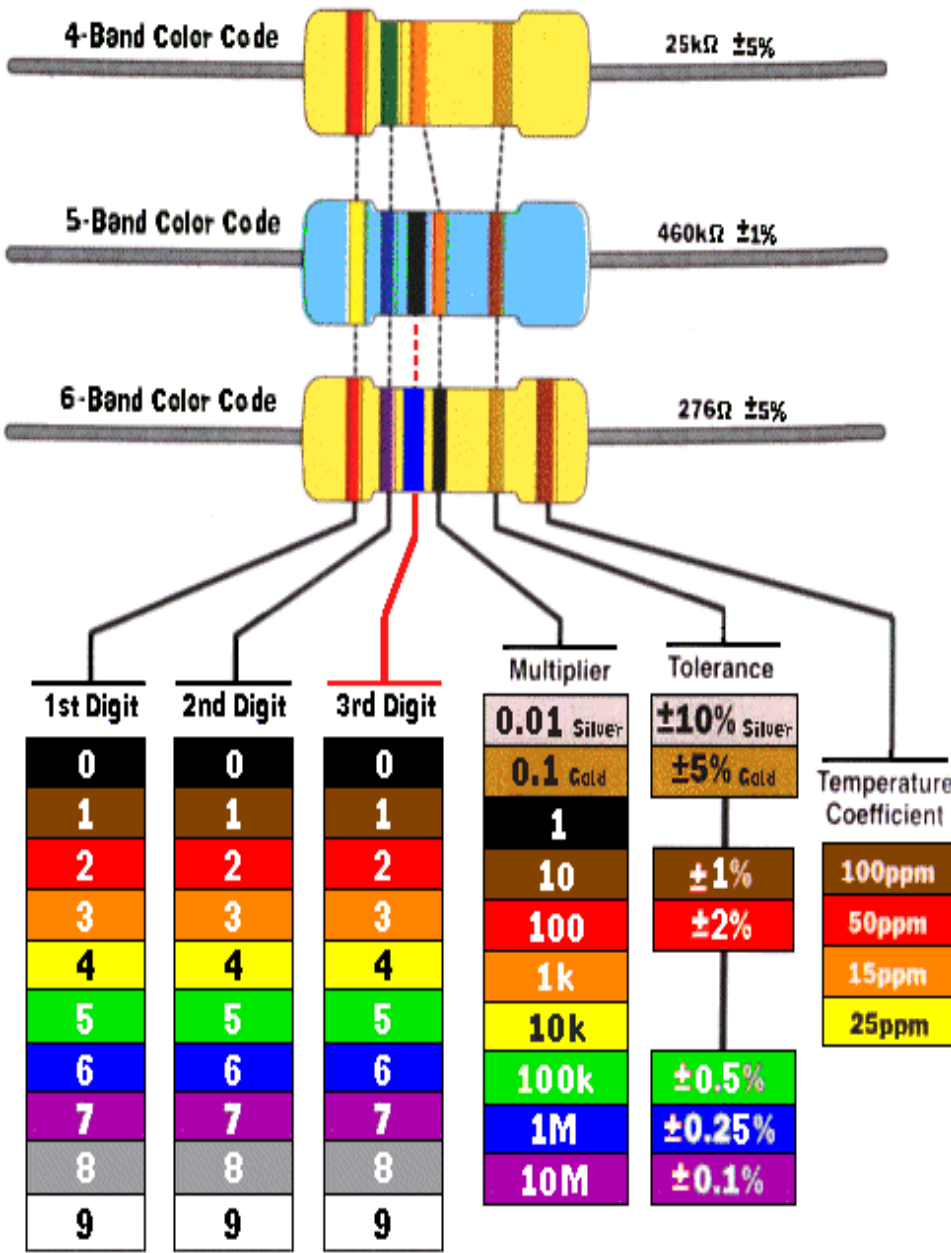
Variable resistor - Preset



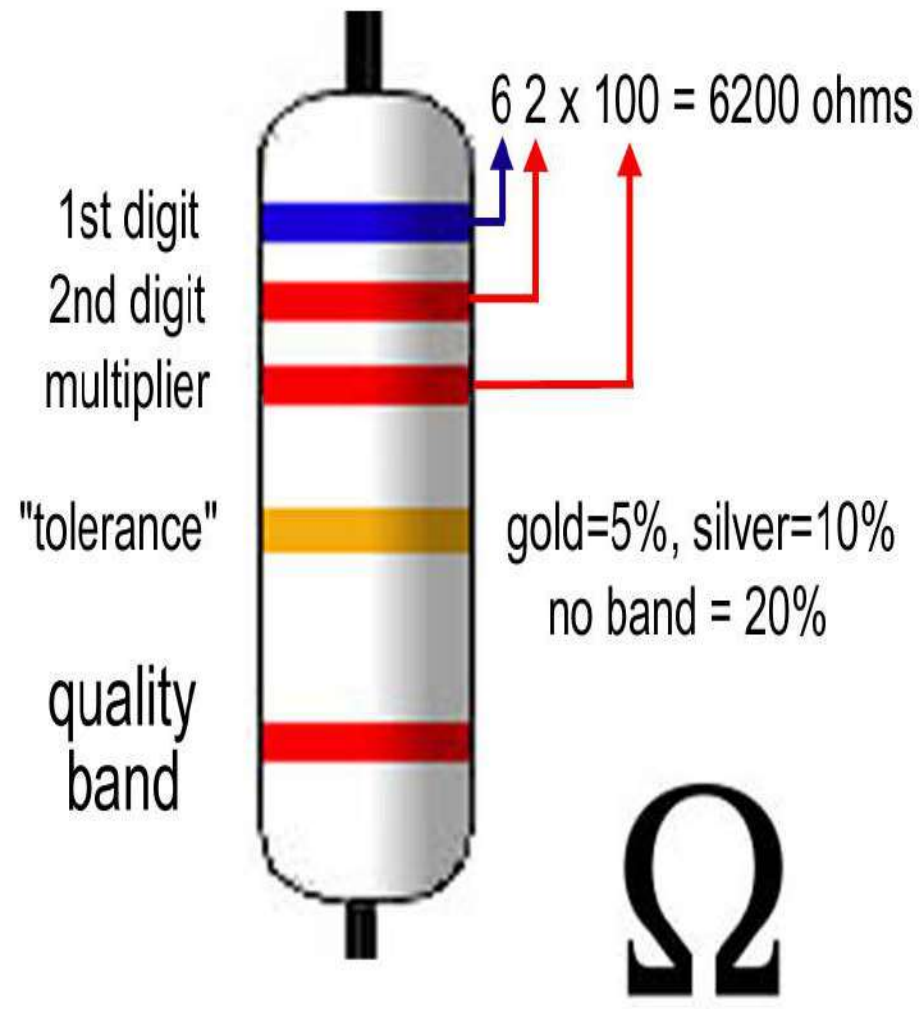
## Old resistor symbols



# ❖ রেজিস্টার ও কালার কোড দেখে মান নির্ণয়



standard carbon resistor



# ❖ ভ্যারিঅ্যাবল (পরিবর্তনশীল মান) রেজিস্টরের চিত্র

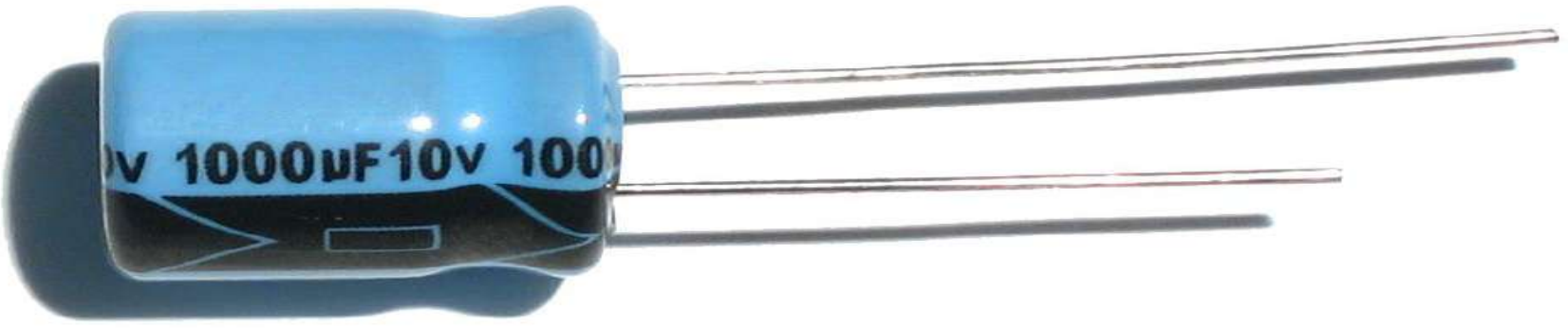




# ❖ ক্যাপাসিটরের চিত্র



# ❖ ক্যাপাসিটরের চিত্র

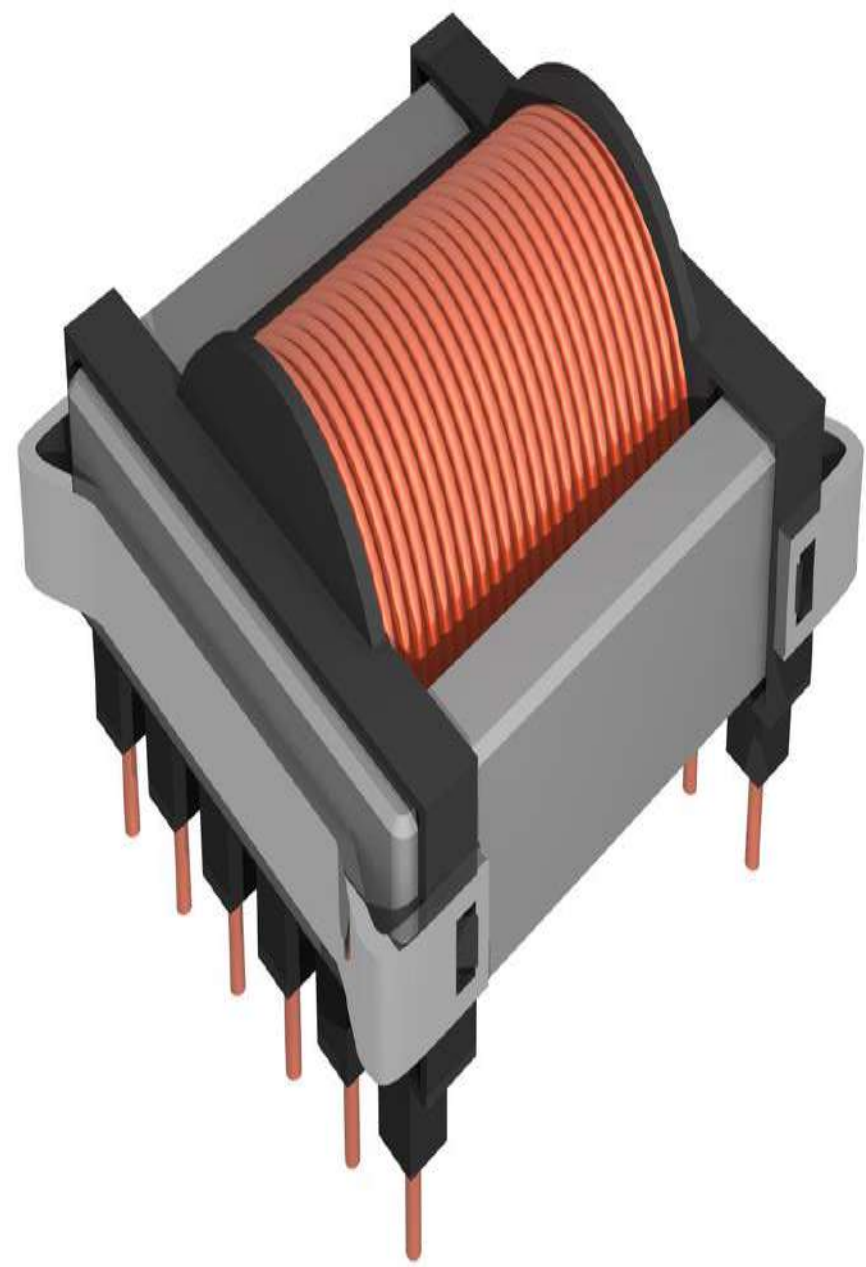




# ❖ ইন্ডাক্টরের চিত্র



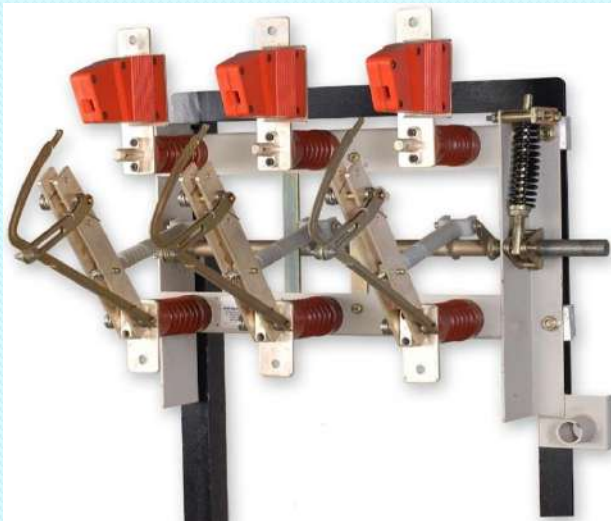
# ❖ ইন্ডাক্টরের চিত্র



# ❖ স্লো-ব্রেক সুইচ



# ❖ কুইক-ব্রেক সুইচ



# Ammeter

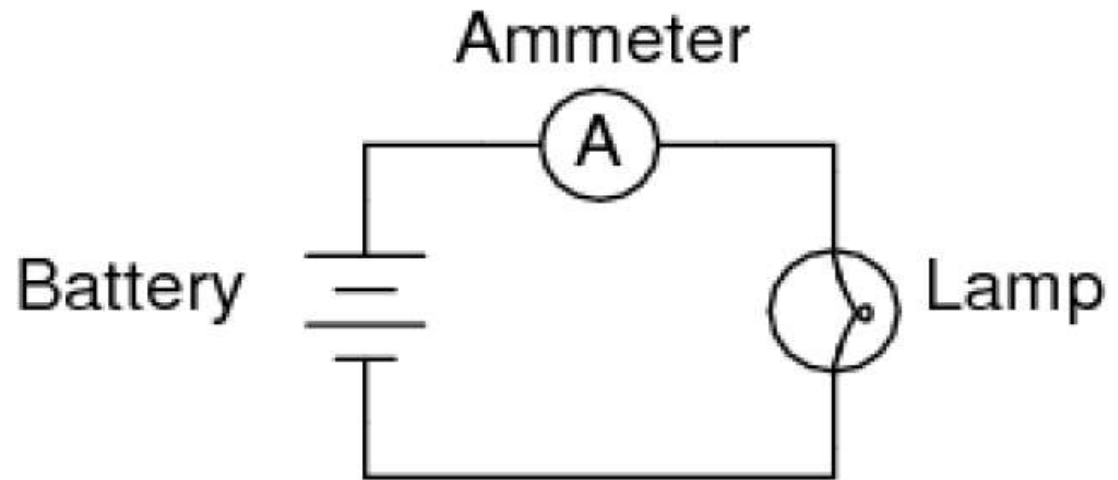
- ❖ Measures The amount of Current flow through the circuit

## Types:

1. DC Ammeter
2. AC Ammeter

## Schematic Diagram of Ammeter:

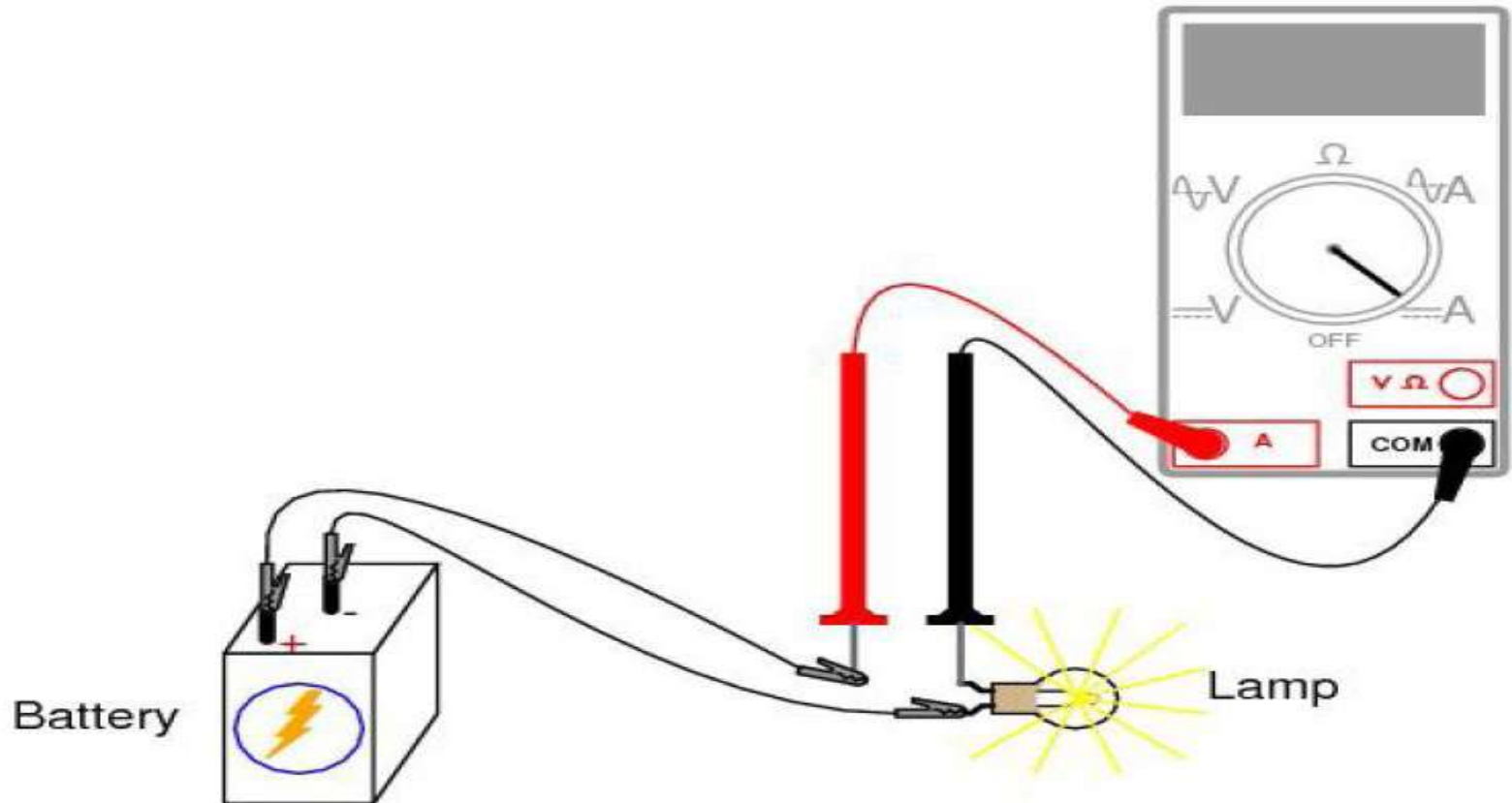
Ammeter  
Should be  
always  
connected  
in Series  
with Load





# ❖ অ্যামিটারের সংযোগ চিত্র

## Connection Diagram of Ammeter:

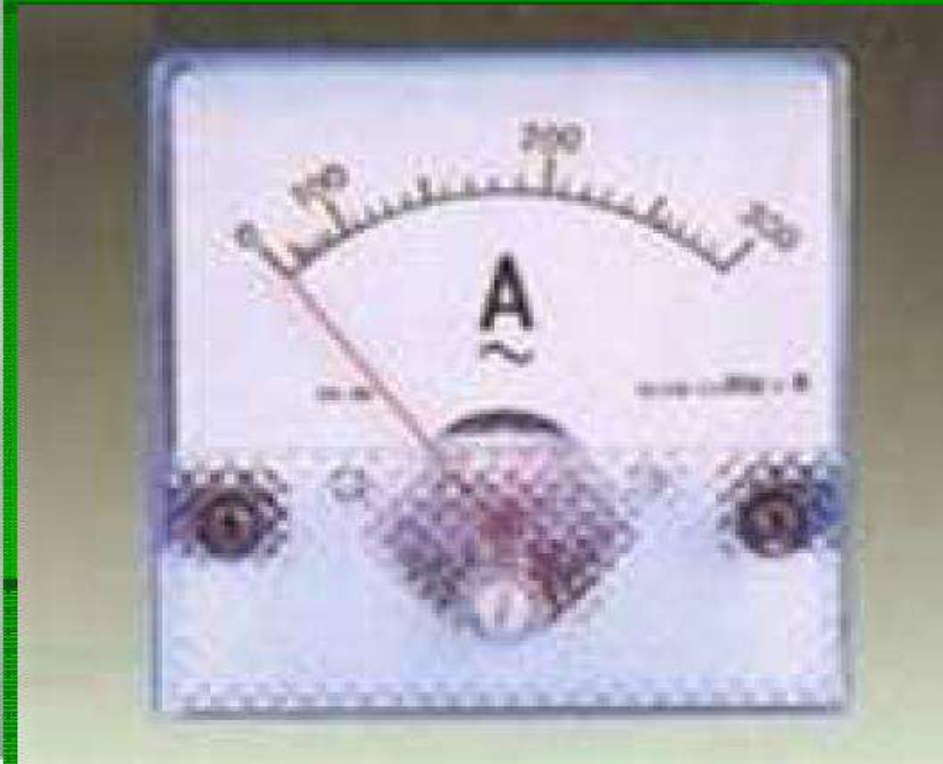


ডিসি ও এসি অ্যামিটারের চিত্র (চলবে.....।)

# Pictorial View of DC & AC Ammeter

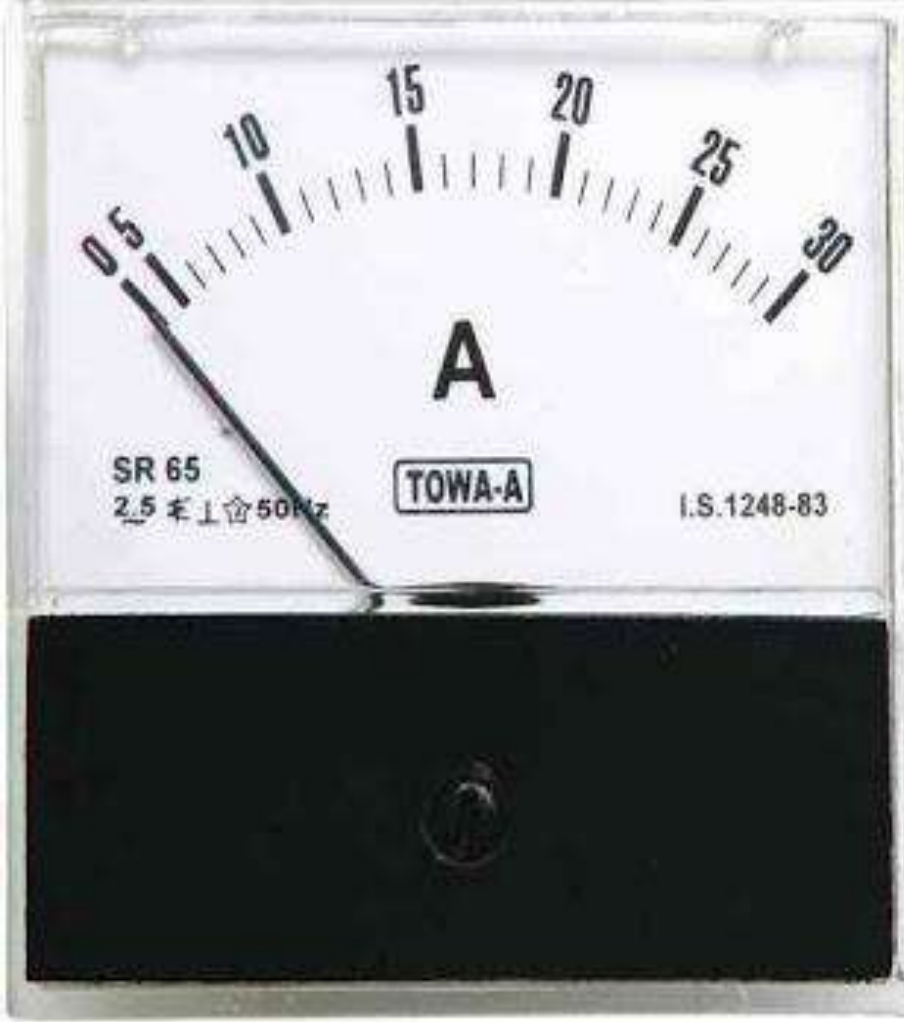


DC Ammeter



AC Ammeter

# ❖ ডিসি ও এসি অ্যামিটারের ছবি (চলবে....)



এসি অ্যামিটার



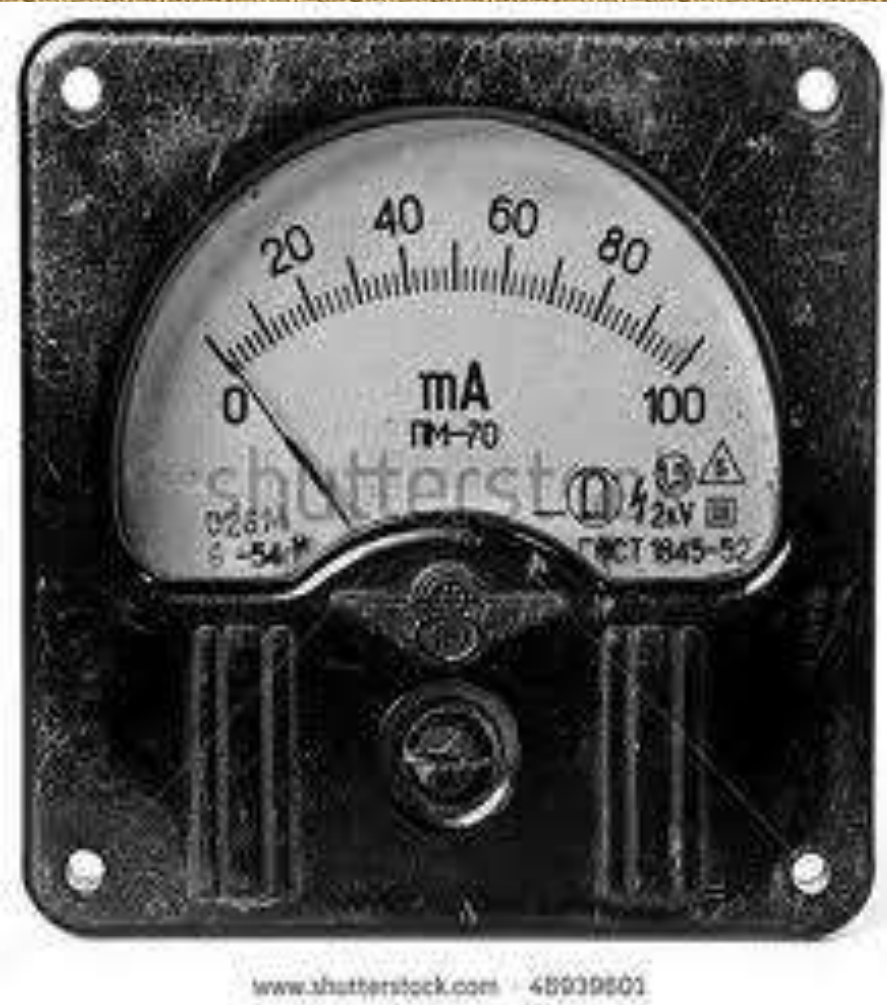
ডিজিটাল অ্যামিটার

# ❖ ডিসি ও এসি অ্যামিটারের ছবি (চলবে....)



ডিসি আমিটার

# ❖ ডিসি ও এসি অ্যামিটারের ছবি



Old Type

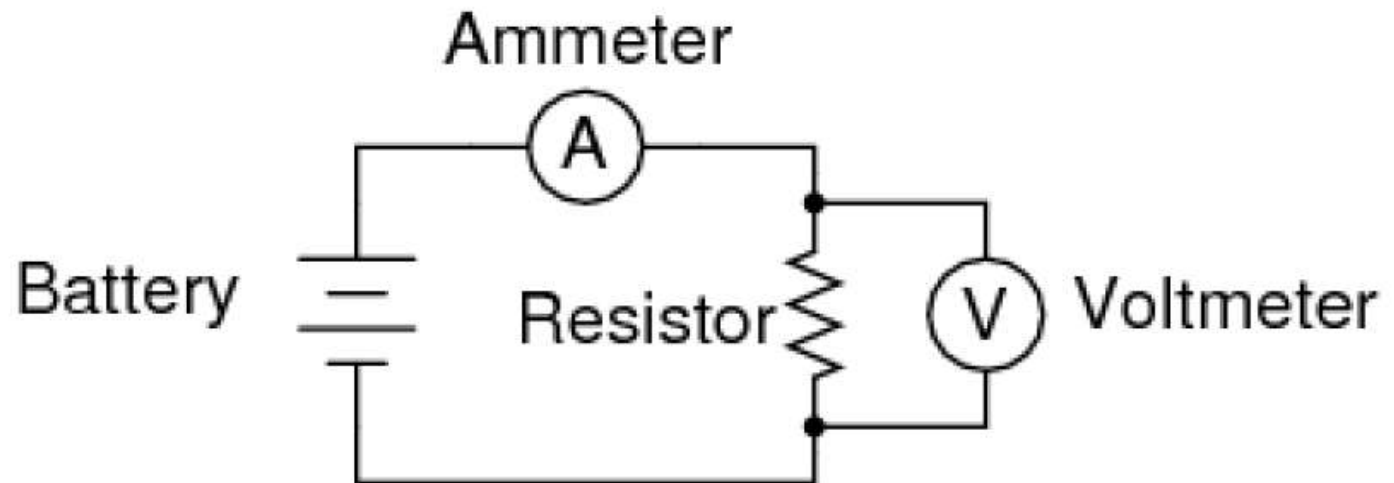
# Voltmeter

- ❖ used for measuring Electrical potential difference between two points in an electric circuit

## Types:

1. DC Voltmeter
2. AC Voltmeter

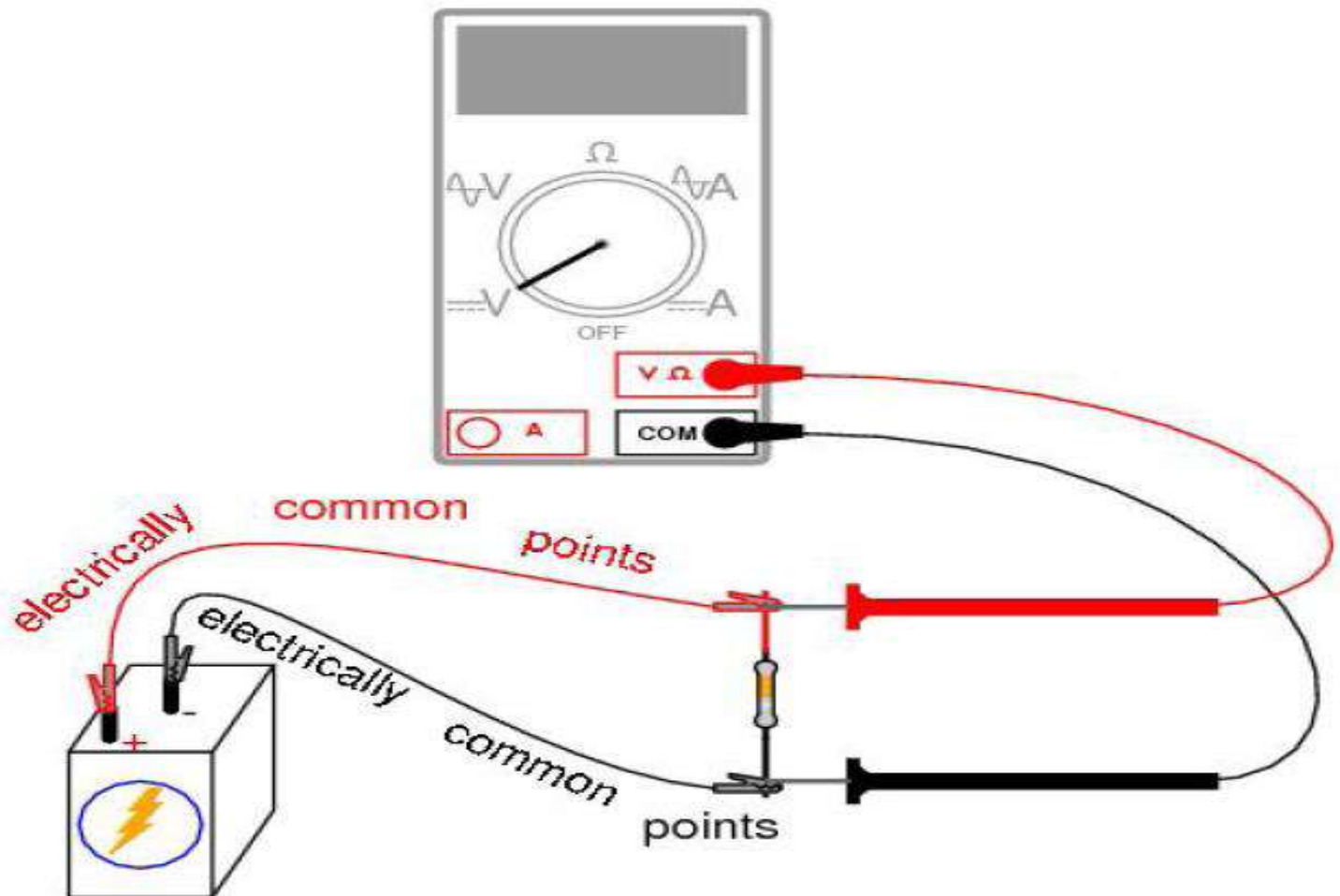
## Schematic Diagram of Voltmeter:



**Voltmeter must be connected in Parallel with Load**

# ❖ ভোল্টমিটারের সংযোগ চিত্র

## Connection Diagram of Voltmeter:





❖ ডিসি ও এসি ভোল্টমিটারের ছবি(চলবে....)

# Pictorial View of DC & AC Voltmeter

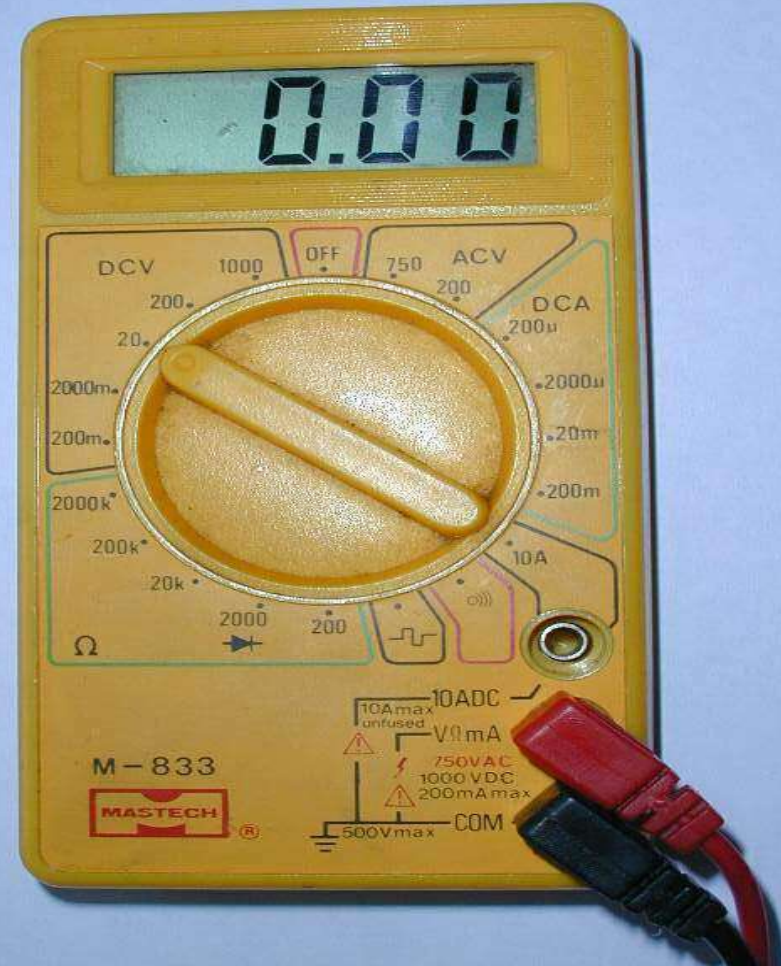


DC Voltmeter



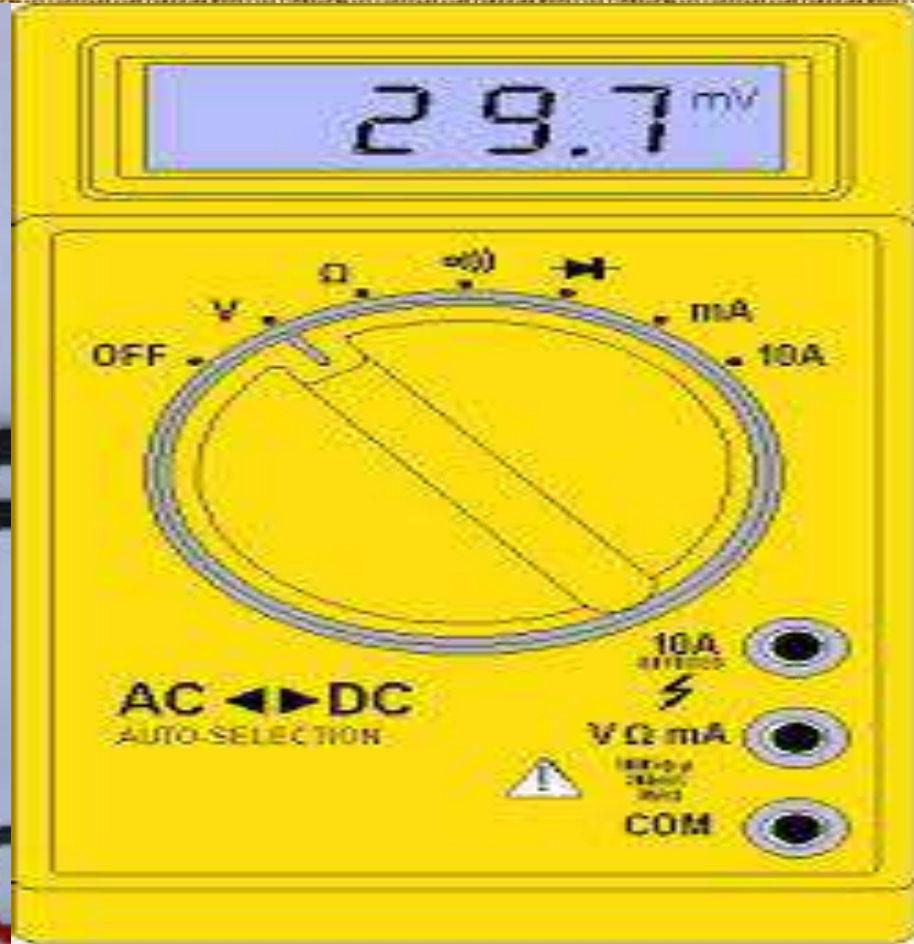
AC Voltmeter

# ❖ ডিসি ও এসি ভোল্টমিটারের ছবি(চলবে....)



ডিজিটাল ভোল্টমিটার

# ❖ ডিসি ও এসি ভোল্টমিটারের ছবি(চলবে....)



ডিজিটাল ভোল্টমিটার

# ❖ ডিসি ও এসি ভোল্টমিটারের ছবি(চলবে...)



ডিজিটাল ভোল্টমিটার

# ❖ ডিসি ও এসি ভোল্টমিটারের ছবি(চলবে....)



ডিসি ভোল্টমিটার

# ❖ ডিসি ও এসি ভোল্টমিটারের ছবি(চলবে....)



ডিসি ভোল্টমিটার

# ❖ ডিসি ও এসি ভোল্টমিটারের ছবি



এসি ভোল্টমিটার

# ❖ মাল্টিমিটারের ছবি(চলবে.....)

## Multimeter/AVO meter:



Analog multimeter



Digital multimeter

➤ মাল্টিমিটার দিয়ে ভোল্টেজ, কারেন্ট, রোধ তিনটিই পরিমাপ করা যায়



# ❖ মাল্টিমিটারের ছবি(চলবে.....)



**Analog Type**

# ❖ মাল্টিমিটারের ছবি



Digiital Type

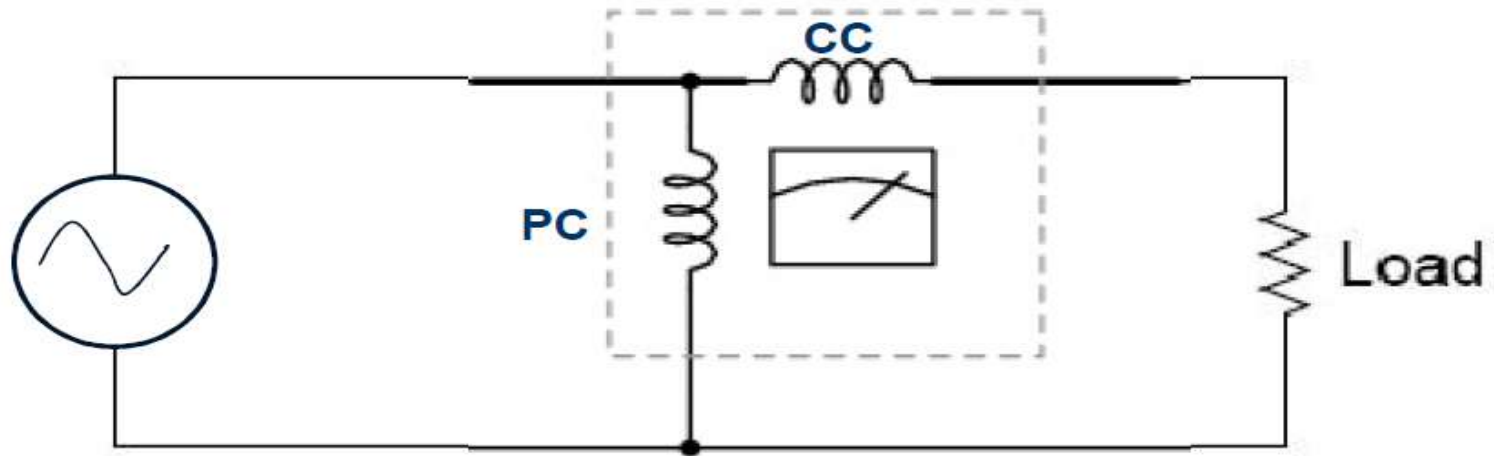
# Wattmeter

Measures the Electric power in watts

## Types:

1. Analog Wattmeter
2. Digital Wattmeter

## Schematic Diagram of Wattmeter:



Measured Power,  $P = VI \cos\theta$

$\theta =$  angle between  $v$  and  $i$

❖ ওয়াটমিটারের ছবি(চলবে.....)

# Pictorial View of Wattmeter:



(B)

# ❖ ওয়াটমিটারের ছবি(চলবে.....)



<http://www.mcpsh.com>

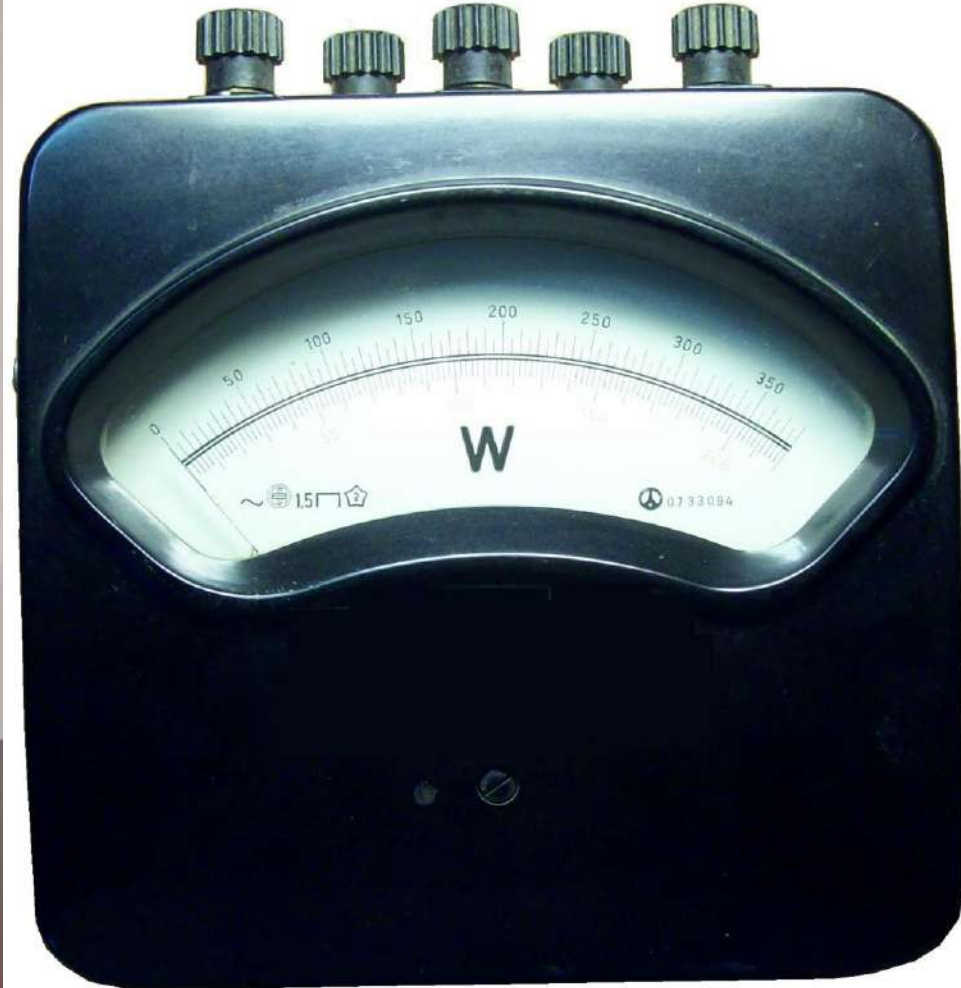
ডিজিটাল ওয়াট মিটার

# ❖ ওয়াটমিটারের ছবি (চলবে.....)



ডিজিটাল ওয়াট মিটার

# ❖ ওয়াটমিটারের ছবি



Old Type(Analog)



# ❖ ডিসি পাওয়ার সাপ্লাইয়ের ছবি



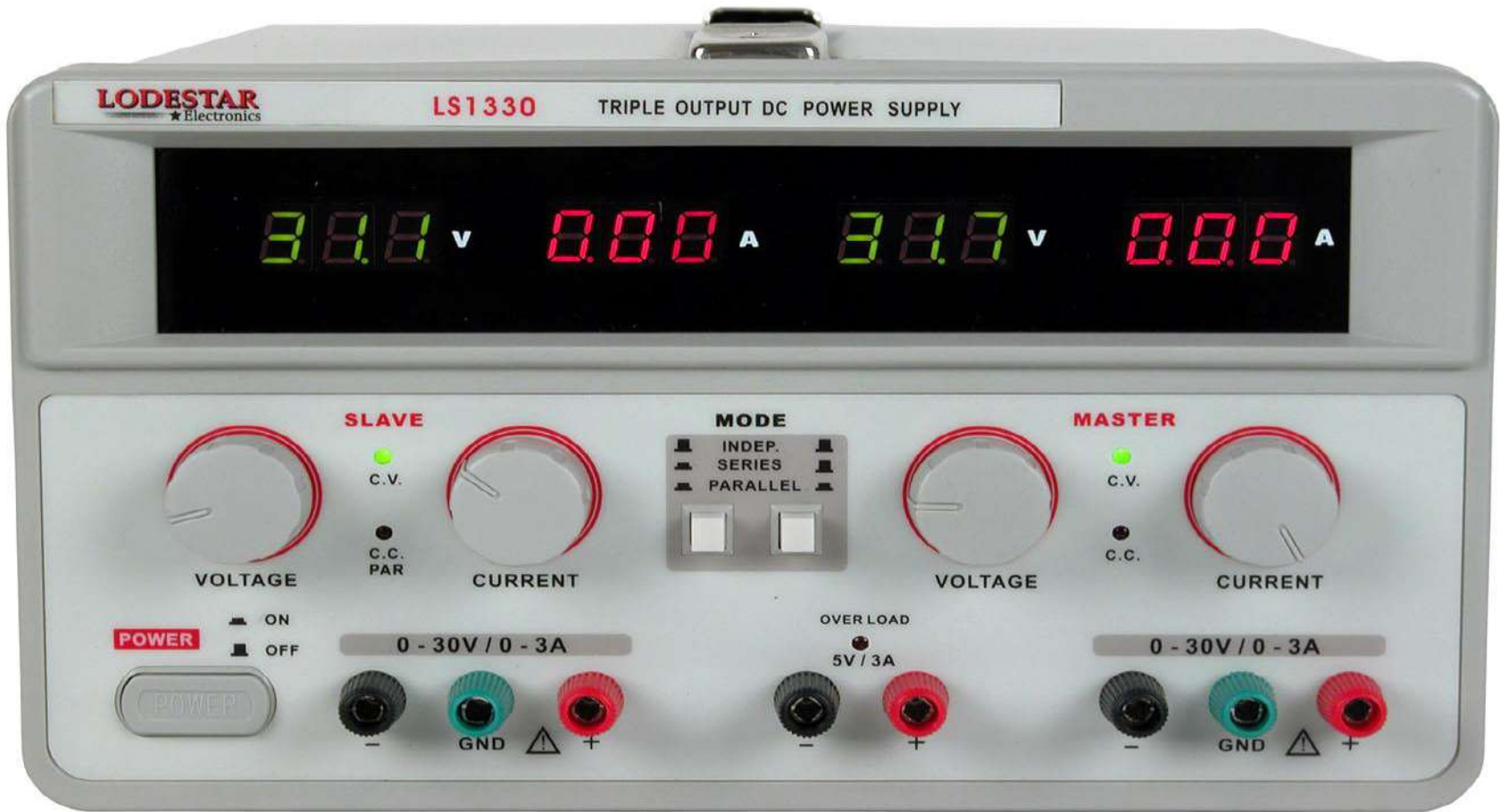
<http://www.mcps.com> > more details

<http://www.mcps.com>

# ❖ ডিসি পাওয়ার সাপ্লাইয়ের ছবি



# ❖ ডিসি পাওয়ার সাপ্লাইয়ের ছবি



Dual port

# ধন্যবাদ



শুভেচ্ছা

ও

স্বাগতম

মহাম্মদ সাদাত উল্লাহ

# Today's Exp. No. : 02

Name of the Experiment:

রিলে, টাইমার ও ম্যাগনেটিক কন্ট্রোল এবং সেন্সর এর  
কার্যপ্রণালী পরীক্ষণ

Name of the Experiment: **Function of Relay, Timer  
Magnetic contact & sensor with application**

Relay: Relay একটি electrically operated switch. অনেক  
রিলে Electromagnet ধর্মের ভিত্তিতে কাজ করে।

### Relay type:

- Latching Relay ,
- Reed Relay,
- Mercury Relay,
- Mercury-wattted Relay,
- Polarized Relay,
- Machine tool Relay,
- Co axial Relay,
- contactor Relay,
- Solid-state Relay,
- Solid-state contactor Relay,
- Buchholr Relay,
- Forced-guided Relay,
- Contaces Relay,
- Over load Relay,
- Proctaction vacuum Relay অন্যতম।

# Construction of Relay

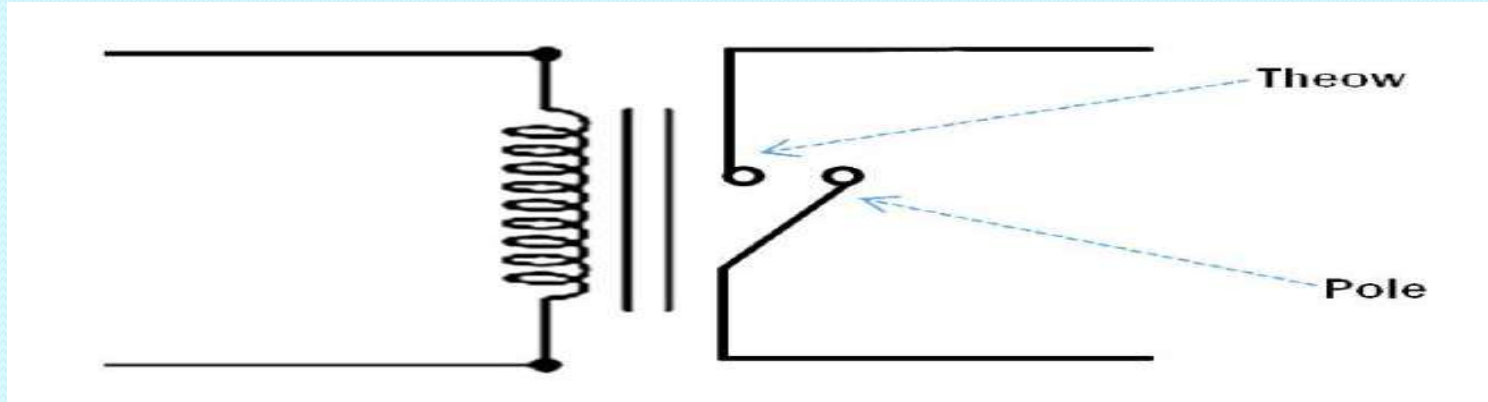
Relay সাধারণত Relay, coil, pole & throw এর সমন্বয়ে গঠিত।

নিচে উল্লেখিত Relay এর পদবী গুলো বেশি ব্যবহৃত হয়...

- SPST: (Single Pole Single Throw)
- SPDT: (Single Pole Double Throw)
- DPST: (Double Pole Single Throw)
- DPDT: (Double Pole Double Throw):

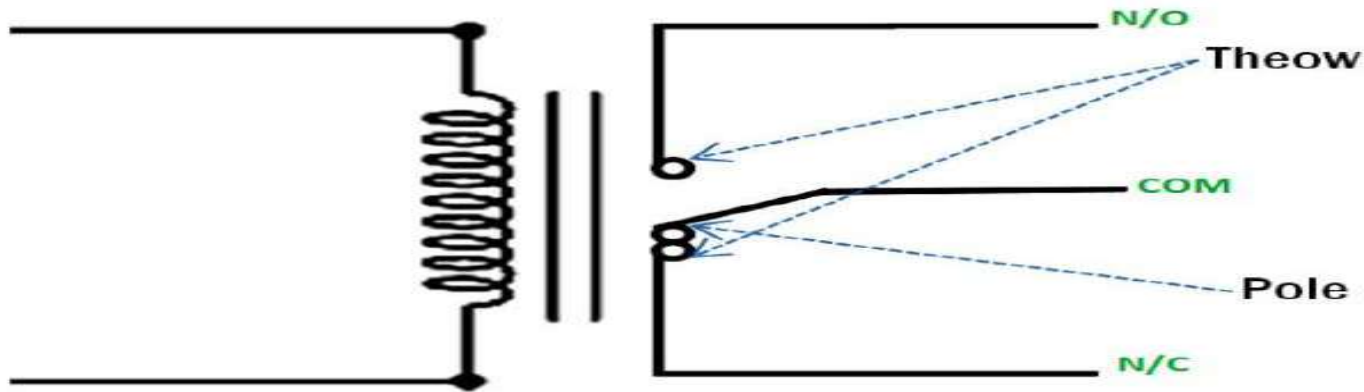


# SPST: (Single Pole Single Throw)



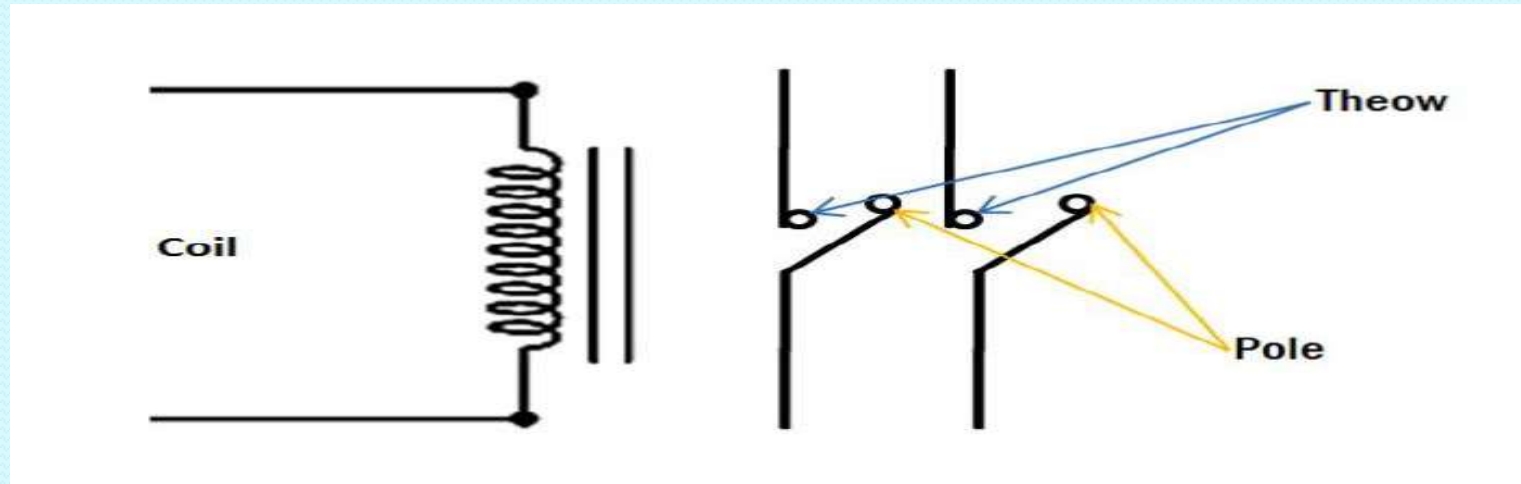
এই Relay এর pin সংখ্যা থাকে ৪টি এই ৪টি pin এর মধ্যে ২টি pin থাকে coil এর জন্য, যেখানে supply দেওয়া হয়, এবং ২টি pin switching এর জন্য ব্যবহৃত হয়, যাদের একটি pole এবং একটি throw থাকে।

# SPDT: (Single Pole Double Throw)



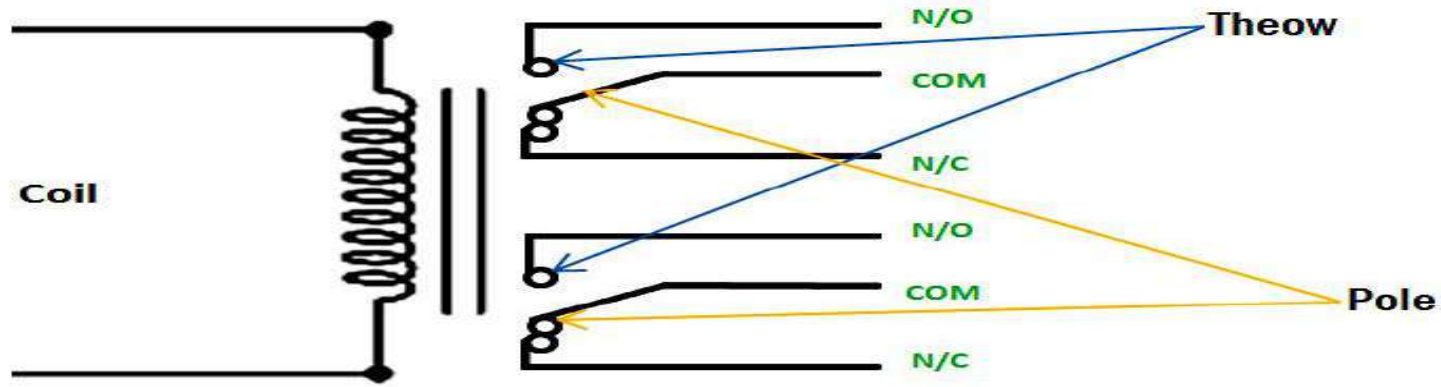
- এই Relay এর pin সংখ্যা থাকে ৫টি, এই ৫টি pin এর মধ্যে ২টি pin থাকে coil এর জন্য, যেখানে supply দেওয়া হয় এবং ৩টি pin switching এর জন্য ব্যবহৃত হয়, যাদের একটি pole এবং দুইটি throw থাকে।

# DPST: (Double Pole Single Throw)



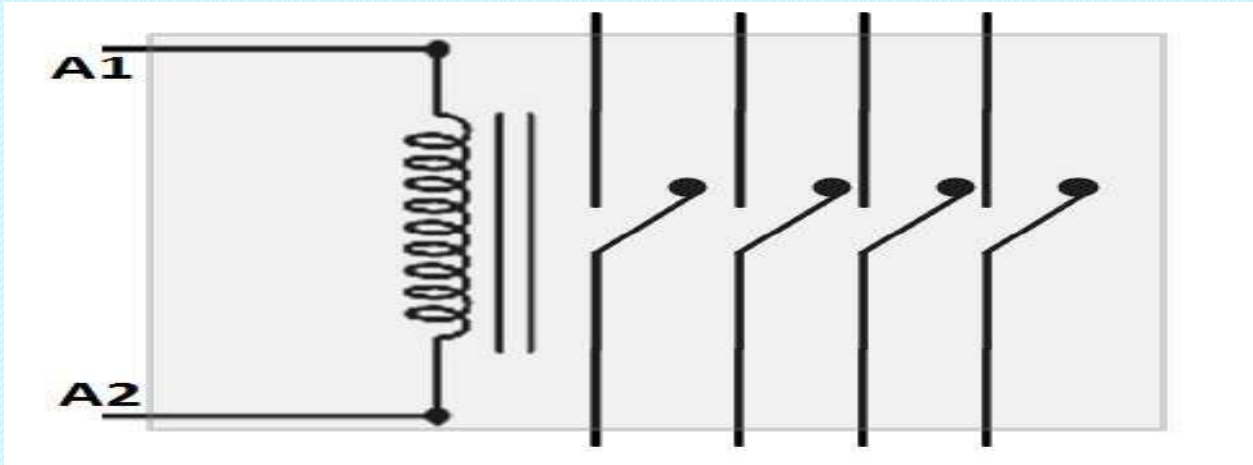
- এই Relay এর pin সংখ্যা থাকে ৬টি এই ৬টি pin এর মধ্যে ২টি pin থাকে coil এর জন্য, যেখানে supply দেওয়া হয়, এবং ৪টি pin switching এর জন্য ব্যবহৃত হয়, যাদের দুইটি pole এবং দুইটি throw থাকে।

# DPDT: (Double Pole Double Throw):



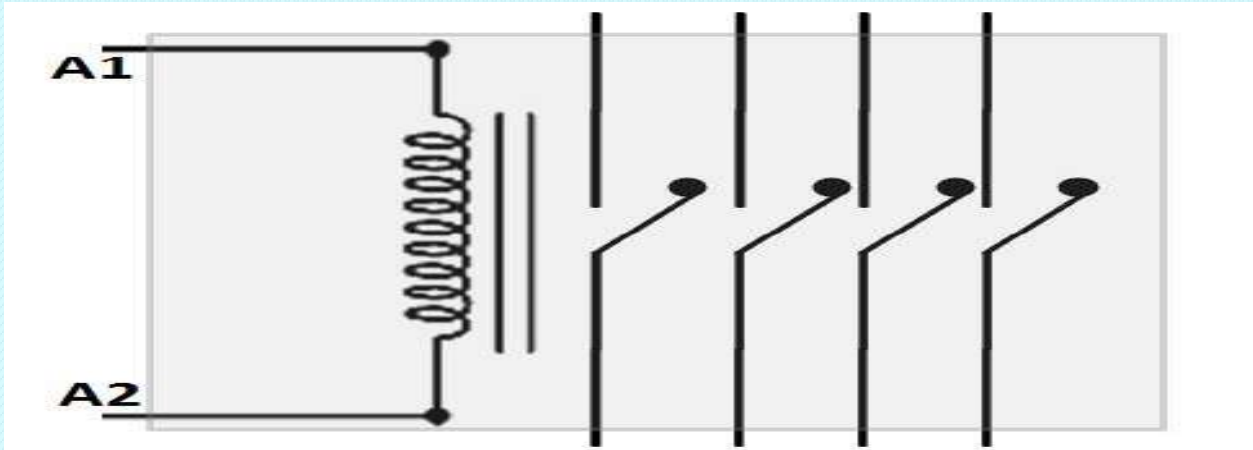
- এই Relay এর pin সংখ্যা থাকে ৮টি এই ৮টি pin এর মধ্যে ২টি pin থাকে coil এর জন্য, যেখানে supply দেওয়া হয়।
- এবং ৬টি pin switching এর জন্য ব্যবহৃত হয়, যাদের তিনটি pole এবং তিনটি throw থাকে।

# Magnetic Contac:



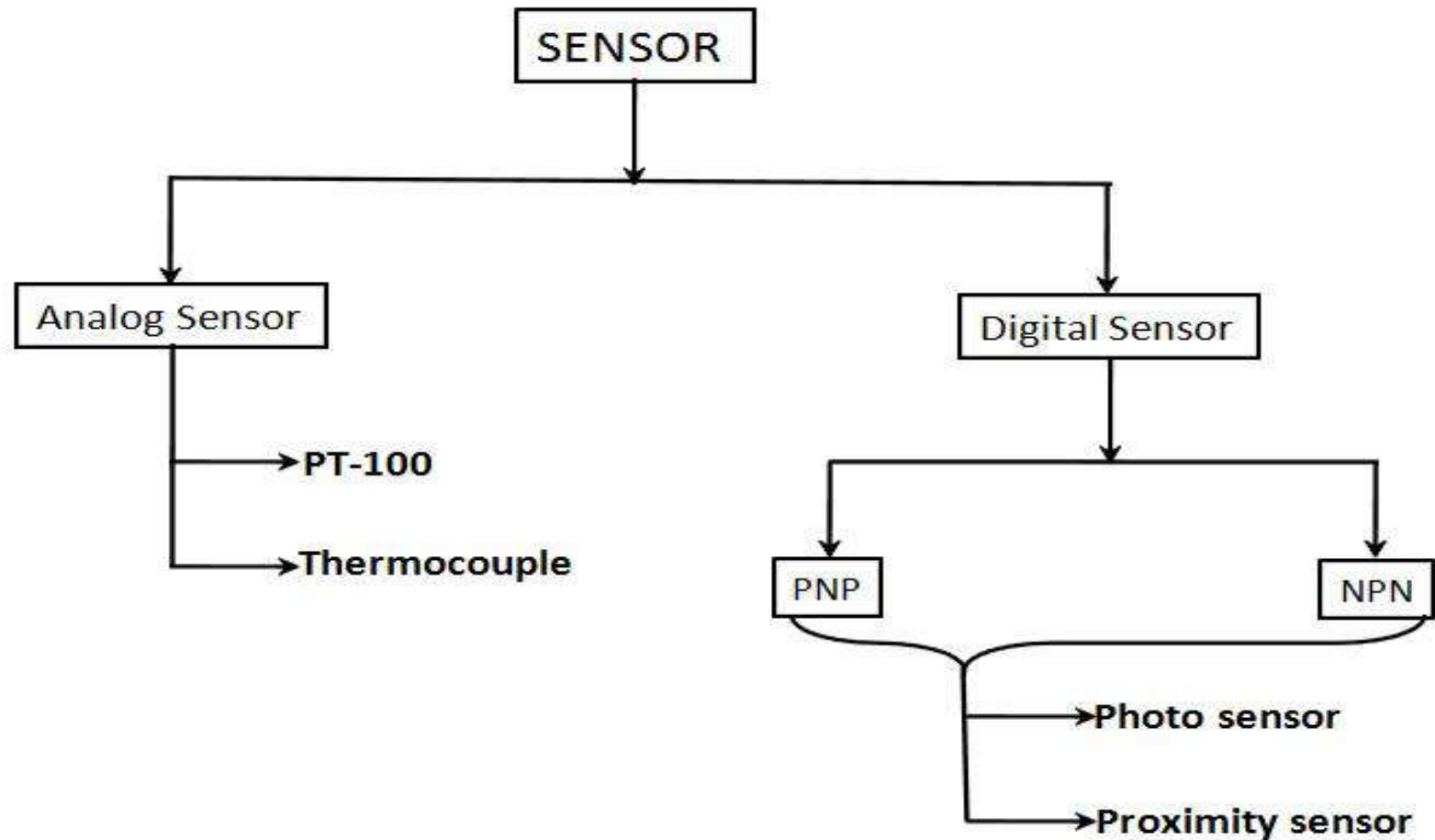
- Magnetic contact ও একটি automatic switching device যা electromagnetic ধর্মের ভিত্তিতে কাজ করে, এর coil এ সবসময় AC ভোল্টেজ supply দেওয়া হয়। একটি Magnetic contact একসাথে ৪টি port কে switching করে এর coil এর ২ টি প্রান্ত কে A1 এবং A2 বলা হয়, এর coil এর ২ প্রান্তে AC220v supply দেওয়া হলে এর কোরটি magnet এ রূপান্তরিত হয়, ফলে একসাথে ৪ টি port switching হয়।

# Magnetic Contact:



- Magnetic contact ও একটি automatic switching device যা electromagnetic ধর্মের ভিত্তিতে কাজ করে, এর coil এ সবসময় AC ভোল্টেজ supply দেওয়া হয়। একটি Magnetic contact একসাথে ৪টি port কে switching করে এর coil এর ২ টি প্রান্ত কে A1 এবং A2 বলা হয়, এর coil এর ২ প্রান্তে AC220v supply দেওয়া হলে এর কোরটি magnet এ রূপান্তরিত হয়, ফলে একসাথে ৪ টি port switching হয়।

# Different Type of sensor with application



# Sensor 2 ধরনের হয়ে থাকে

1. Analog Sensor

2. Digital Sensor

## Digital Sensor আবার ২ ধরনেরঃ

1. Photo sensor

2. Proximity sensor

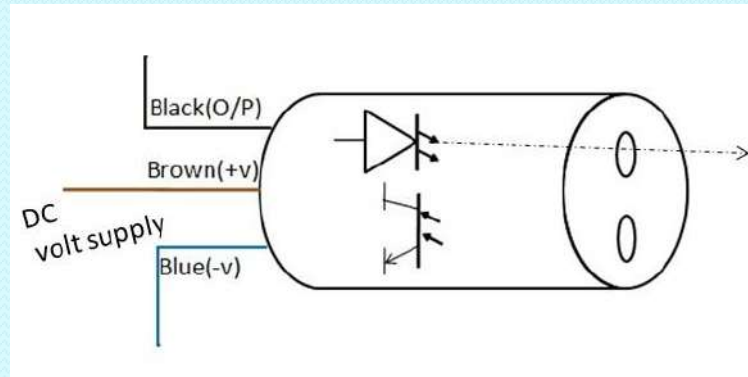
### Photo sensor ২ ধরনের হয়ে থাকে।

- Transriver Photo Sensor.
- Transmitter Receiver Pair Photo Sensor.



# Transriver Photo Sensor

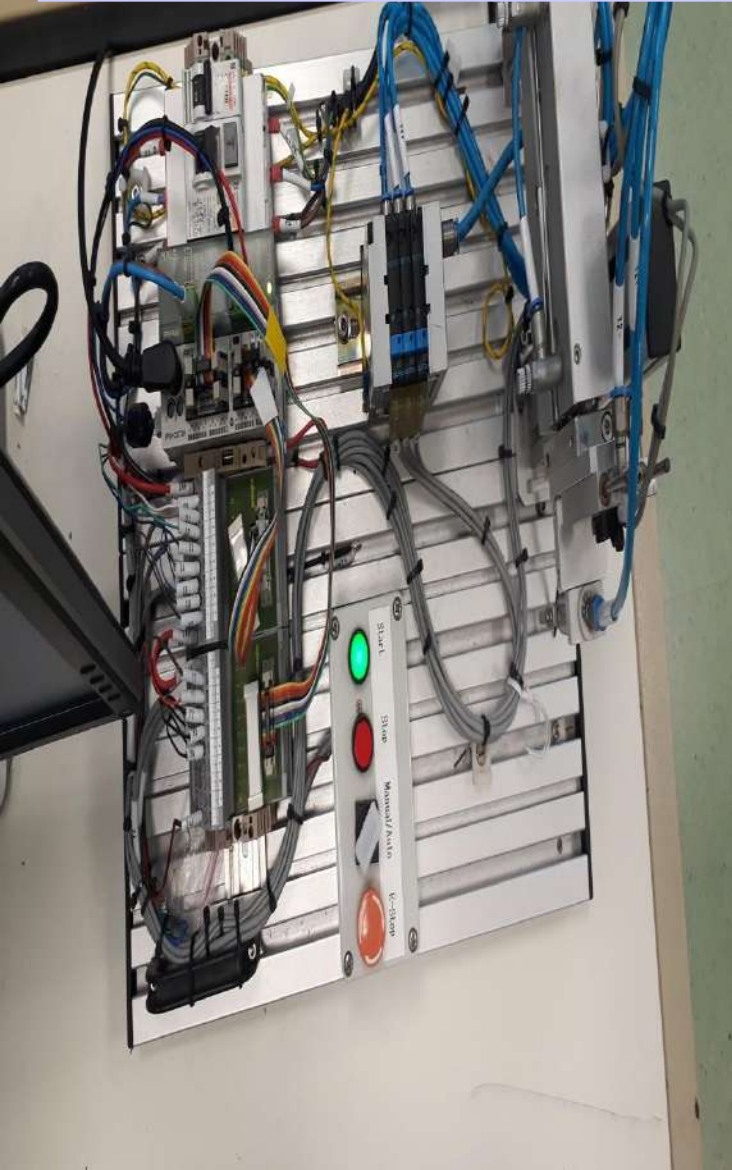
যে Photo sensor এ transmitting এবং Receiving ব্যবস্থা একত্রে থাকে তাকে Transriver Photo Sensor বলাে এক্ষেত্রে Transmitter হিসেবে Photo Diode এবং Receiver হিসেবে Photo Transistor ব্যবহৃত হয়।



ধন্যবাদ



# Practical on the subject of Mechatronics & PLC



Presented by –  
Engr. Muhammad Shadat Ullah  
Workshop Super (Mechanical)

# Topic

- Physical principles of Pneumatic and Electrical system
- Functions and use of Electro-Pneumatic components
- Recognizing and drawing of pneumatic and Electro-Pneumatic symbols and circuit diagrams
- Representation of motion sequences and operating status
- Drawing of pneumatic and electrical circuits diagrams
- Direct and indirect manual controls
- Direct and indirect stroke-dependent controls
- Logical AND/OR function of switch-on signals

# What is

# Pneumatics?

- PNEUMA - Greek root term means “breath”

- It is the industrial implementation and application of air powered actuators (***cylinders and motors***) and their control devices (***valves***) needed in their operation.

- Branch of science which deals with the study of gases especially air, its properties and application at pressure higher (***compressed***) or lower (***vacuum***) than atmospheric.

# Compressed Air as a

## Working Medium

- Air is available everywhere
- Compressed air is easily conveyed in pipelines over large distances
- Compressed air is insensitive to temperature fluctuations
- Compressed air need not be returned
- Compressed air is explosion proof
- Compressed air is clean
- Compressed air is fast
- Straight line movement can be produced directly

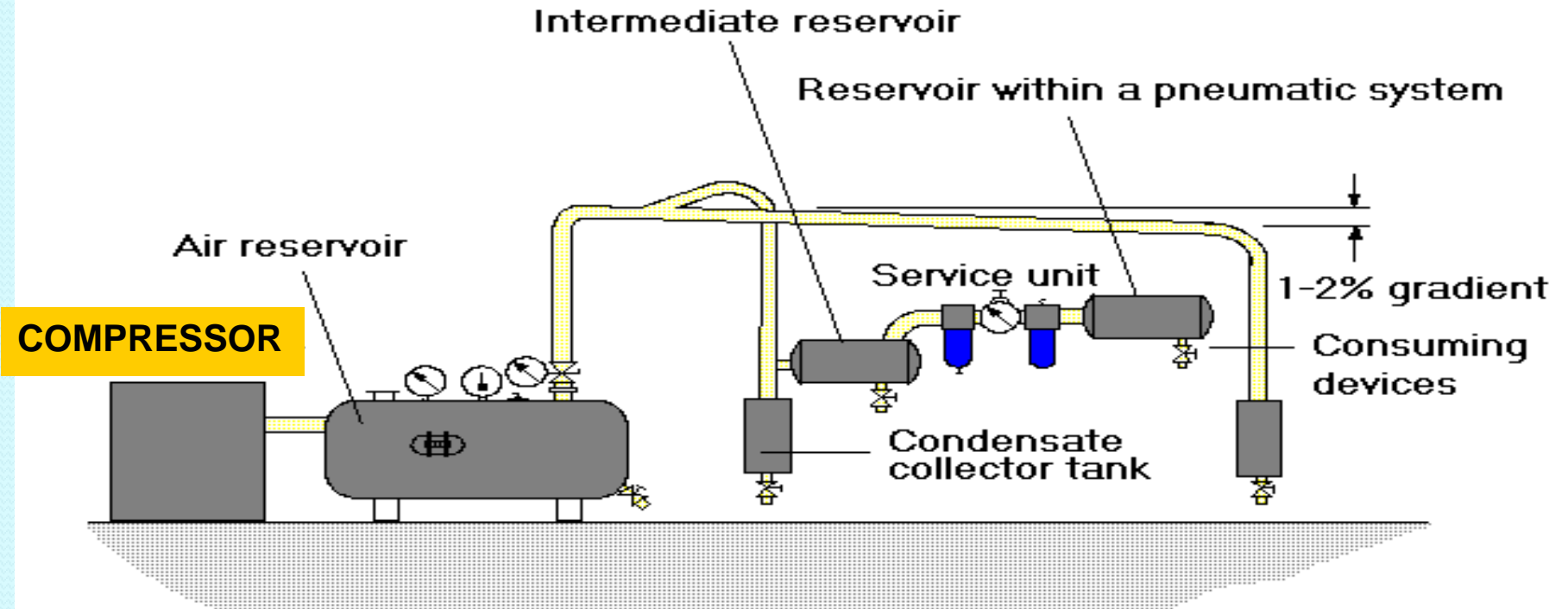


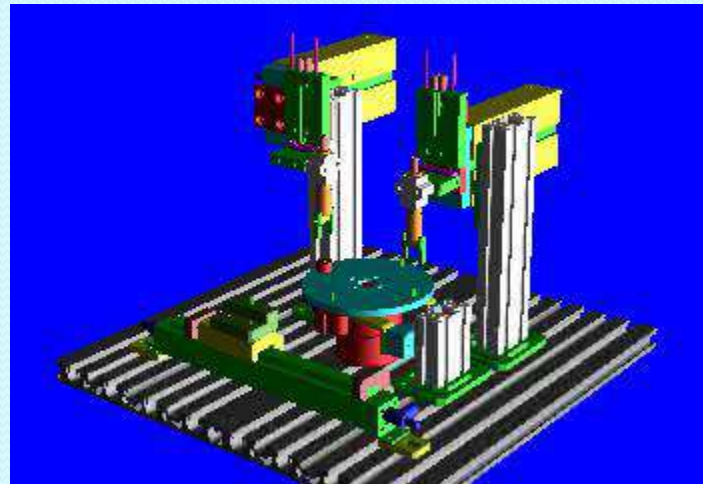
# Compressed Air as a

## Working Medium

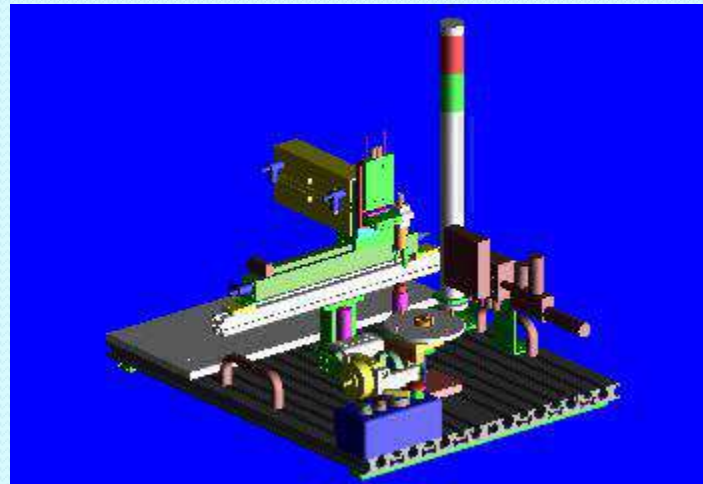
- Compressed air is a relatively expensive means of conveying energy
- Compressed air requires good conditioning
- It is only economical up to a certain force expenditure
- Air is compressible
- Exhaust air is loud (reduced by using silencers)
- The oil mist mixed with air for lubricating purposes exhaust or escapes to the atmosphere







August 28, 2019



Single acting cylinder



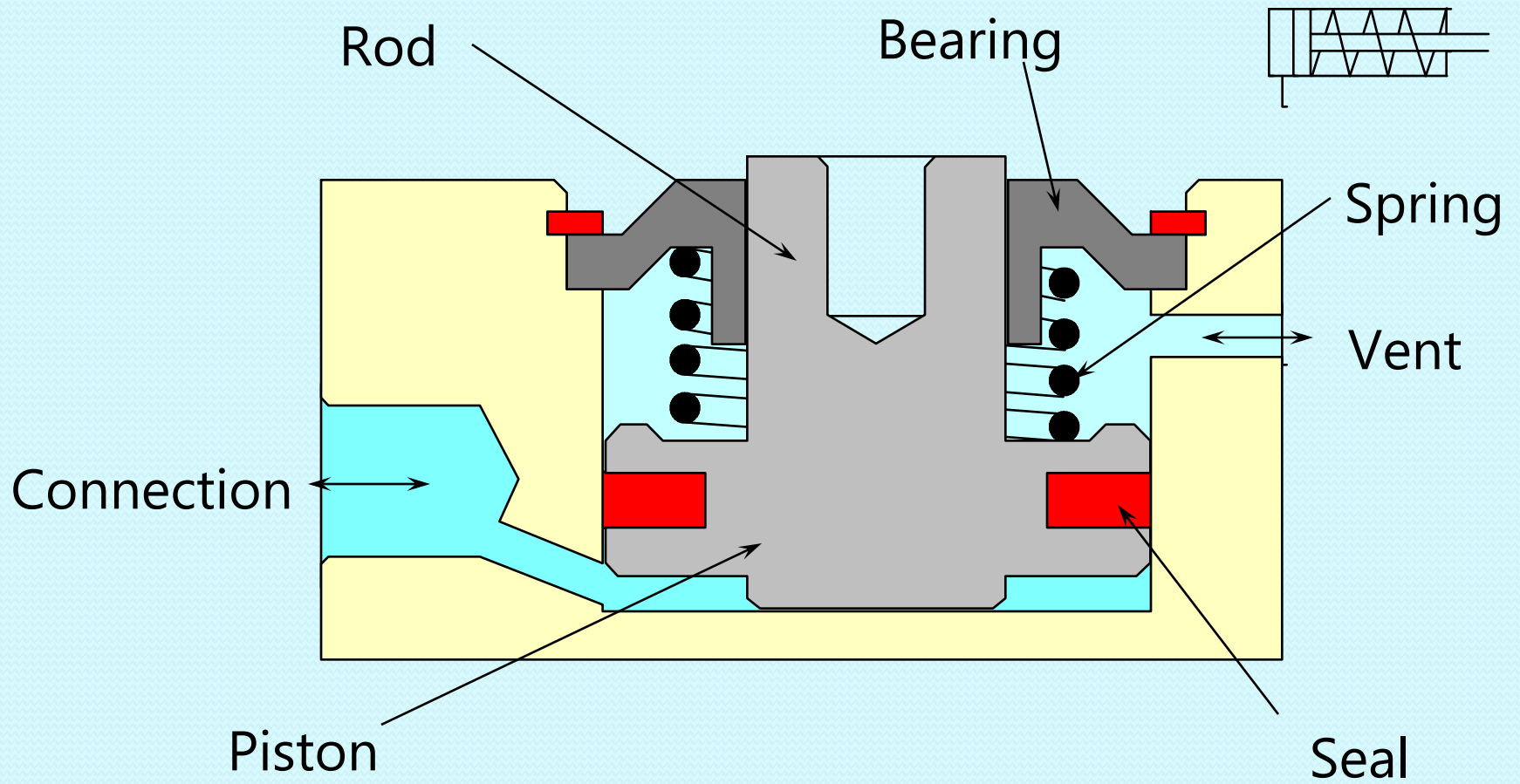
# Sample of Single Acting Cylinders



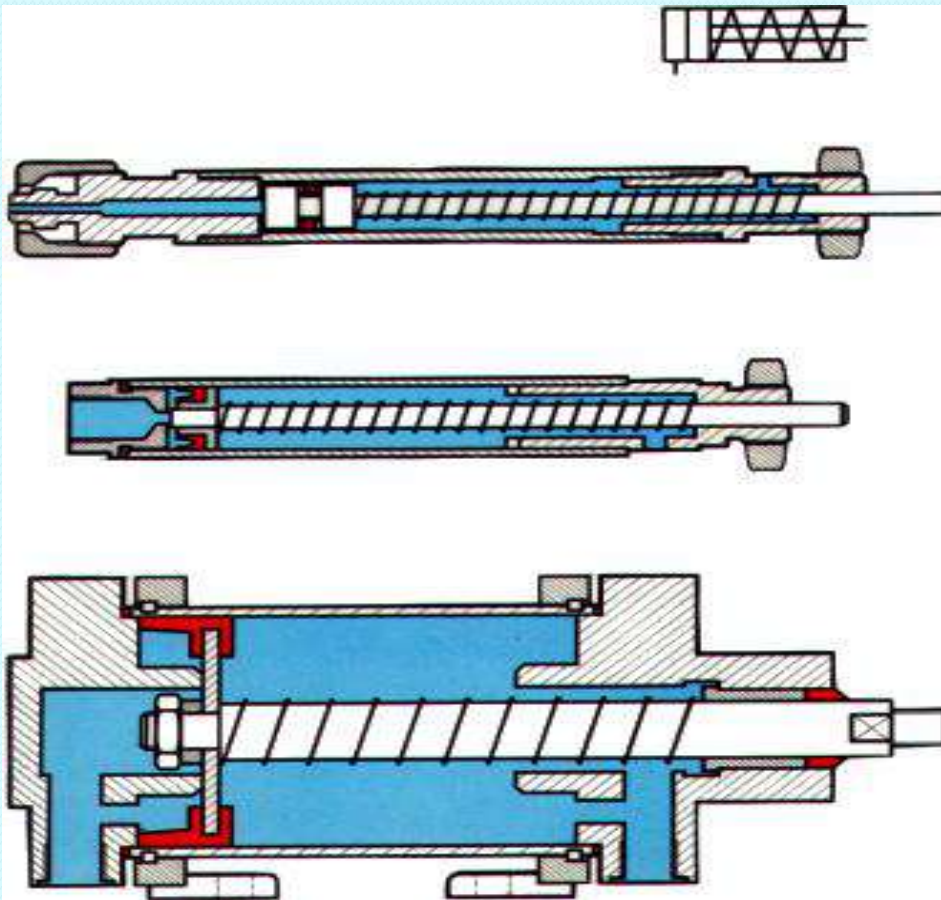
## Single Acting Cylinder

Diameters 10mm to 32mm

Stroke Lengths 5mm to 50mm



## Single Acting Cylinders

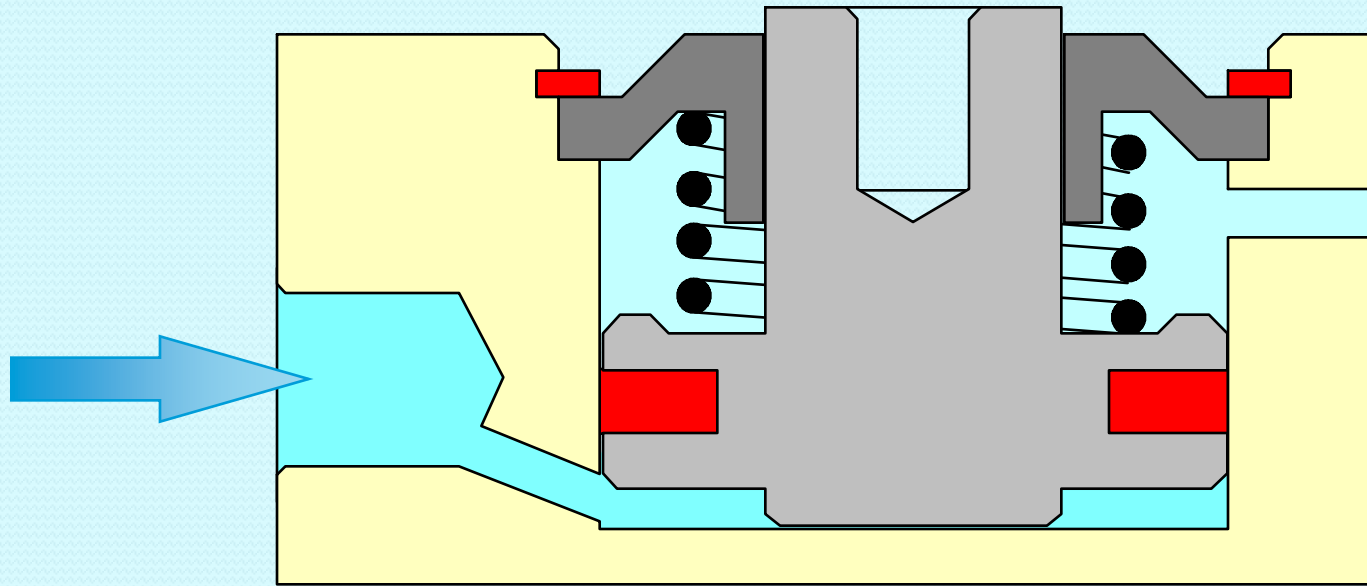
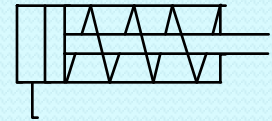


If compressed air is supplied, air hits the piston surface and the piston rod moves out. When air is released, the return spring moves the piston to its initial position.

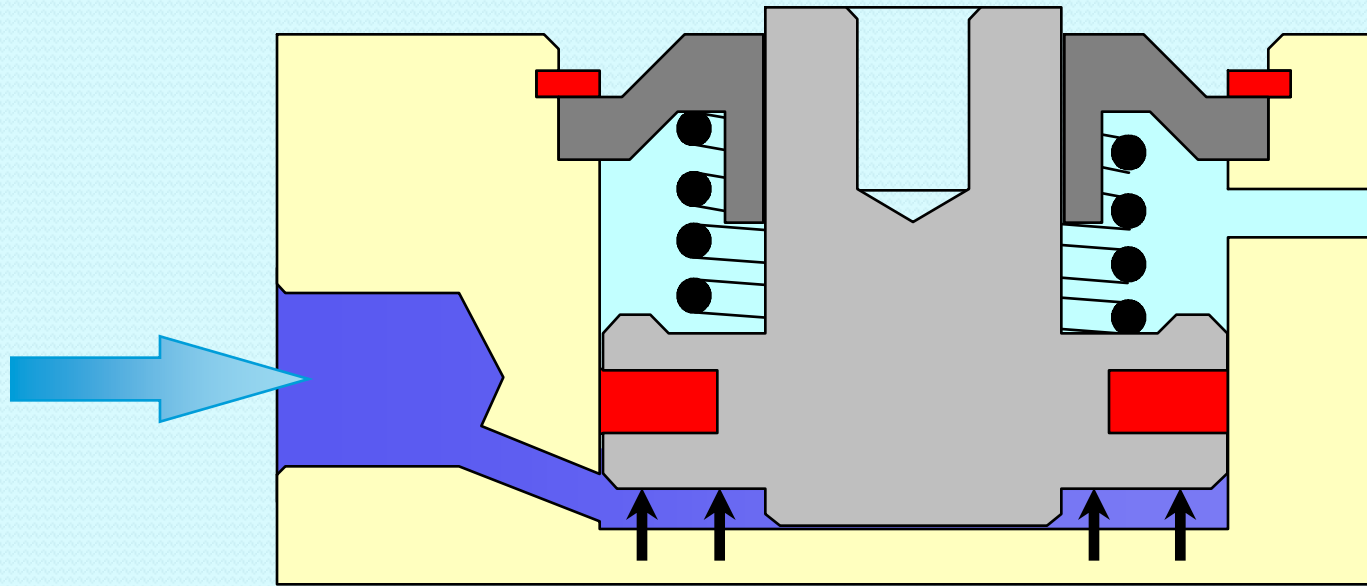
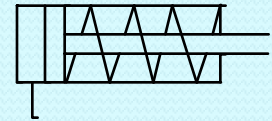
Single acting cylinders do work in one way, therefore they are ideal for tensioning, ejecting, compressing etc.



# Operation of Single Acting Cylinders

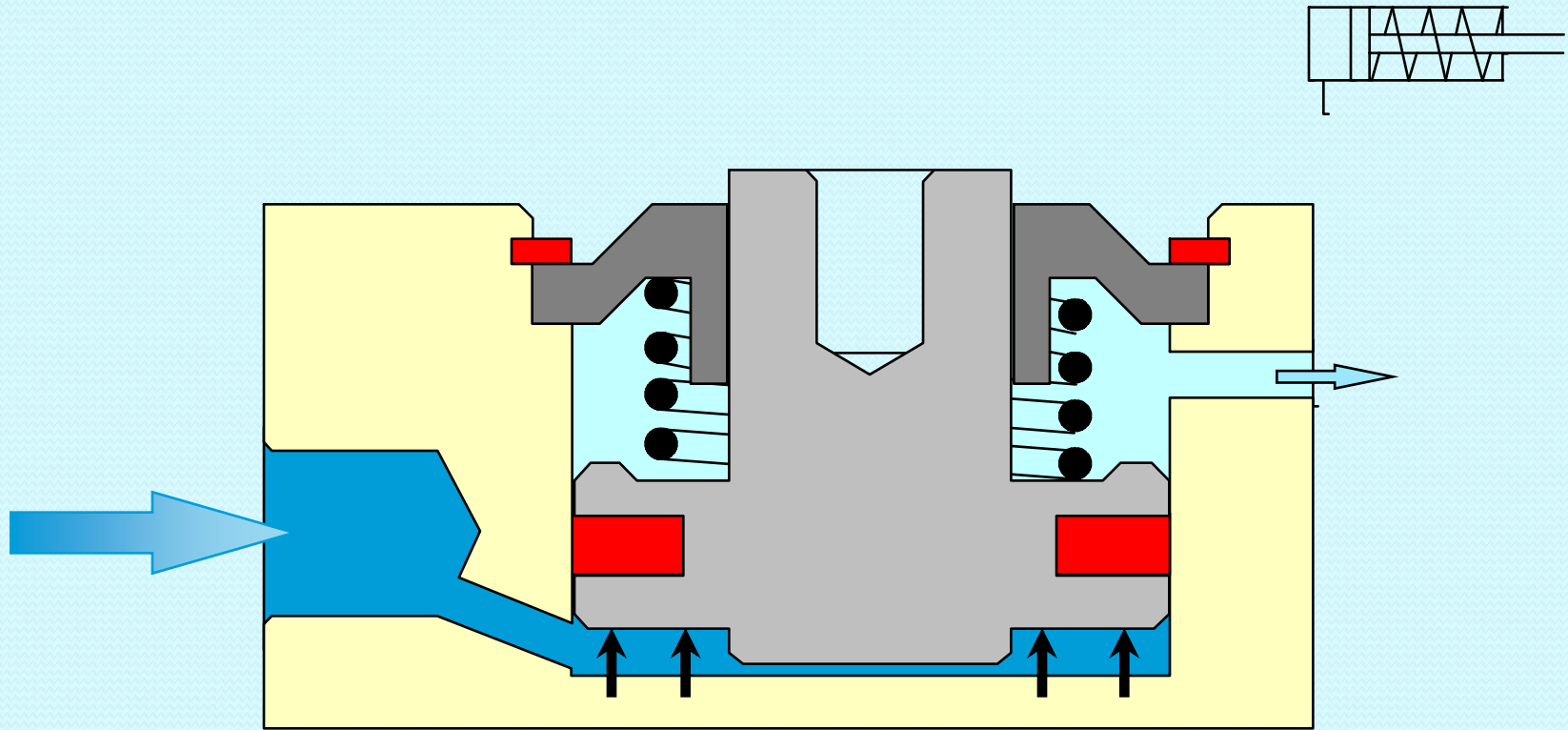


# Operation of Single Acting Cylinders



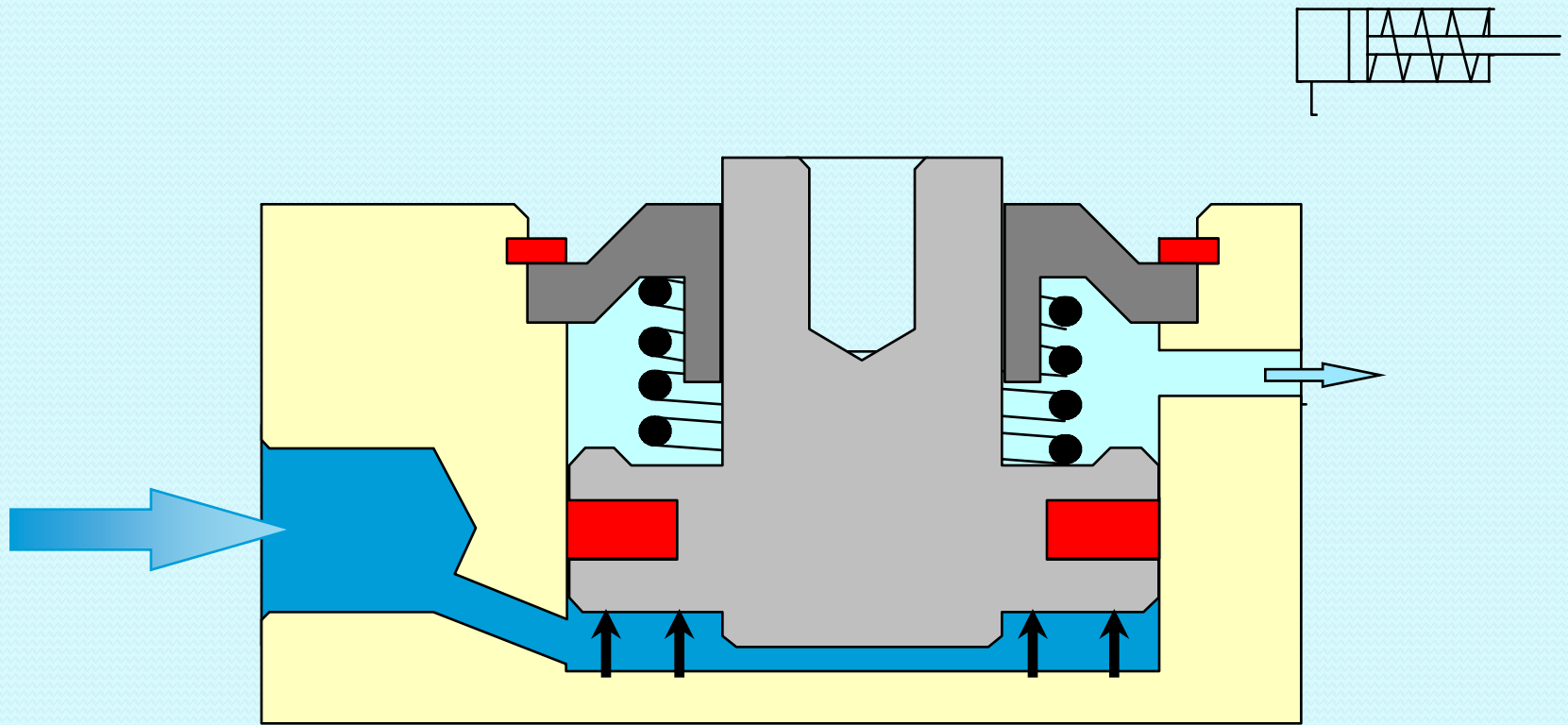
Force = Pressure x Area  
(piston)

# Operation of Single Acting Cylinders



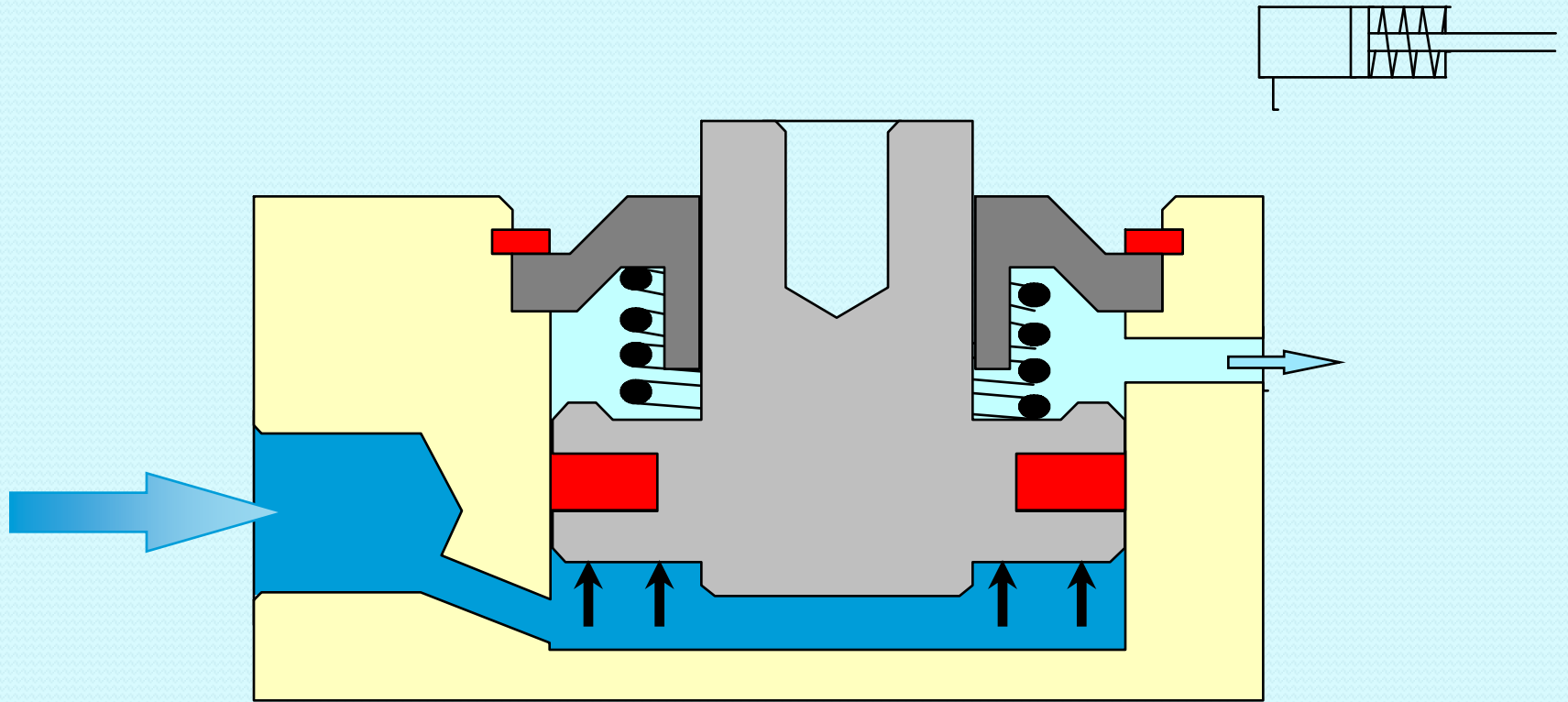
Force = Pressure x Area  
(piston)

# Operation of Single Acting Cylinders



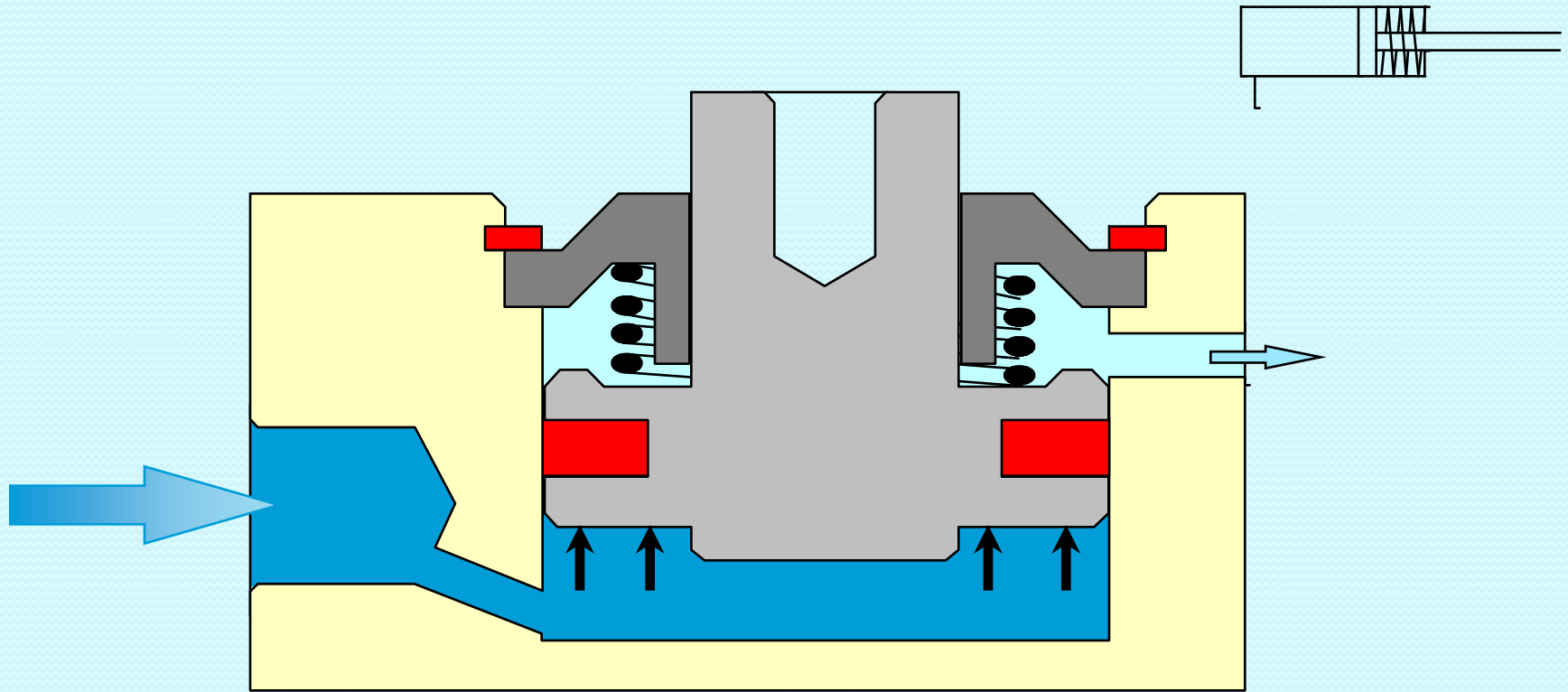
Force = Pressure x Area  
(piston)

# Operation of Single Acting Cylinders



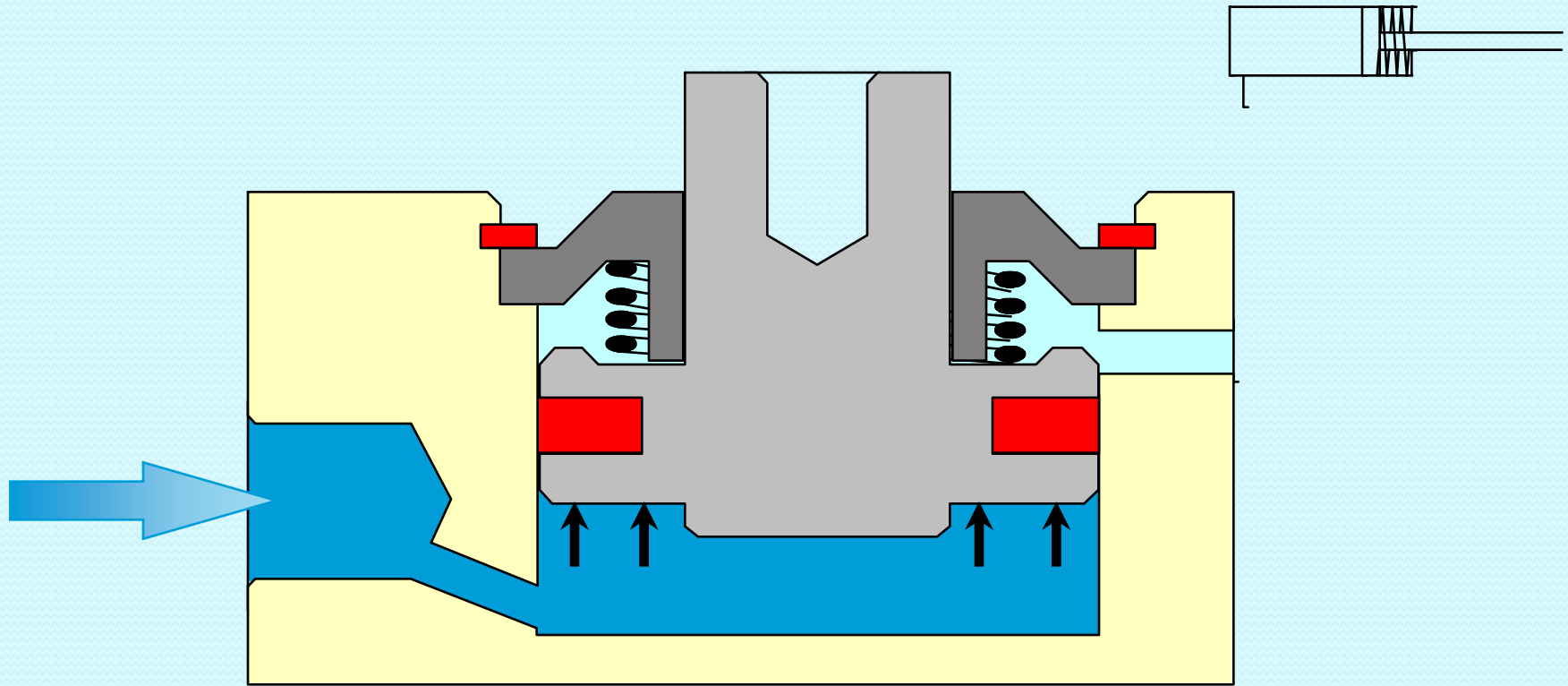
Force = Pressure x Area  
(piston)

# Operation of Single Acting Cylinders



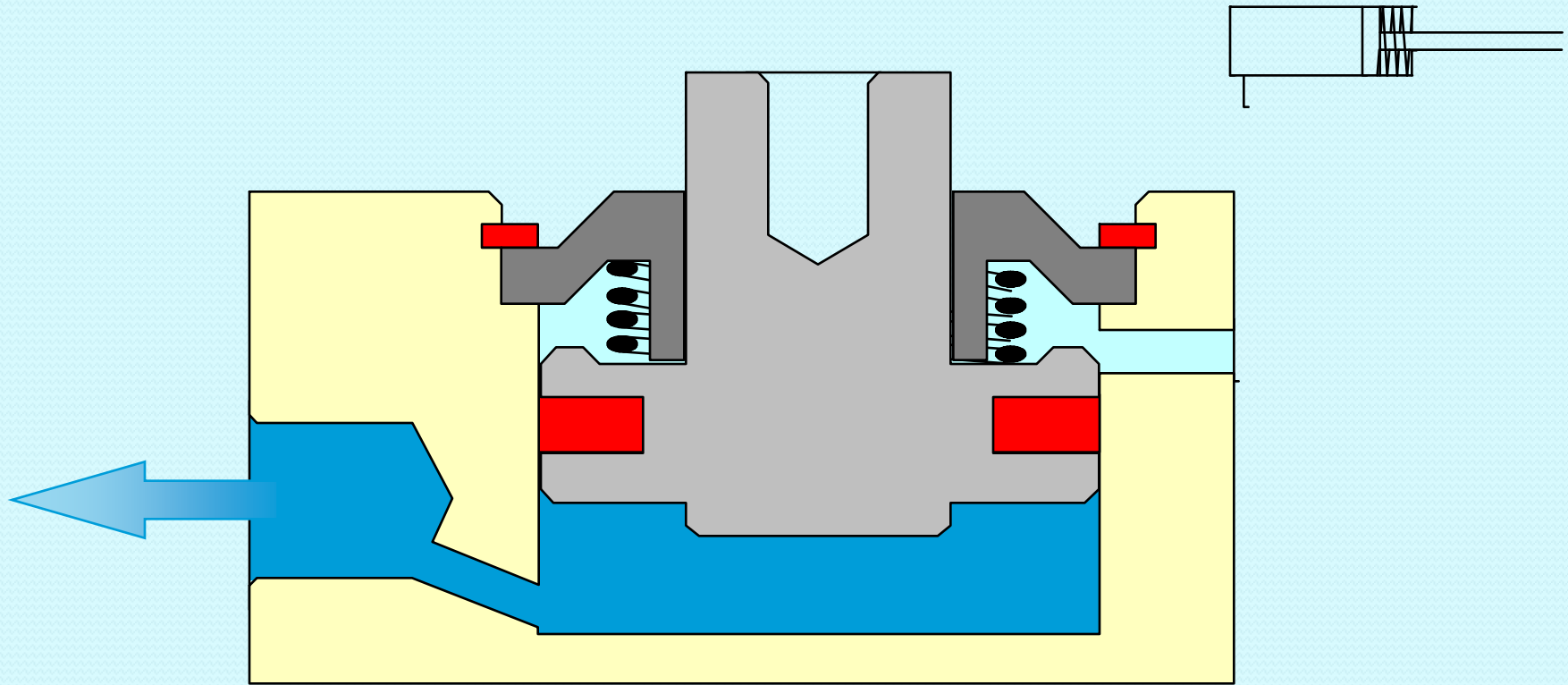
Force = Pressure x Area  
(piston)

# Operation of Single Acting Cylinders



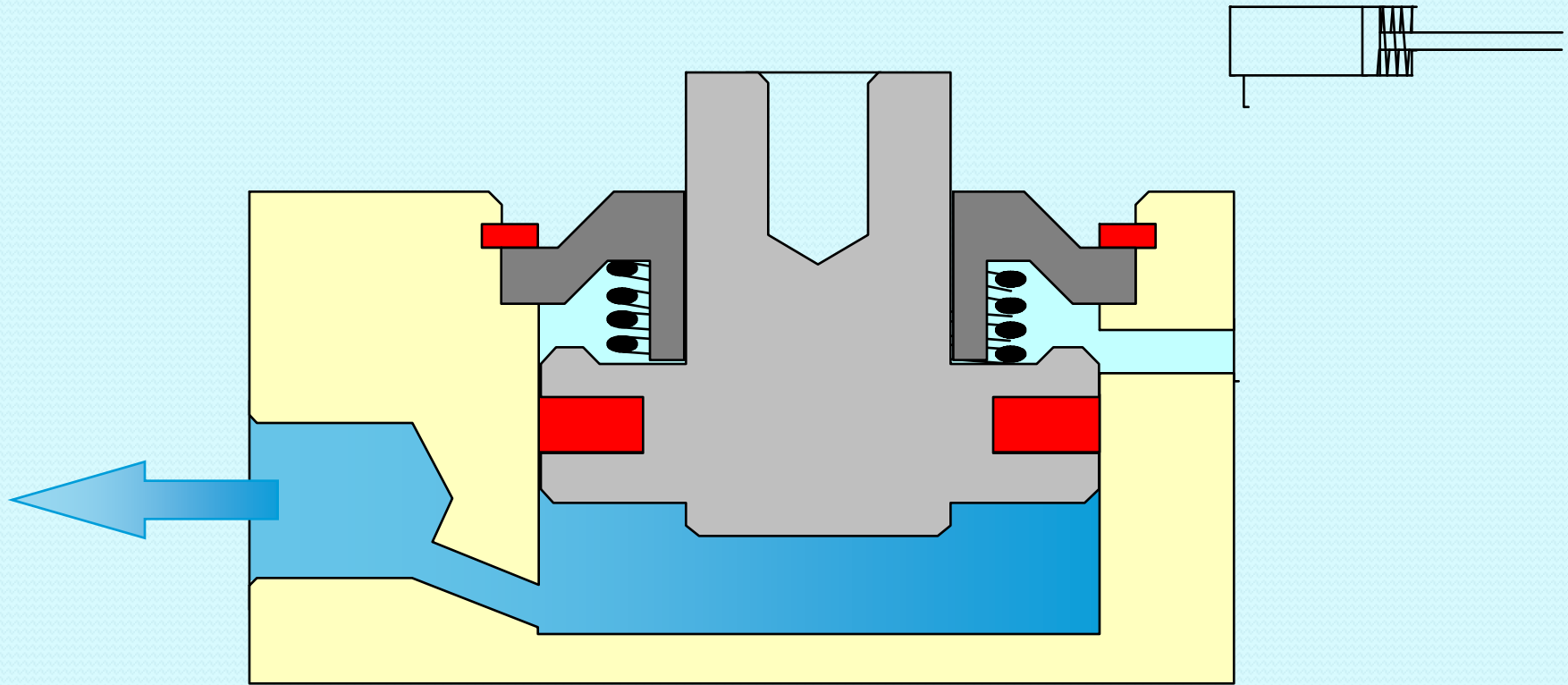
Force = Pressure x Area  
(piston)

# Operation of Single Acting Cylinders

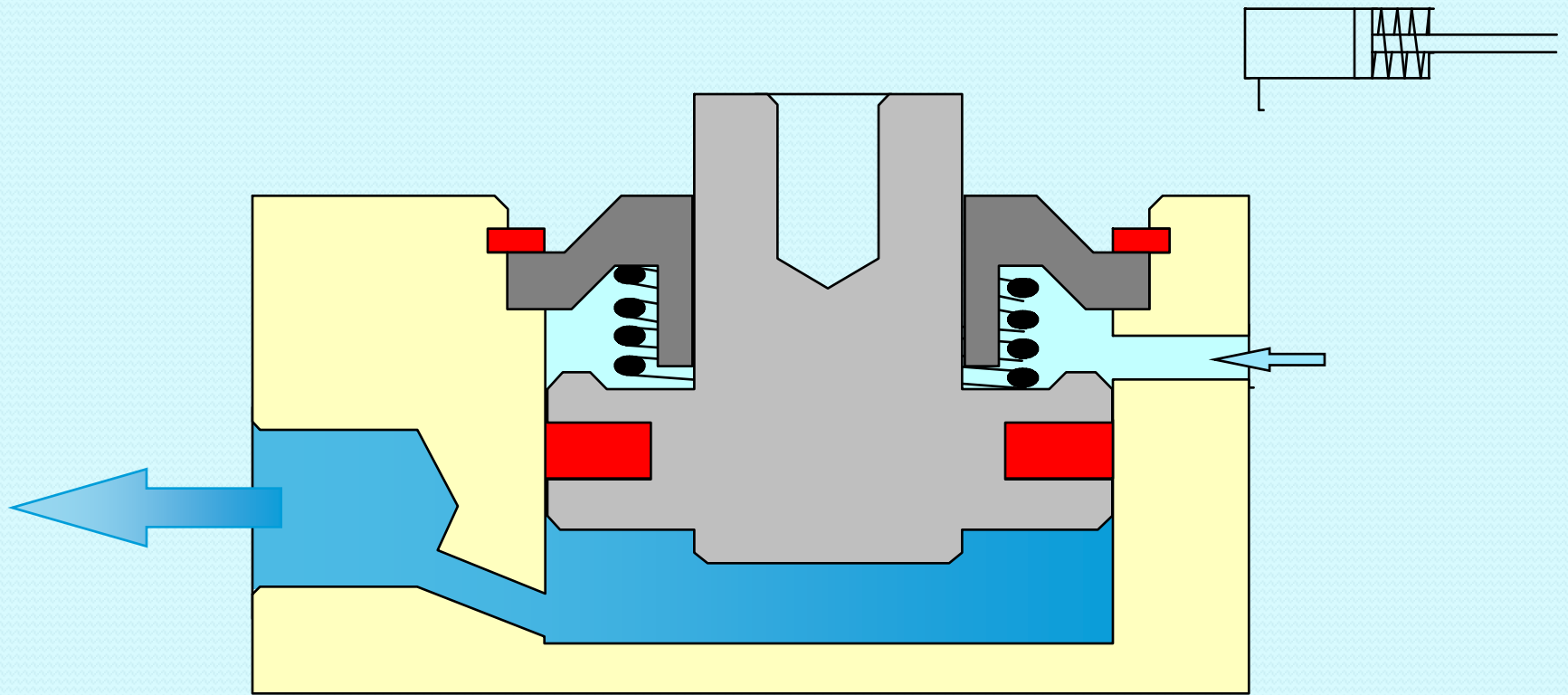




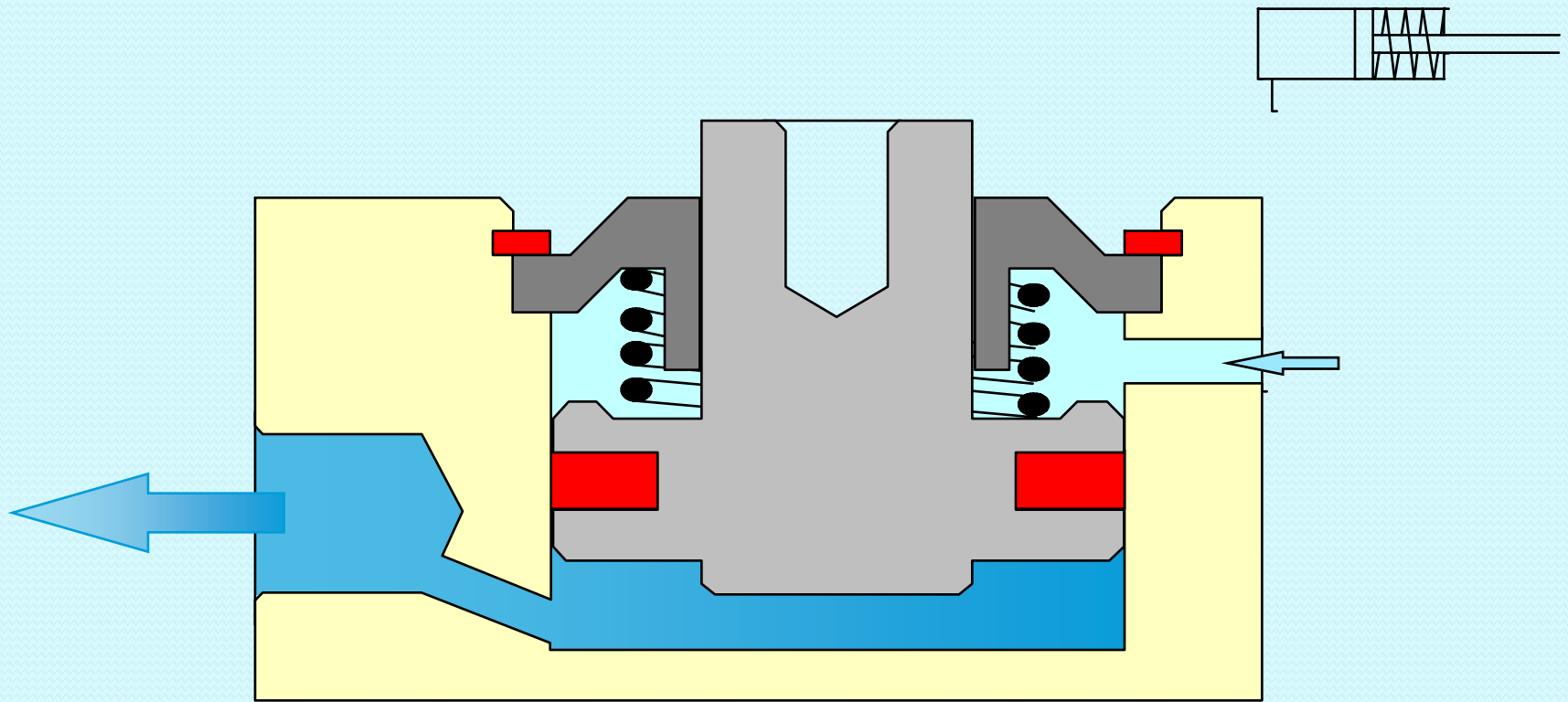
# Operation of Single Acting Cylinders



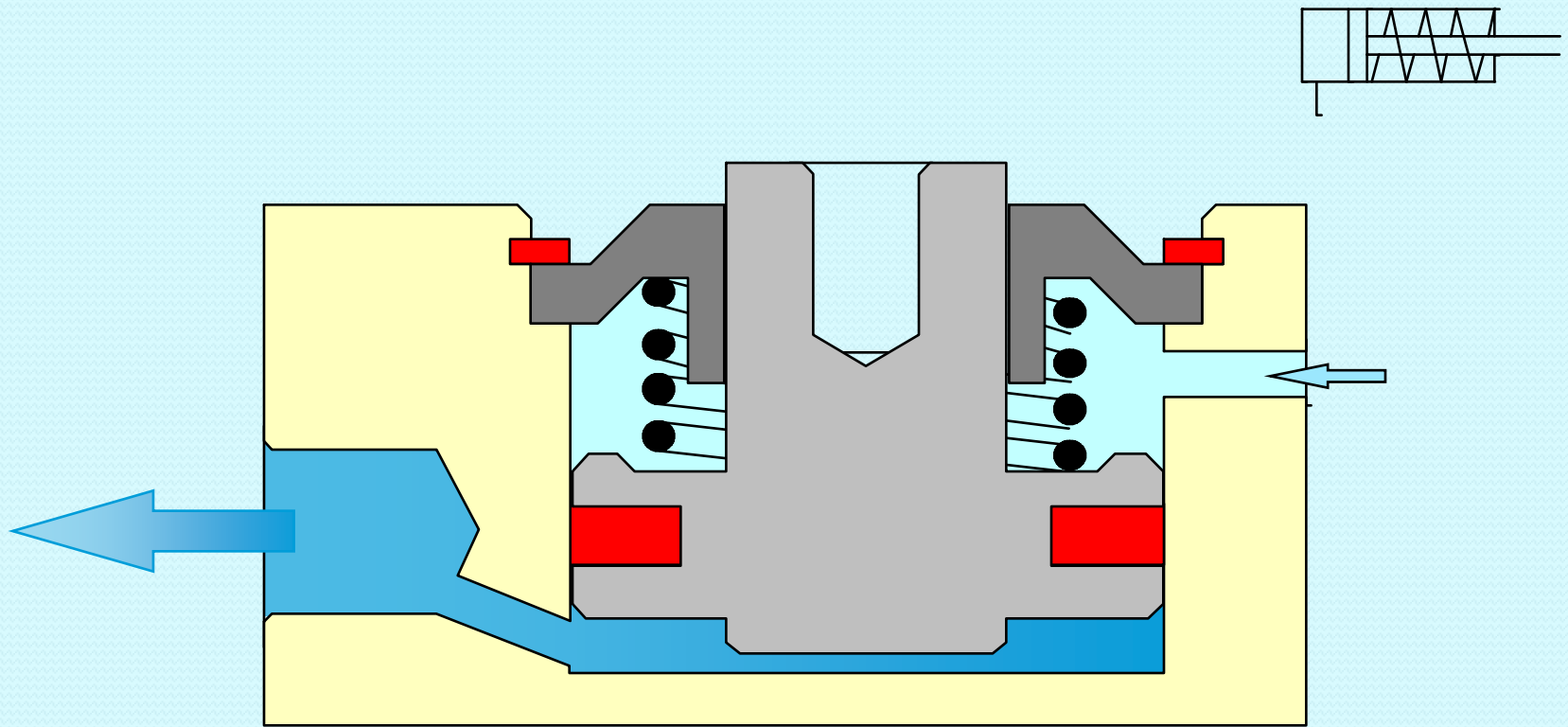
# Operation of Single Acting Cylinders



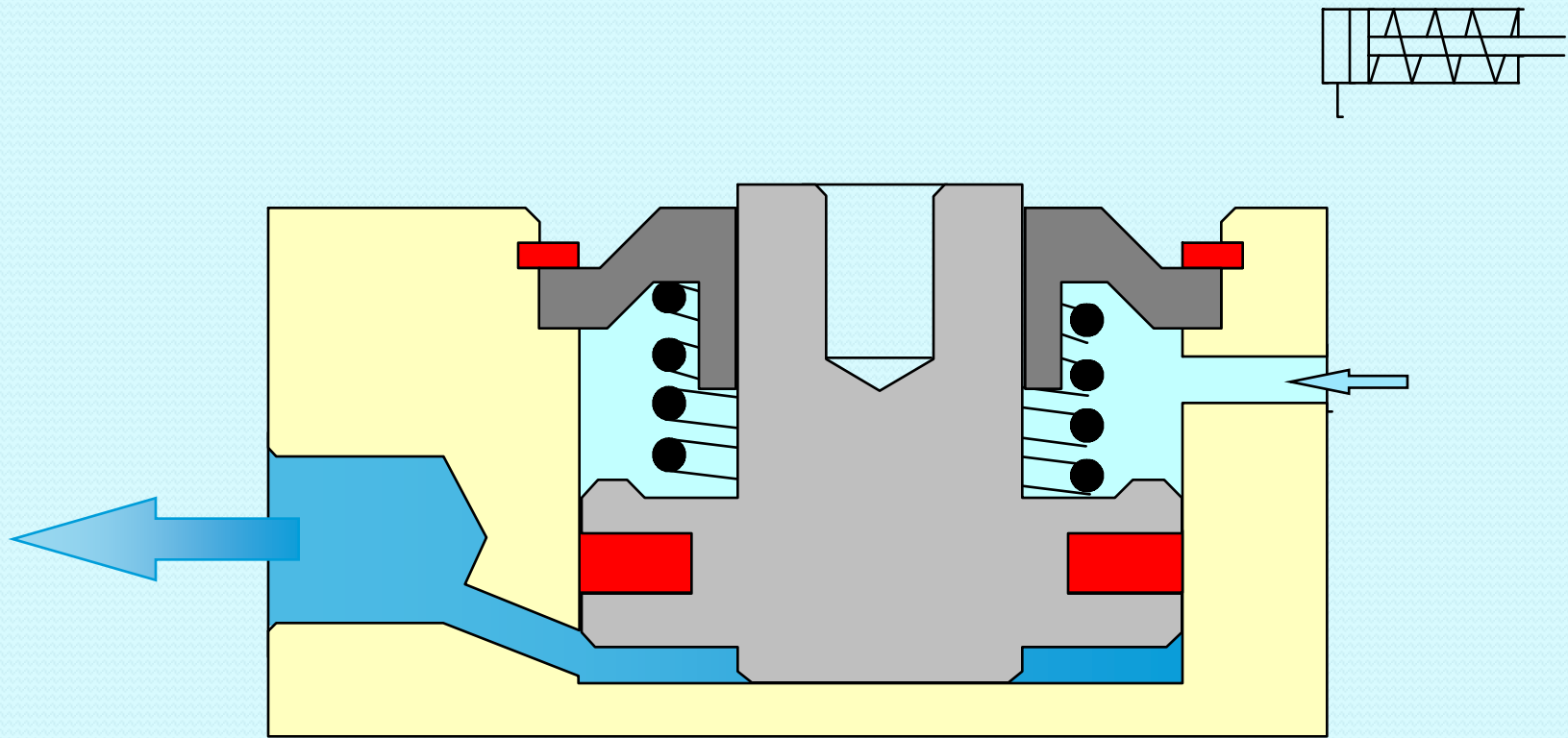
# Operation of Single Acting Cylinders



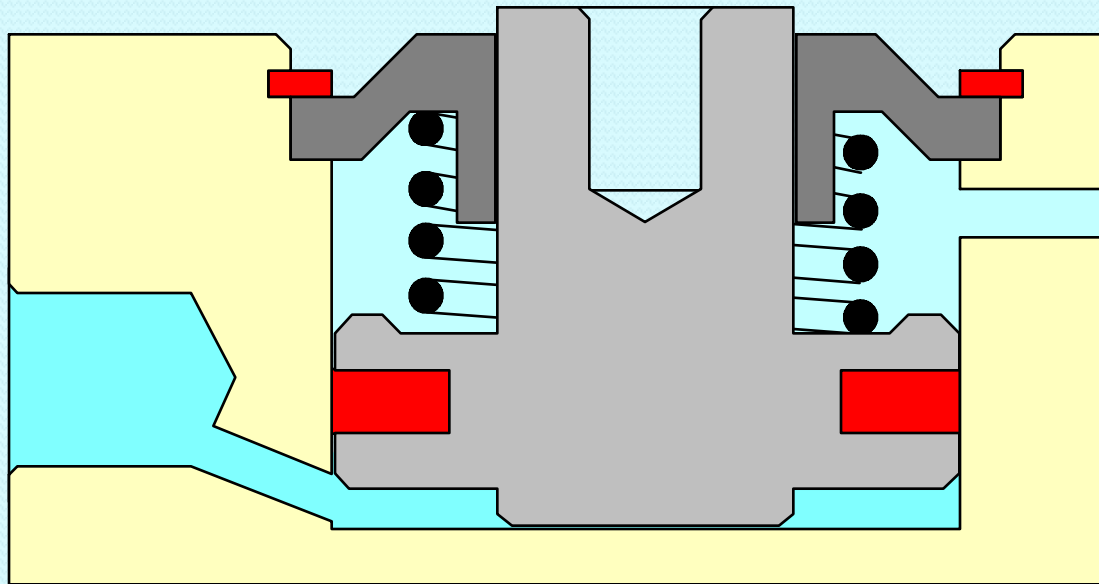
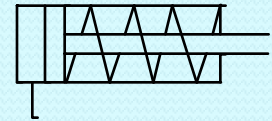
# Operation of Single Acting Cylinders



# Operation of Single Acting Cylinders



# Operation of Single Acting Cylinders





Double acting cylinder

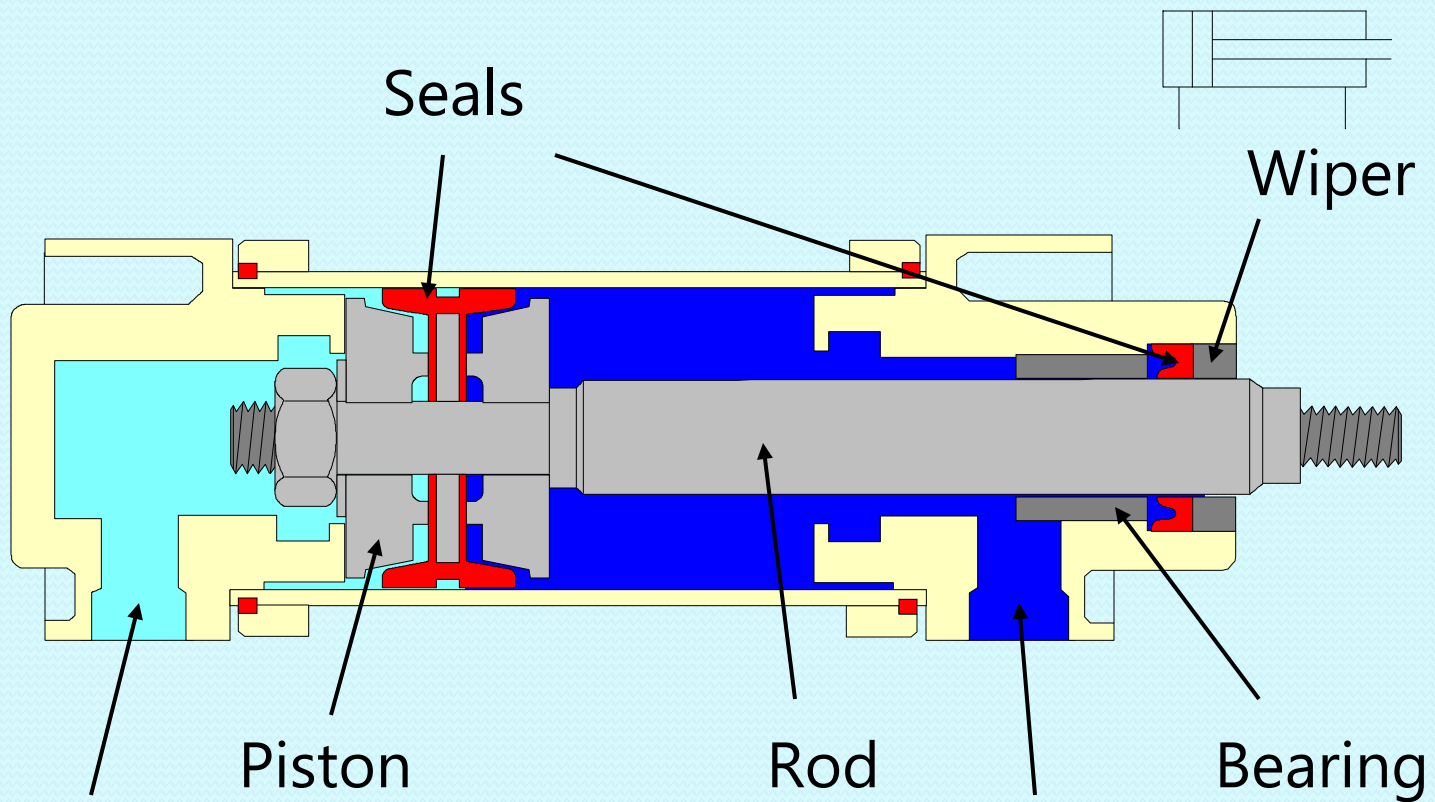


# DOUBLE-ACTING CYLINDERS



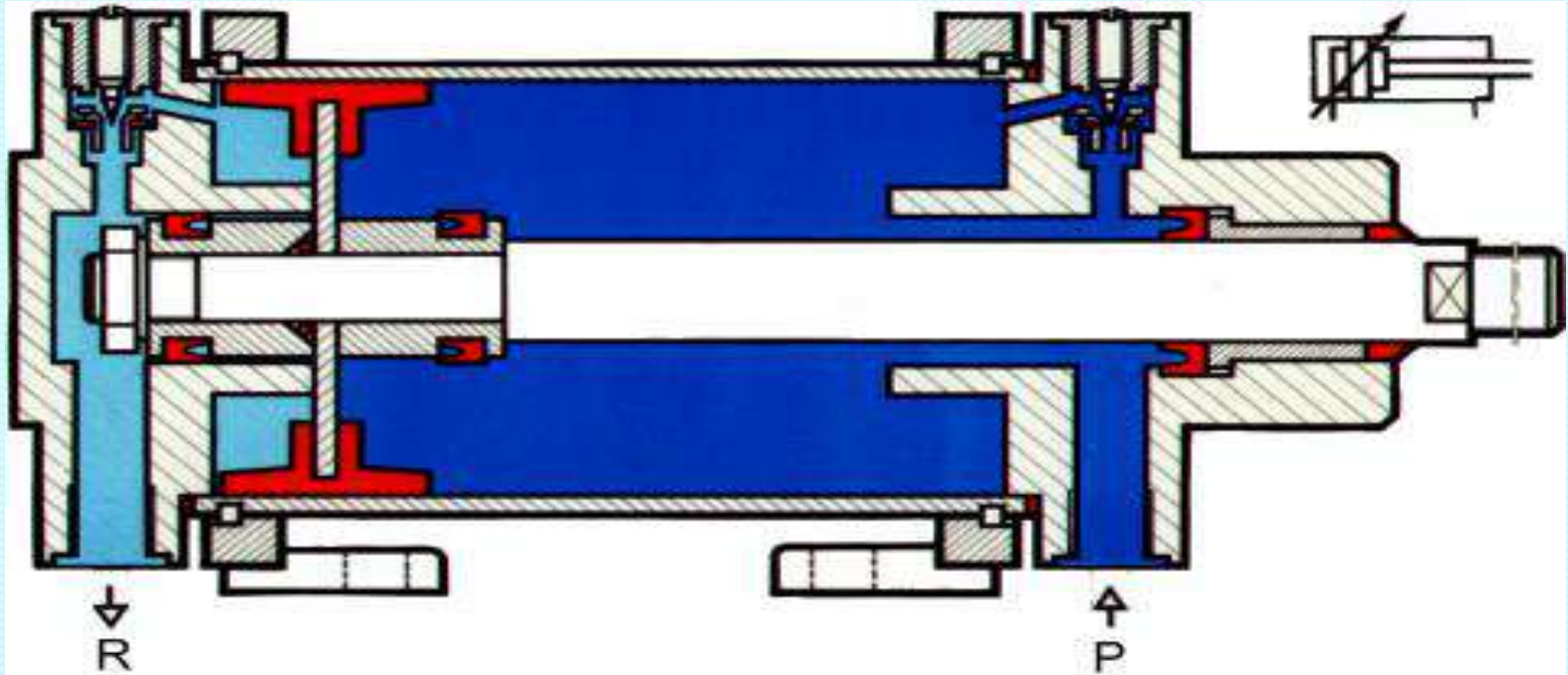
Stroke Length 100mm (max)





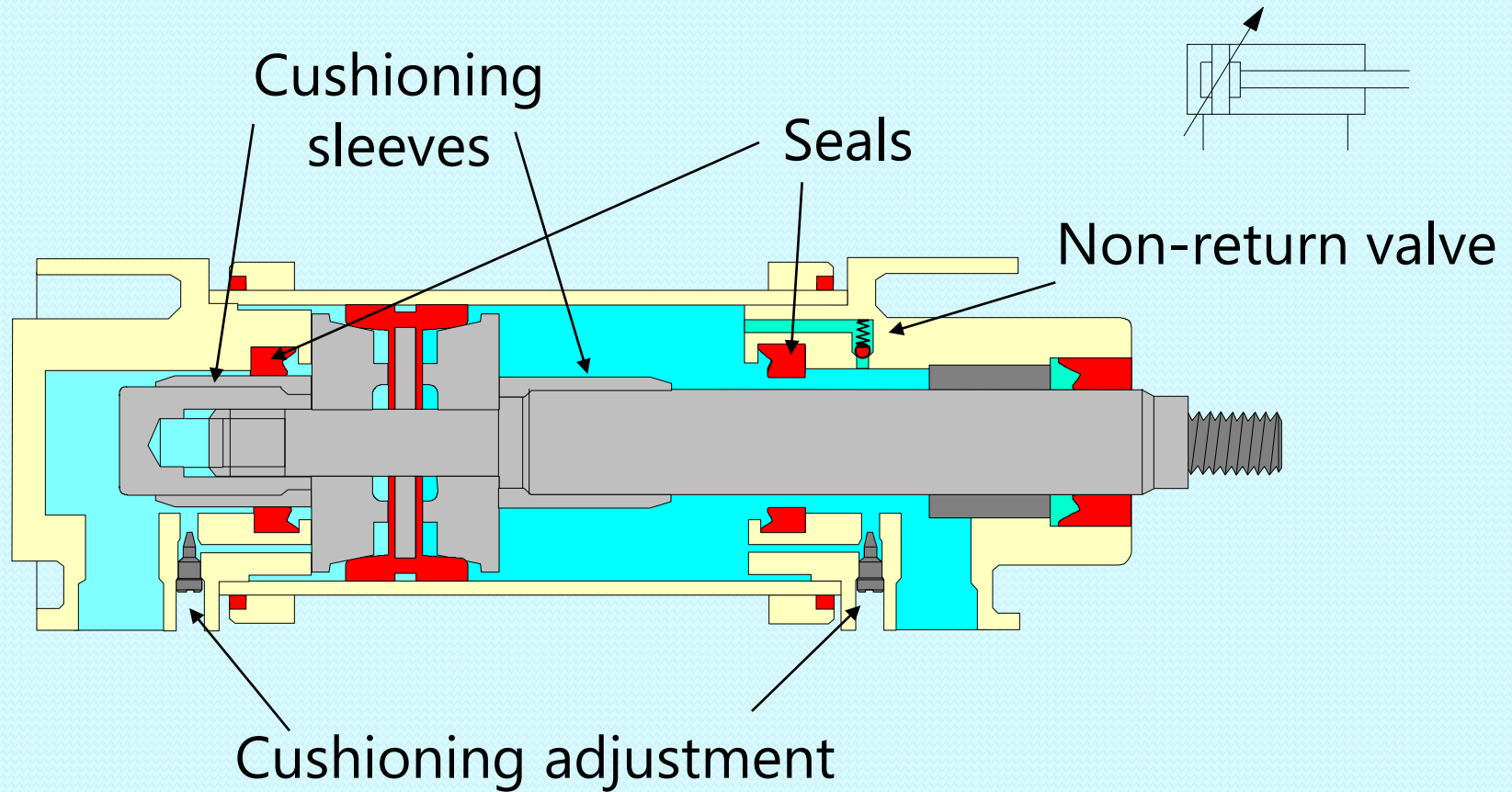
Base end ———— Connections ———— Rod end

## Double Acting Cylinders with Air Cushioning

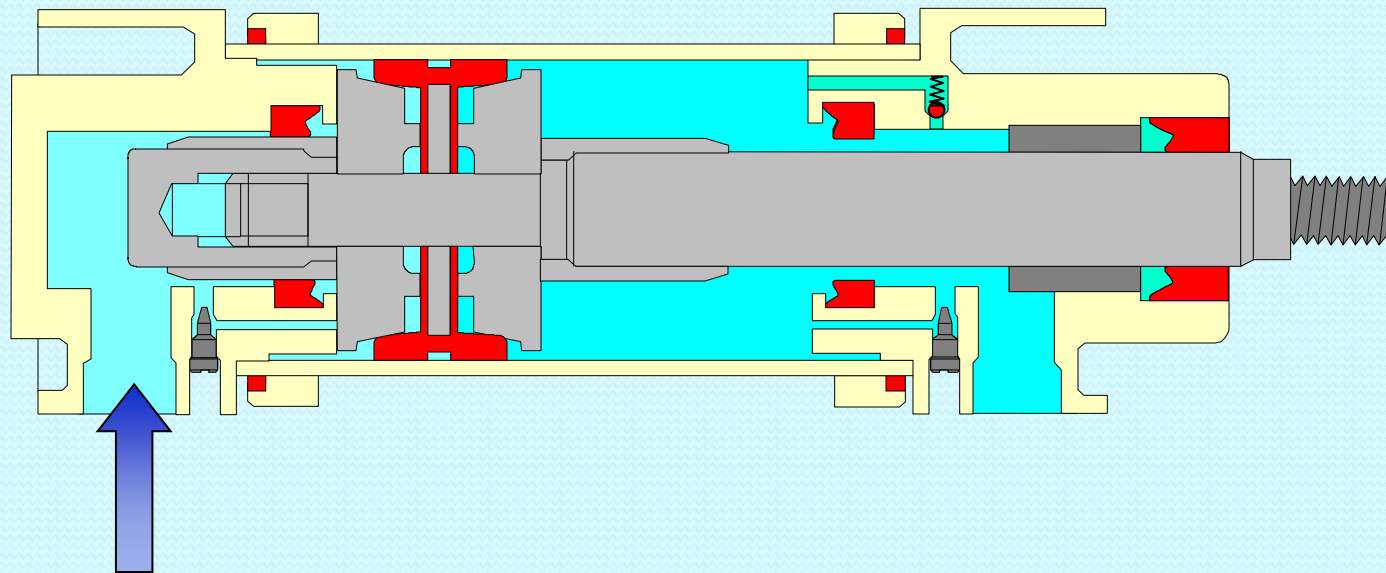
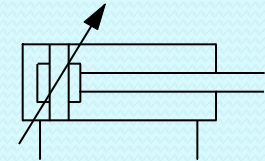


When the piston approaches its final position, the damping piston shuts off the direct air-outlet. Excess pressure sets up an air-cushion in the remaining cylinder volume and kinetic energy is converted into pressure. At this stage, air may only leave the cylinder through a controlled cross section of stream discharge.

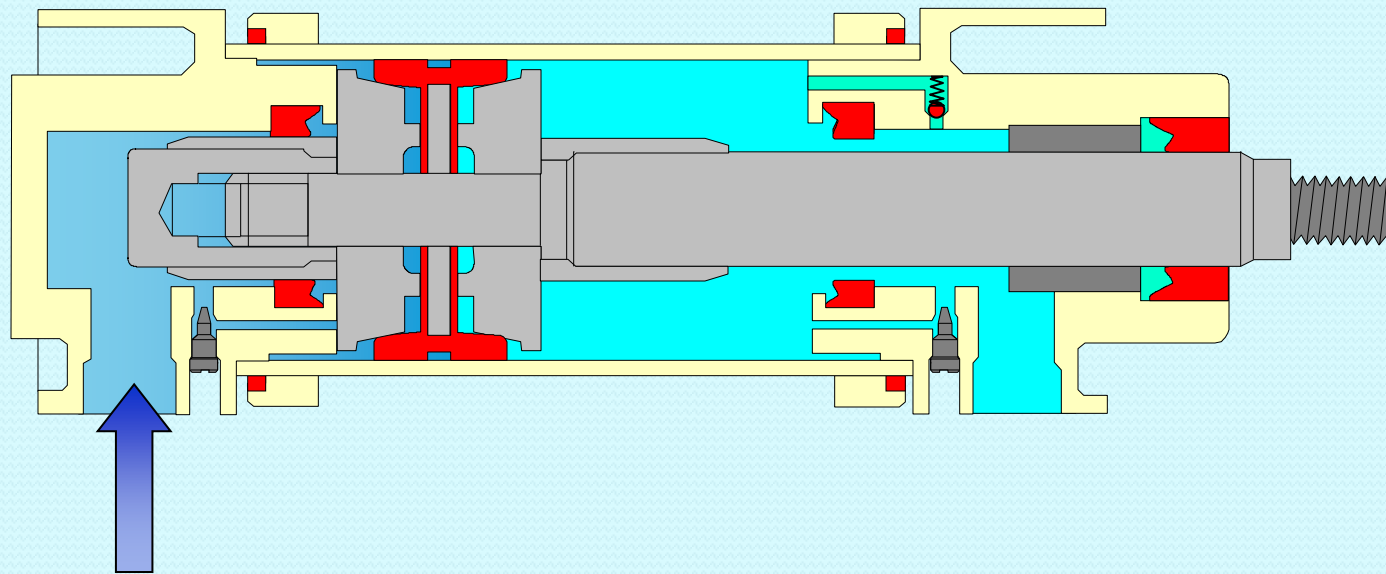
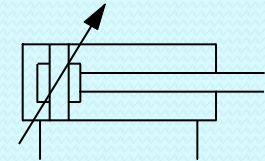
# Operation of Double Acting Cylinders with Air Cushioning



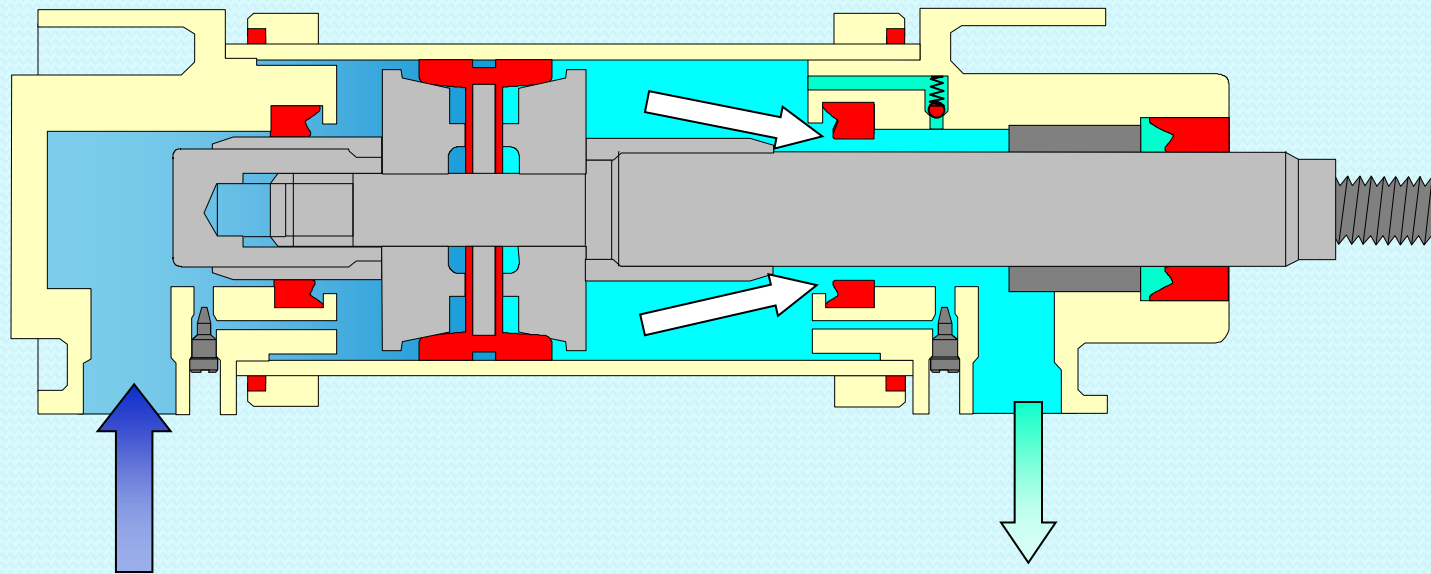
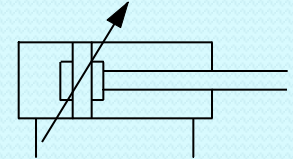
# Operation of Double Acting Cylinders with Air Cushioning



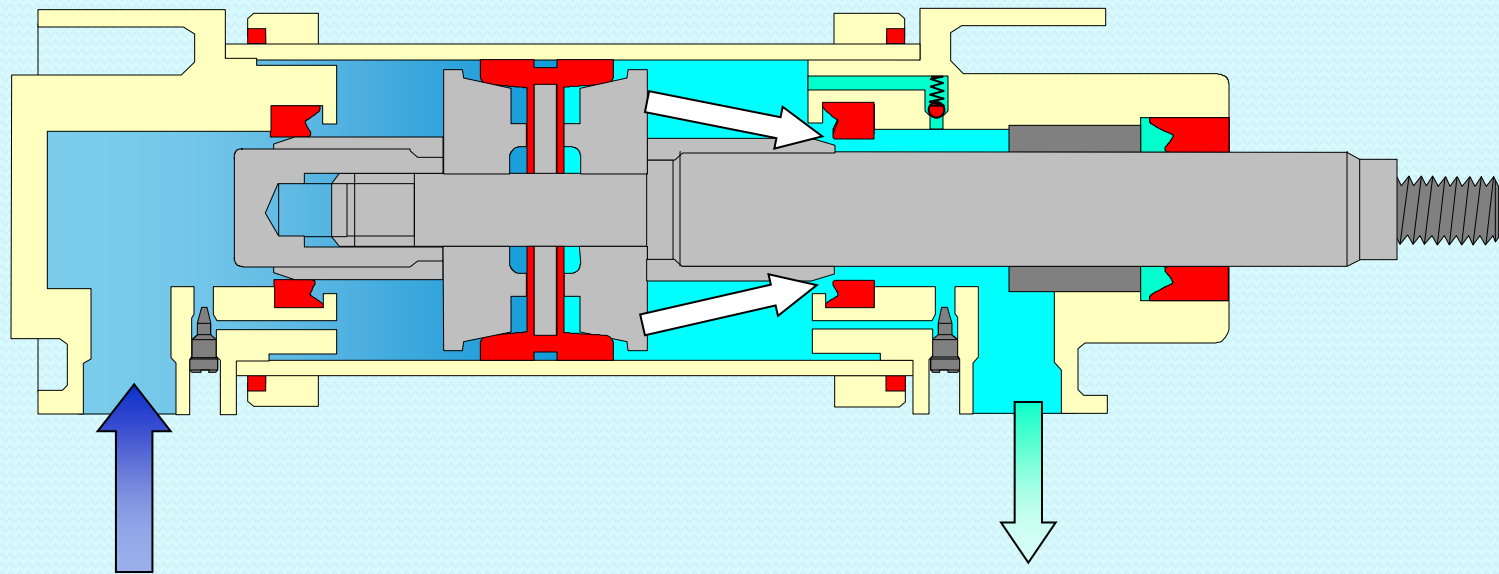
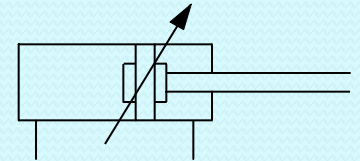
# Operation of Double Acting Cylinders with Air Cushioning



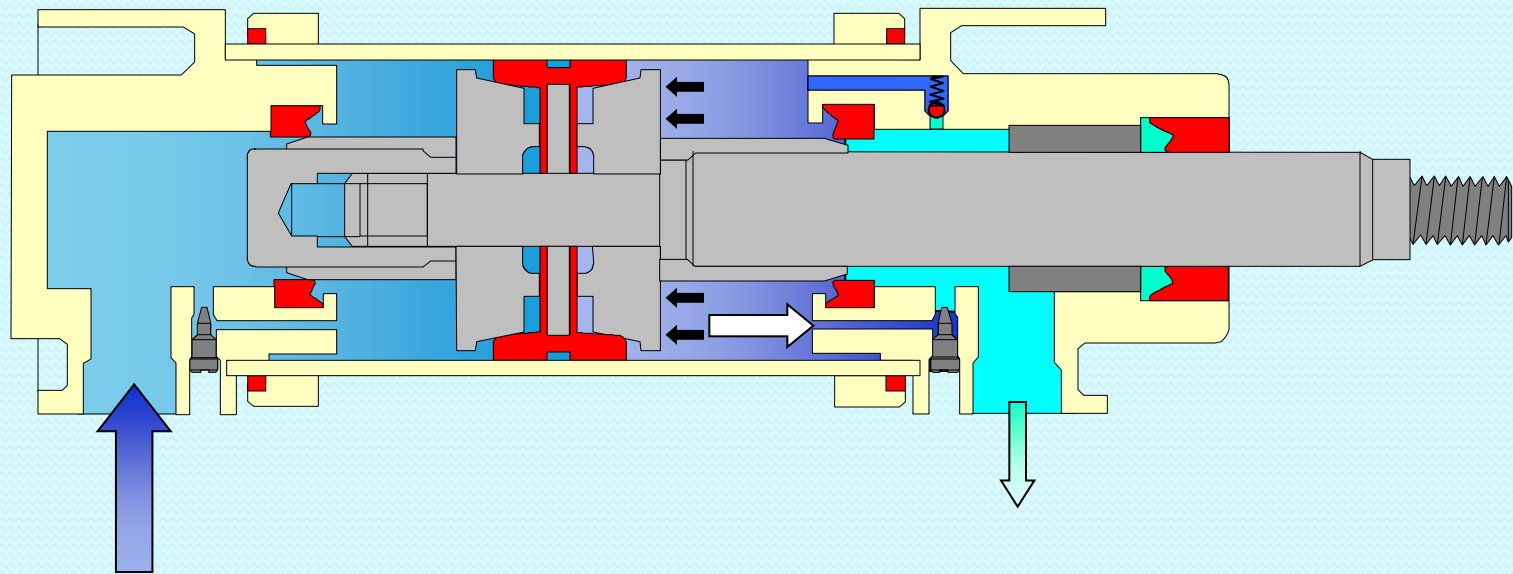
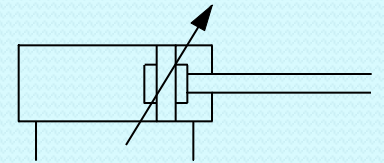
# Operation of Double Acting Cylinders with Air Cushioning



# Operation of Double Acting Cylinders with Air Cushioning

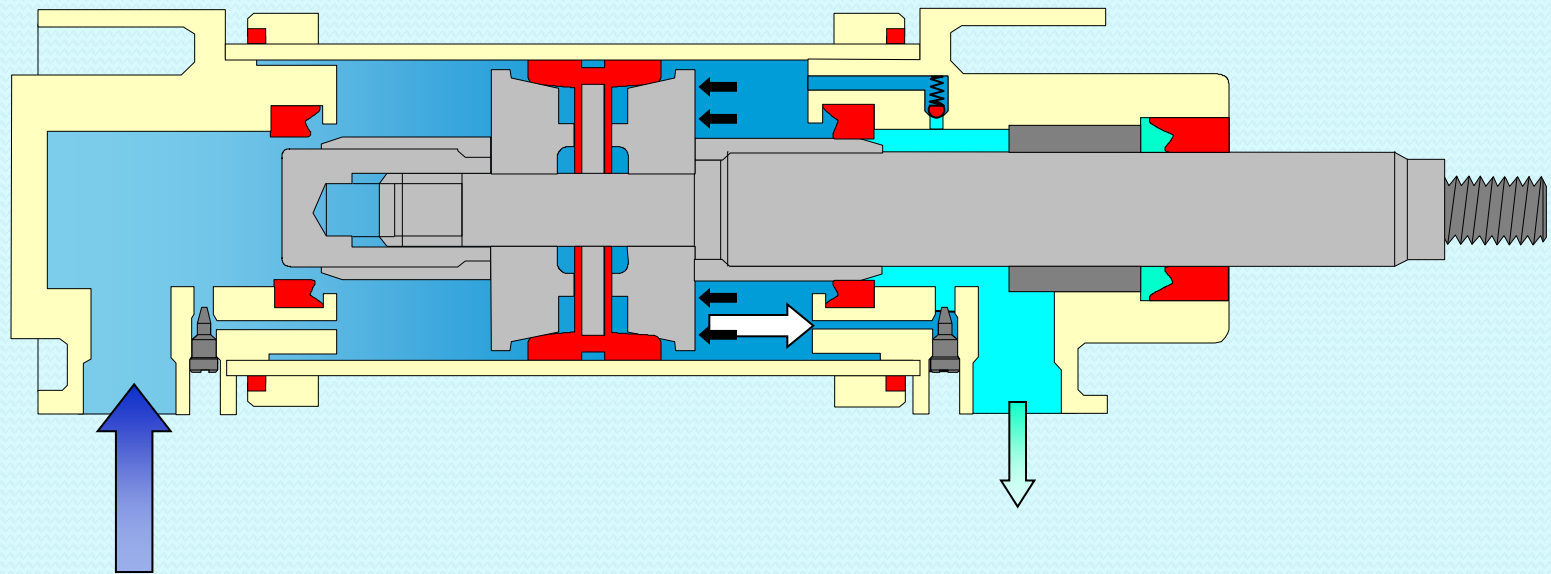
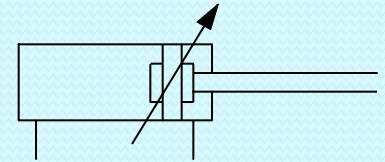


# Operation of Double Acting Cylinders with Air Cushioning

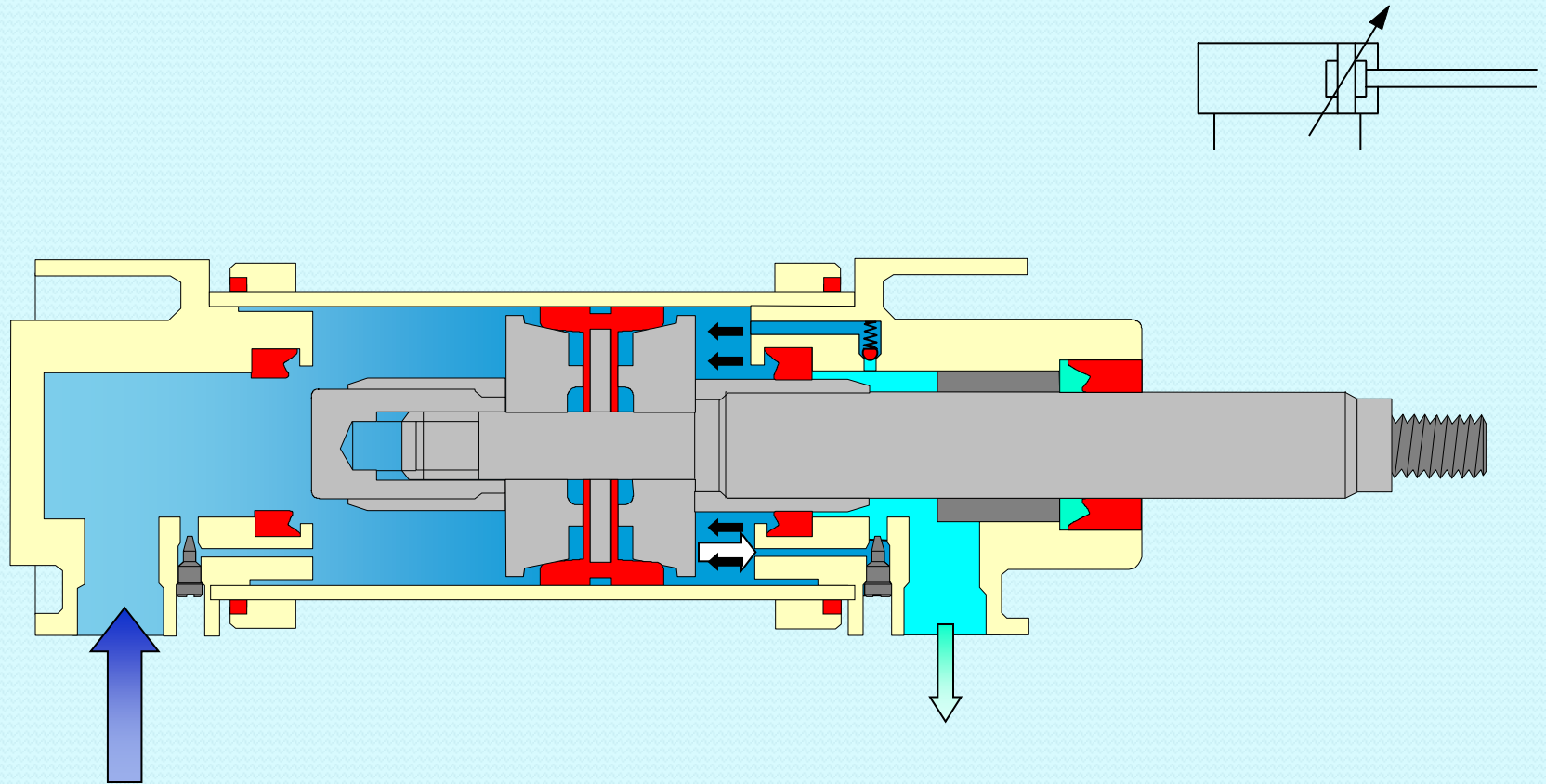




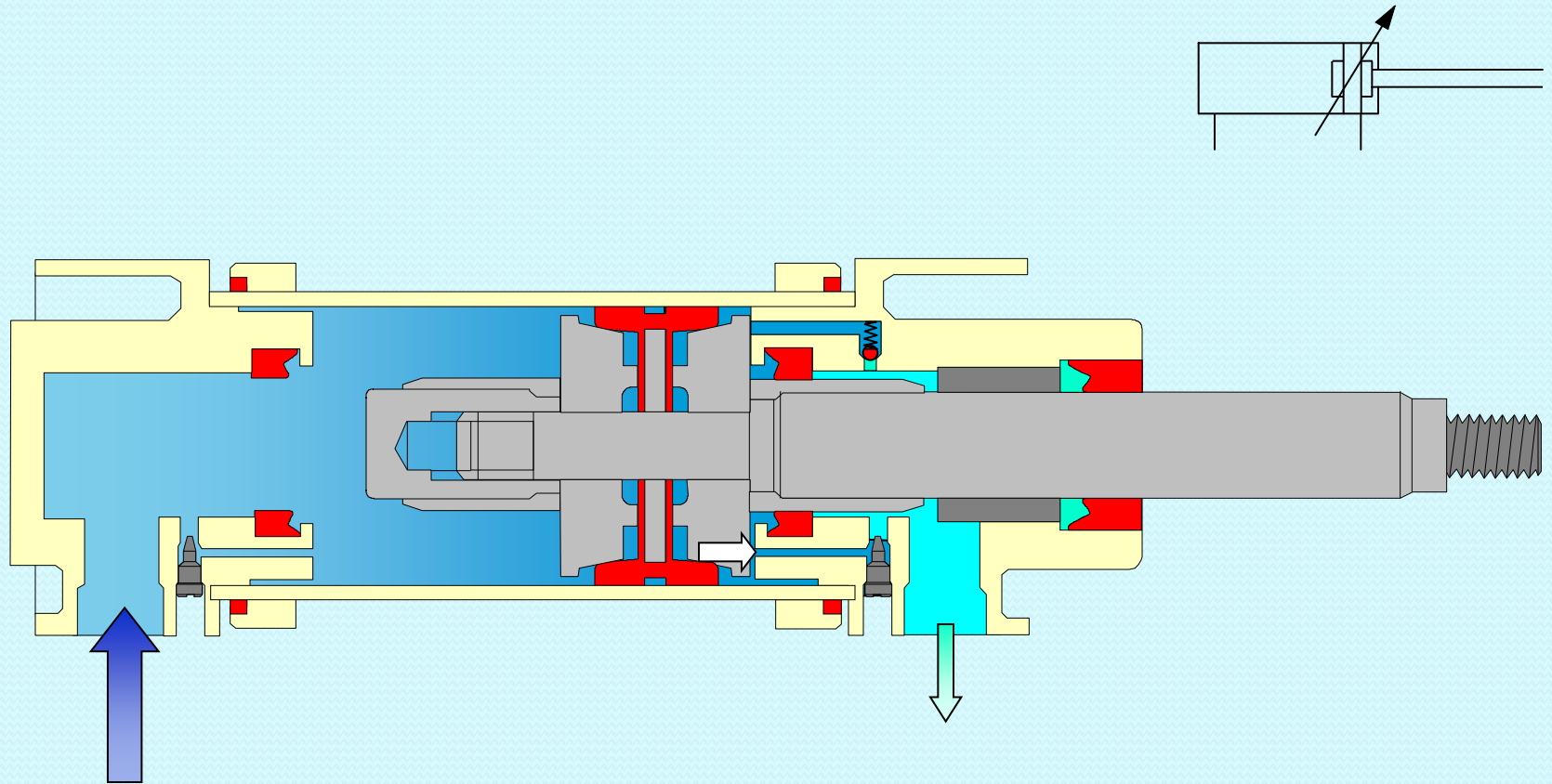
# Operation of Double Acting Cylinders with Air Cushioning



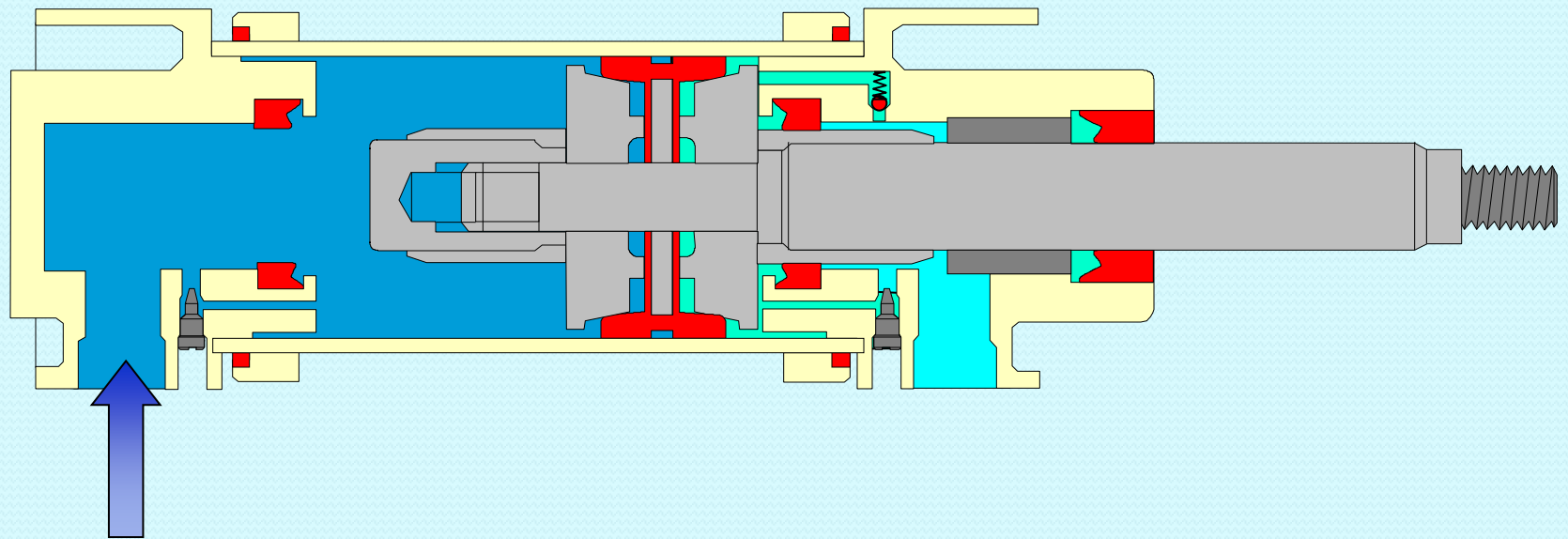
# Operation of Double Acting Cylinders with Air Cushioning



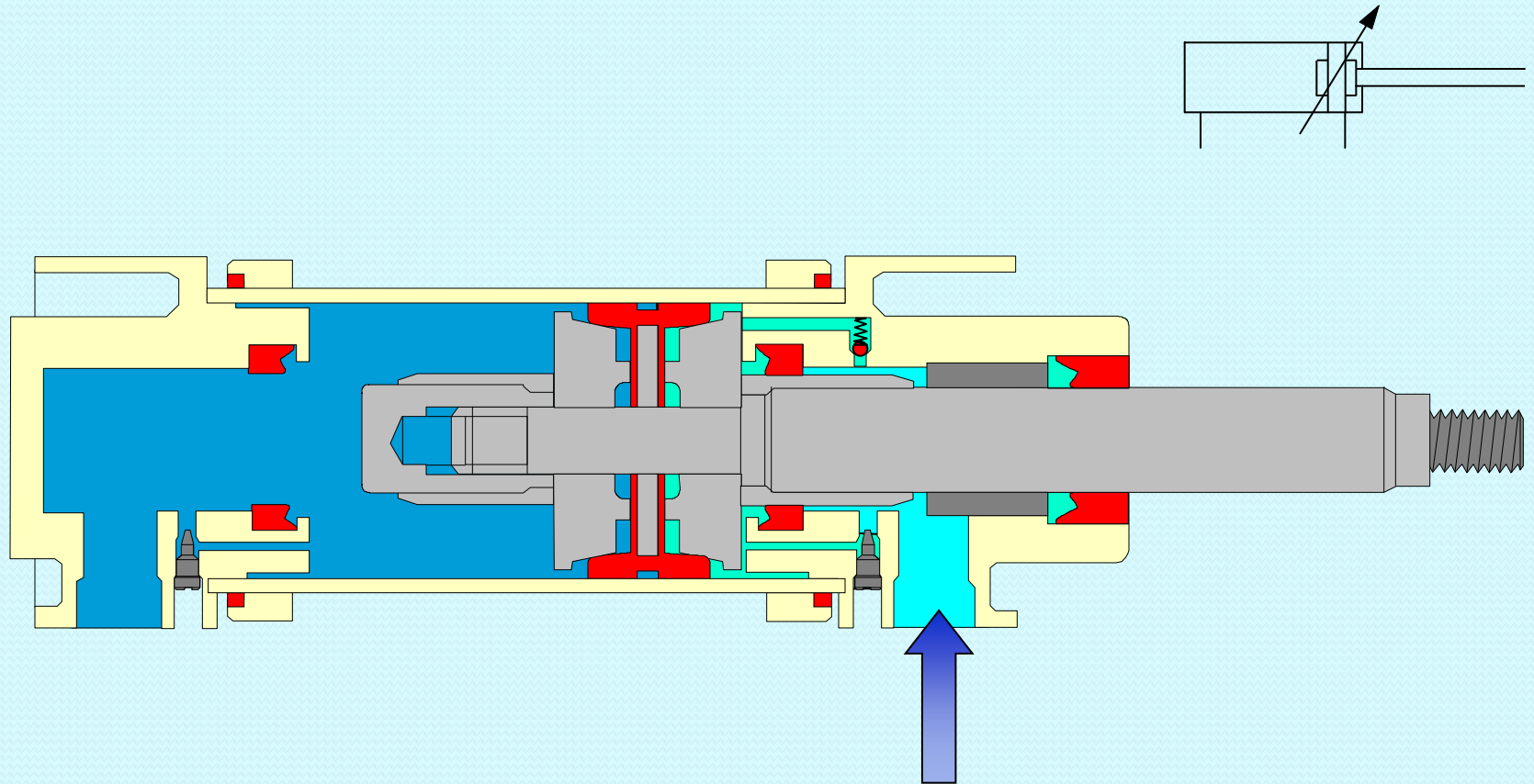
# Operation of Double Acting Cylinders with Air Cushioning



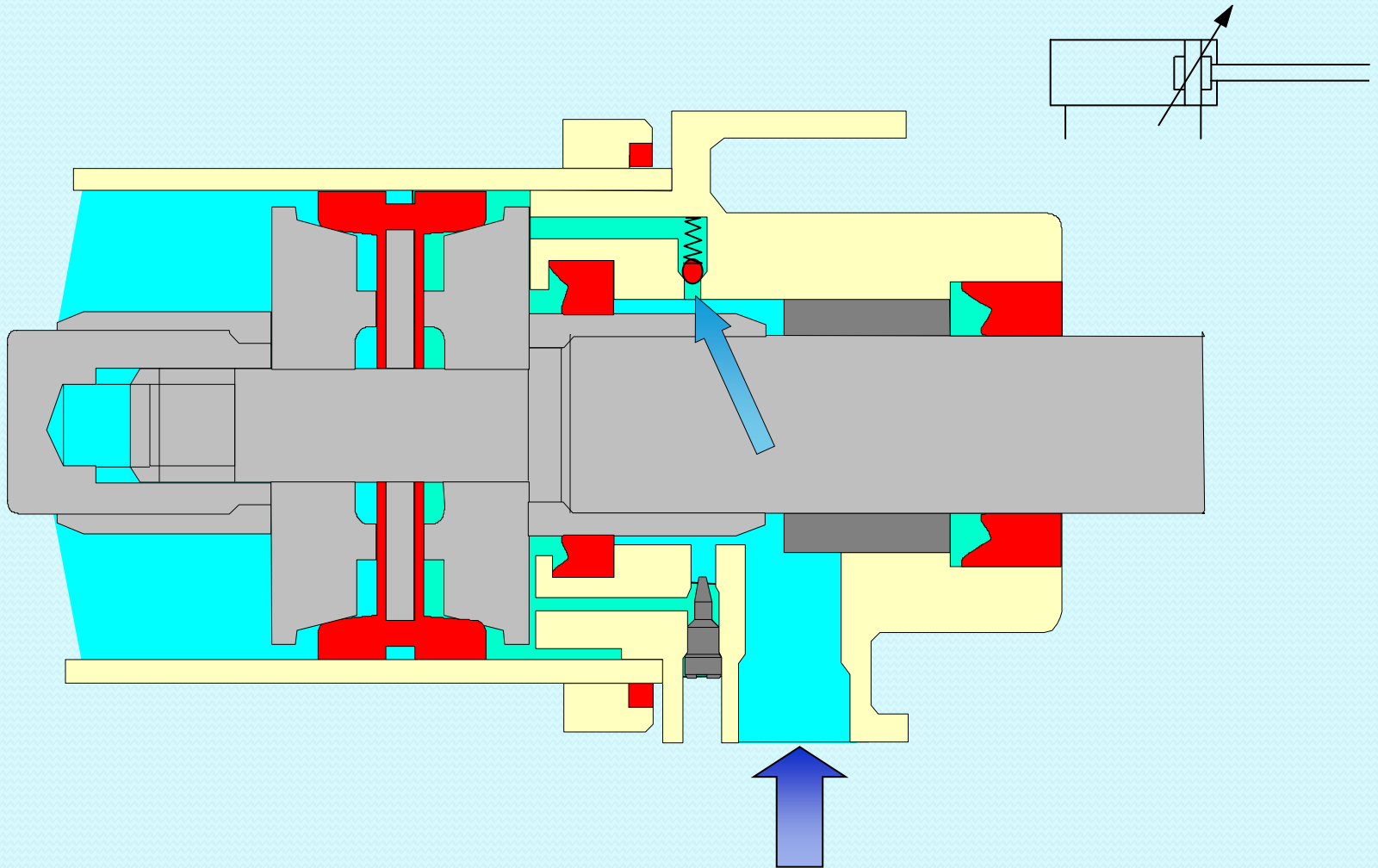
# Operation of Double Acting Cylinders with Air Cushioning



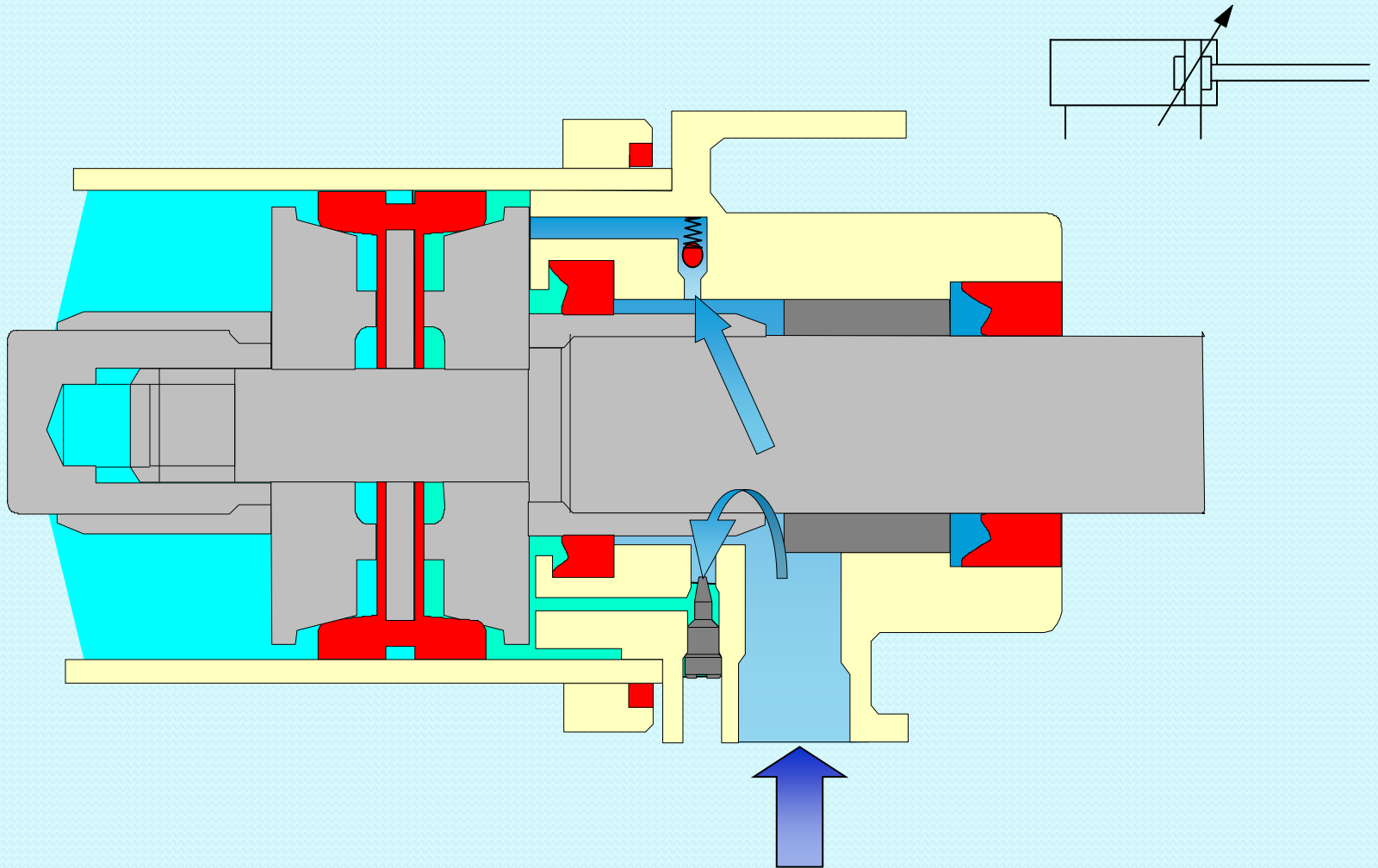
# Operation of Double Acting Cylinders with Air Cushioning



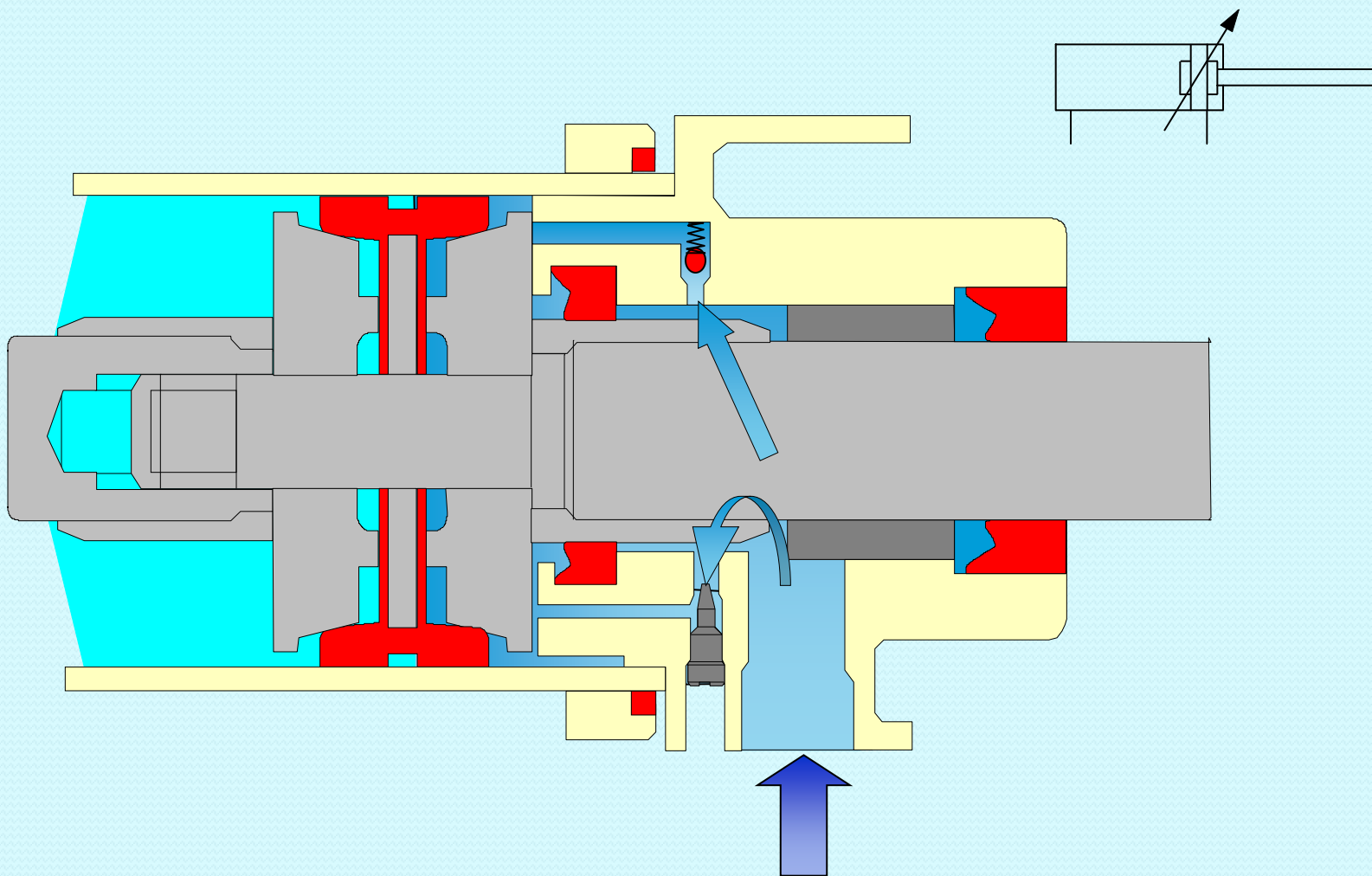
# Operation of Double Acting Cylinders with Air Cushioning



# Operation of Double Acting Cylinders with Air Cushioning



# Operation of Double Acting Cylinders with Air Cushioning

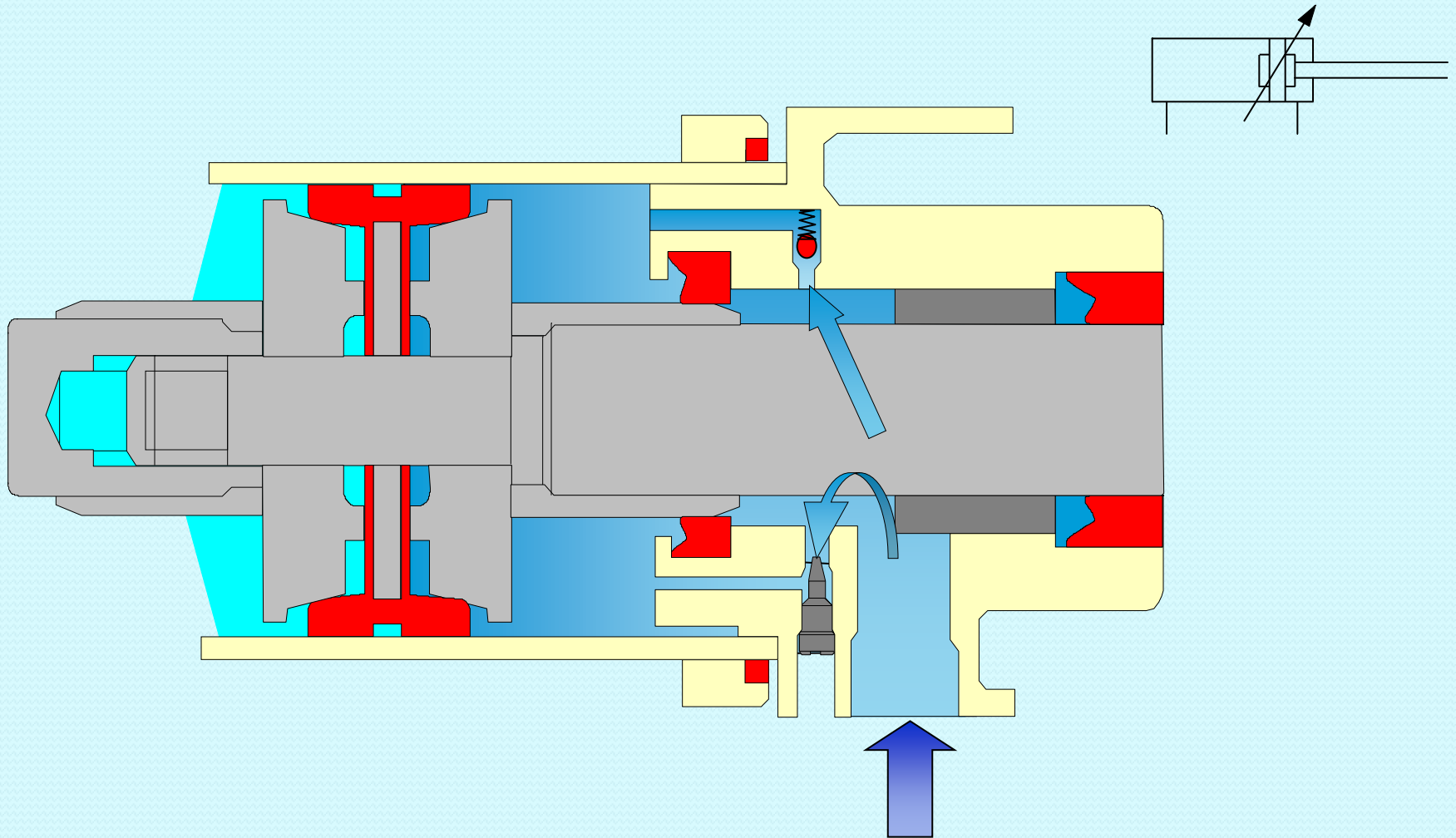




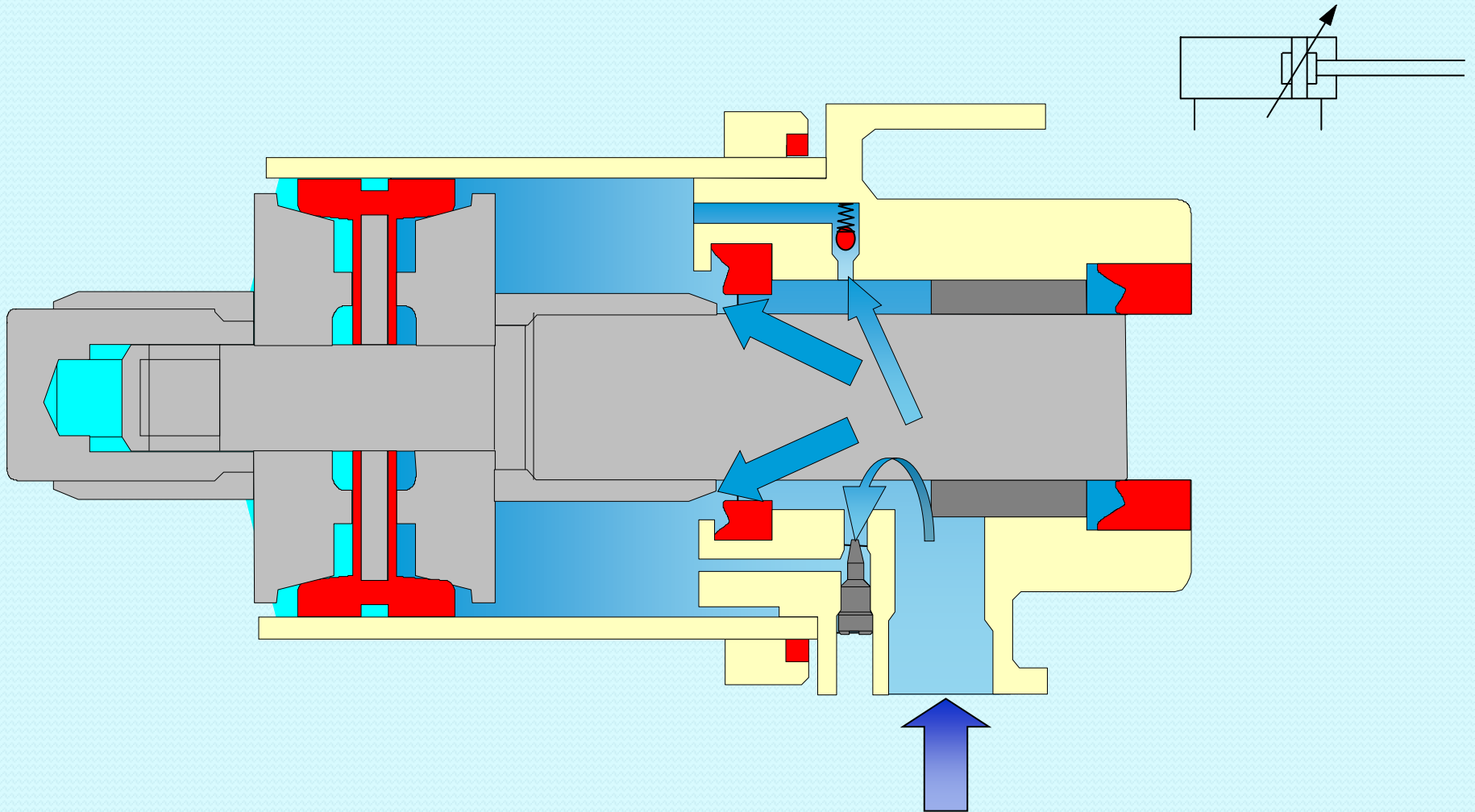




# Operation of Double Acting Cylinders with Air Cushioning

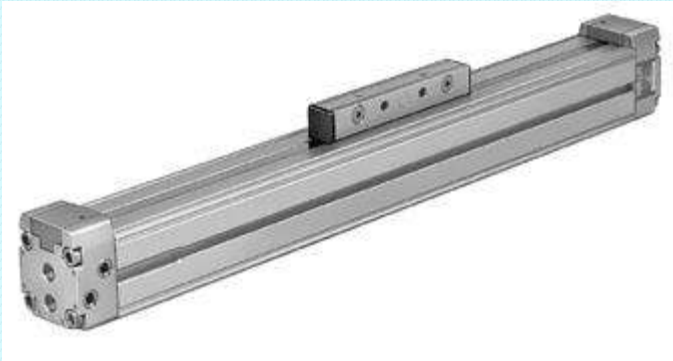


# Operation of Double Acting Cylinders with Air Cushioning

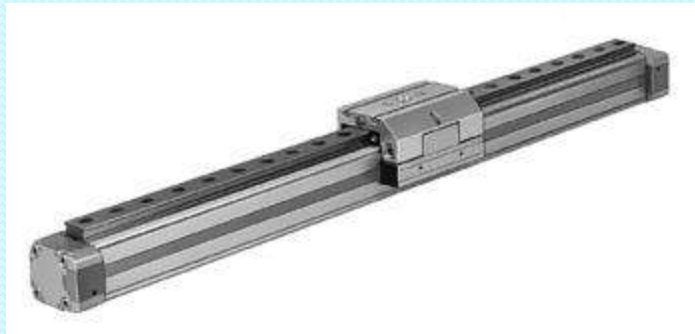


# Rodless Cylinders

Rodless cylinders or Linear Drives are used when long strokes are required or little fitting space is available.

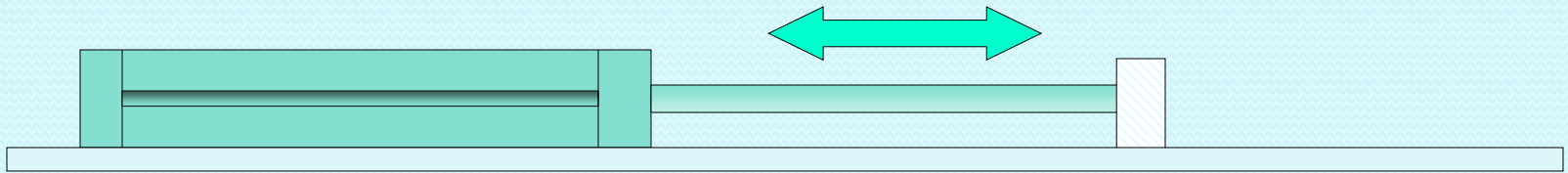


Mechanically coupled

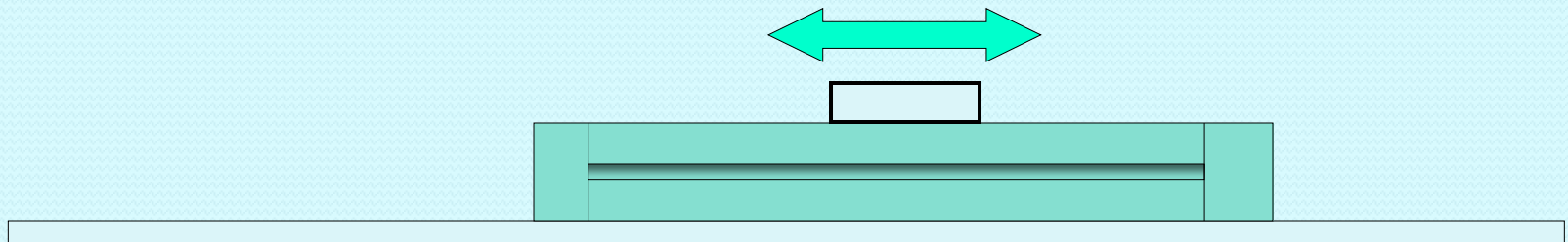


Magnetically coupled

Conventional Double Acting Cylinders require space to house the cylinder.  
Plus space to carry out the work.



More effective use of the available space can be made by using  
Rodless Cylinders



# PNEUMATIC VALVES

## FUNCTIONS :

- open and close flow paths
- regulate pressure
- directs flow to various paths
- adjust flow volume



# Directional control valves

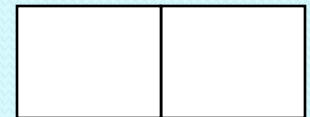


# SWITCHING SYMBOLS FOR

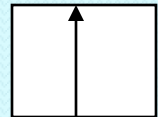
VALVES  
The valve switching position is shown by a square.



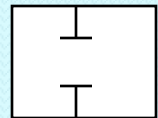
The number of squares corresponds to the number of switching position.



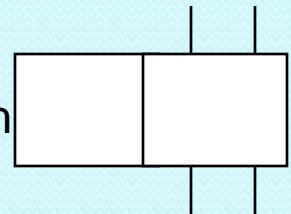
Lines indicate the flow paths, arrows indicate the direction of flow.



Closed ports are shown by two lines drawn at right angles to one another.



The connecting lines for supply and exhaust air are drawn outside the square.



# Ports and Switching

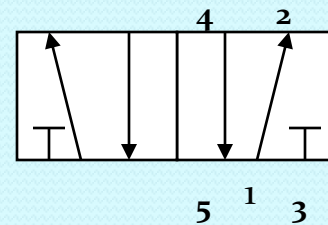
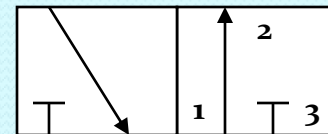
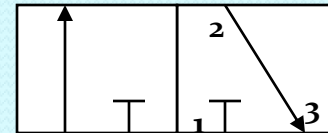
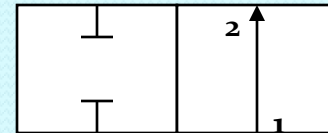
Number of ports  
 Position

2/2 – way valve, normally open position

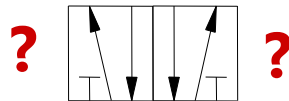
3/2 – way valve, normally closed position

3/2 – way valve, normally open position

5/2 – way valve, flow from 1-2 and from 4-5



# Actuation methods



## MANUAL

 General

 Push Button

 Lever

 Pedal

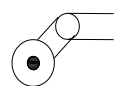
 Detent

## MECHANICAL

 Spring

 Button

 Roller

 Idle Roller

## ELECTRICAL

 Solenoid

## PNEUMATIC

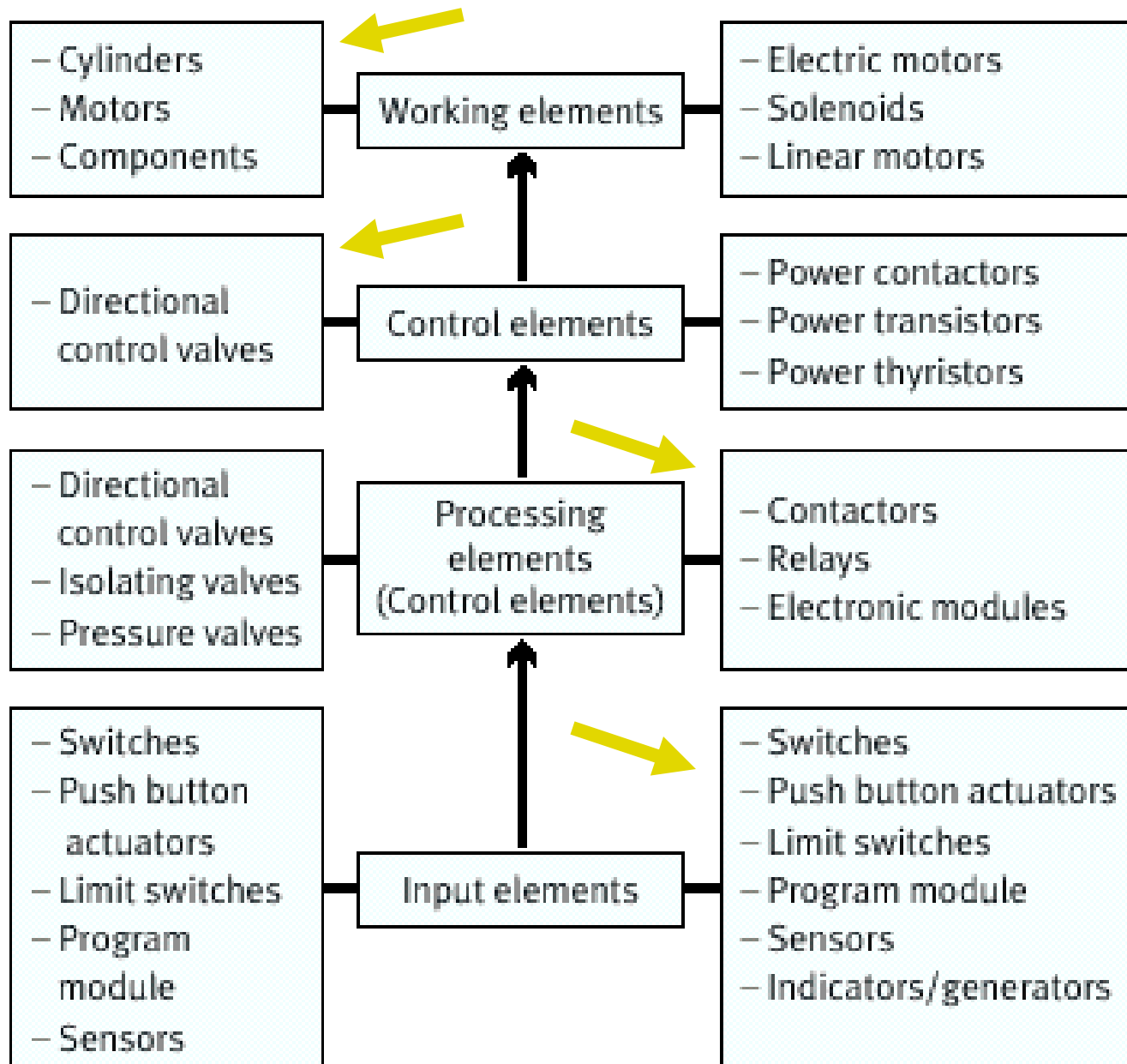
 Pneumatic



# ELECTRO PNEUMATICS

## Pneumatics/ Hydraulics

## Electrics/ Electronics



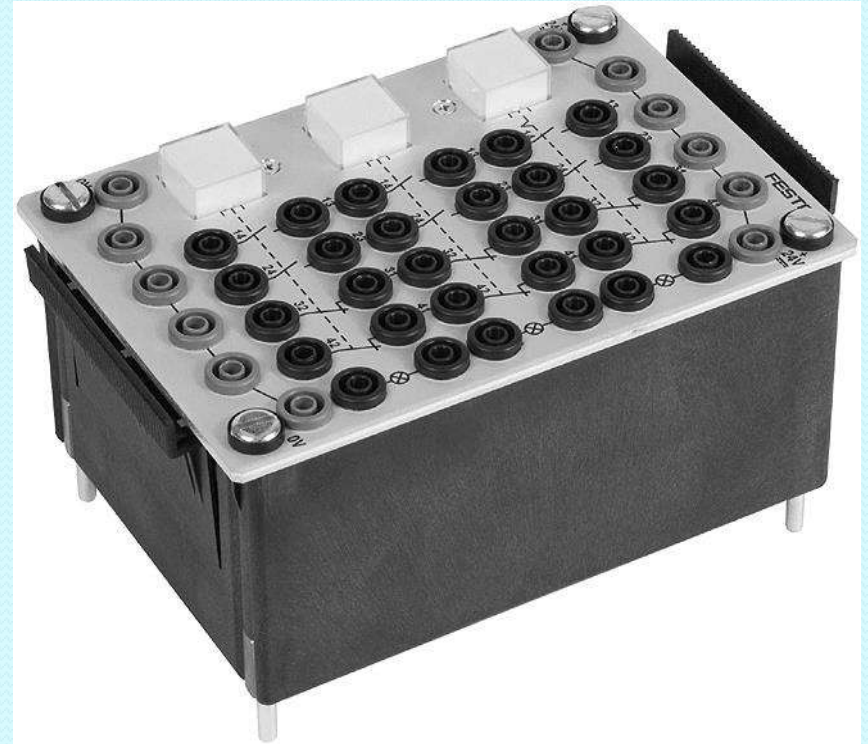
# SWITCHES

## POSITIONS :

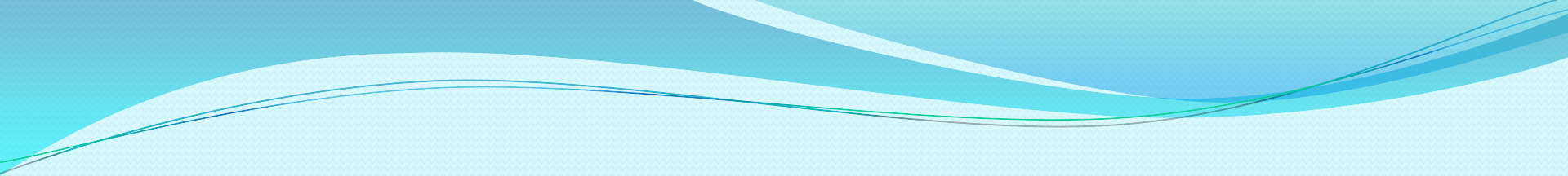
- normally open
- normally closed

## CONTACT CONFIGURATIONS :


- normally open contact
- normally closed contact
- changeover contact



Contact load-----1A (max)  
Power consumption-----0.48W



# Solenoid Valves



# SOLENOIDS

## DEFINITION:

→ a device which is primarily used as an electromagnet used to drive a plunger for the purpose of control actuation.

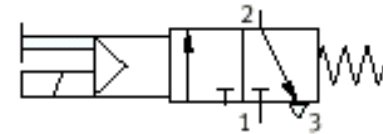
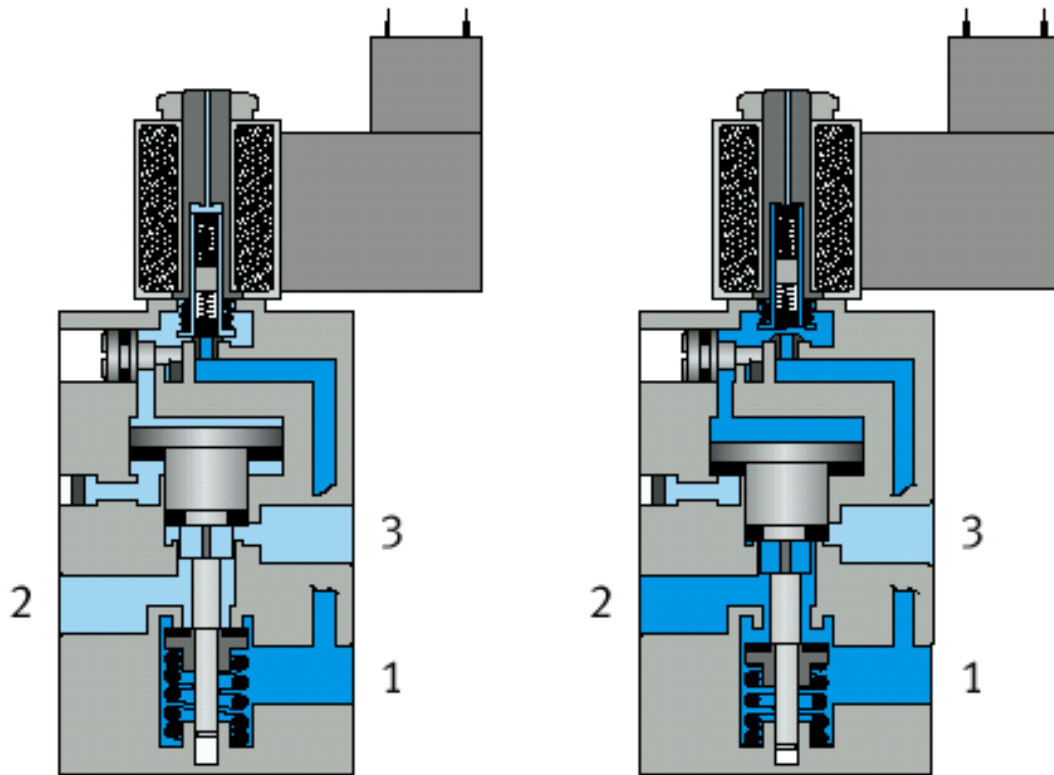
## OPERATING PRINCIPLE:

→ passing an electric current through a coil of copper wire generates an electromagnetic field

→ adding turns to the coil strengthens the EMF while the lines of force are concentrated through the circular form of the coil and the EMF is greatly increased



## 3/2 - way Directional Control Valve, Solenoid Actuated, Spring Returned



When an electric current is applied to the coil, an EMF is generated which lifts the lower sealing lips of the armature and opens the passage for pilot air. Pilot air then applies pressure on the diaphragm which then causes the valve to switch its position.

Upon removal of the current, the pilot air passage closes and a spring returns the valve to its normal switching position.

# PILOT SIGNAL FLOW

By using pilot control, the size of the solenoid  
Can be kept to a minimum.

Main Advantages :

- @ It reduced power consumption
- @ it reduced heat generation

ELECTRICAL SIGNAL  
APPLIED TO SOLENOID



SOLENOID ACTUATES  
PILOT VALVE



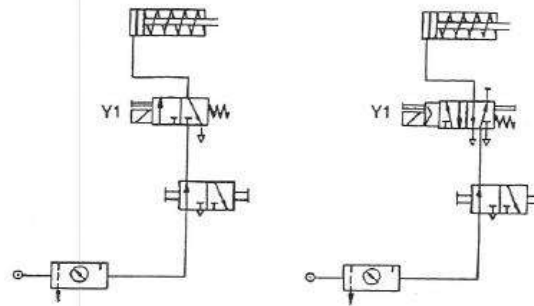
PILOT ACTUATES  
MAIN VALVE

# Seminar EP 211 Electro-Pneumatics Control

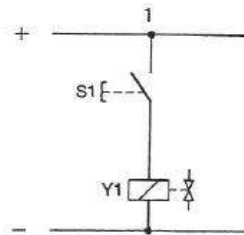
**FESTO**  
DIDACTIC

Solution: 1 Sorting device

Circuit diagram, pneumatic



Circuit diagram, electric



## Relays

Relays are electro-magnetically actuated switches. They consist of a housing with electromagnet and movable contacts. An electromagnetic field is created when a voltage is applied to the coil of the electromagnet. This results in attraction of the movable armature to the coil core. The armature actuates the contact assembly. This contact assembly can open or close a specific number of contacts by mechanical means. If the flow of current through the coil is interrupted, a spring



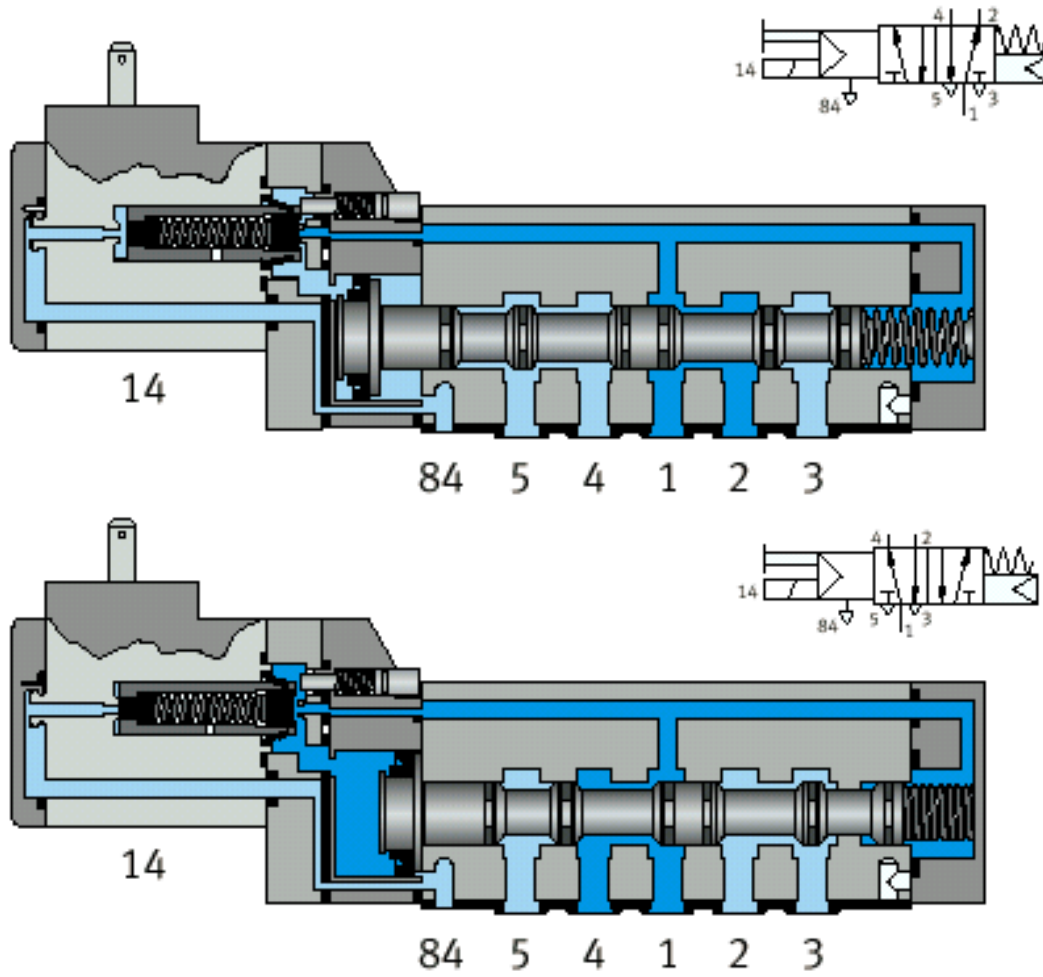
## Advantages of Relays

- Easily adapted to various operating voltages
- Not much affected by the temperature of their surroundings
- Relatively high resistance between contacts in the off state
- Several independent circuits can be switched

## Disadvantages of Relays

- Working surface of contacts wear through oxidation
- Large space requirement compare to transistors
- Noise is created during the switching operation
- The contacts are affected by contamination
- Limited switching speed of 3ms - 17ms

## 5/2 - way Directional Control Valve, Solenoid Actuated, Spring Returned



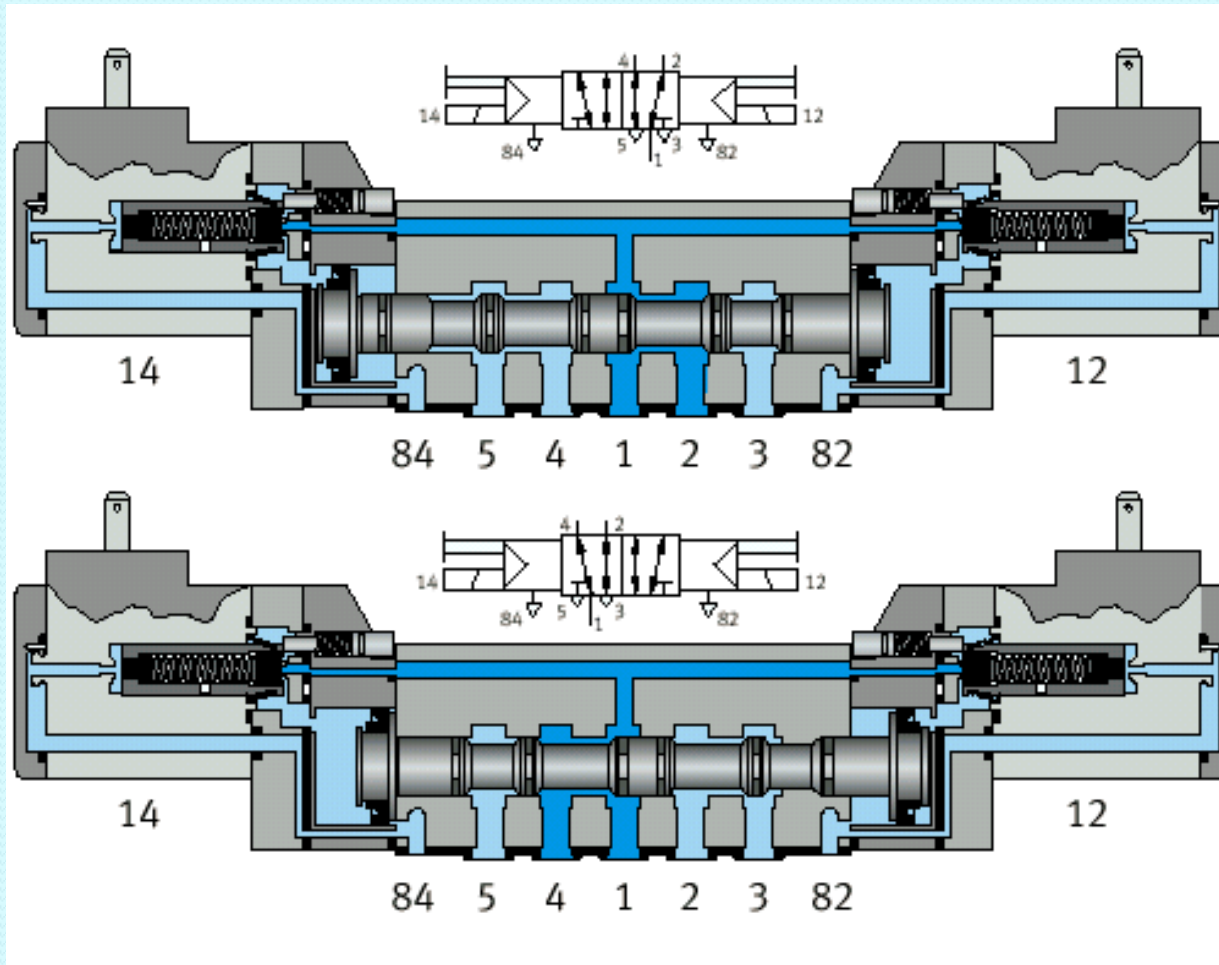
When the solenoid is energized, the armature moves and the pilot air passage opens. The pilot air applies pressure to the left side of the valve piston resulting to the valve switching its position.

Upon removal of the electrical signal, a spring returns the valve to its neutral switching position.

Used for the control of double acting cylinders.



## 5/2 - way Directional Control Valve, Double Solenoid Actuated



Because of the absence of a return spring, double solenoid actuated valves retain the last signal administered to them. They remain in their last switched position even with power removed from both solenoids.

Effectively, this means that this valve has **“memory characteristic”**.

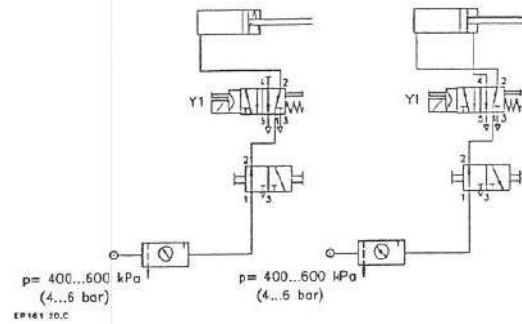
# Seminar EP 211

## Electro-Pneumatics Control

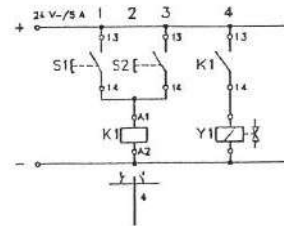


Solution: 3 Tipping device

Circuit design, pneumatic



Circuit design, electric

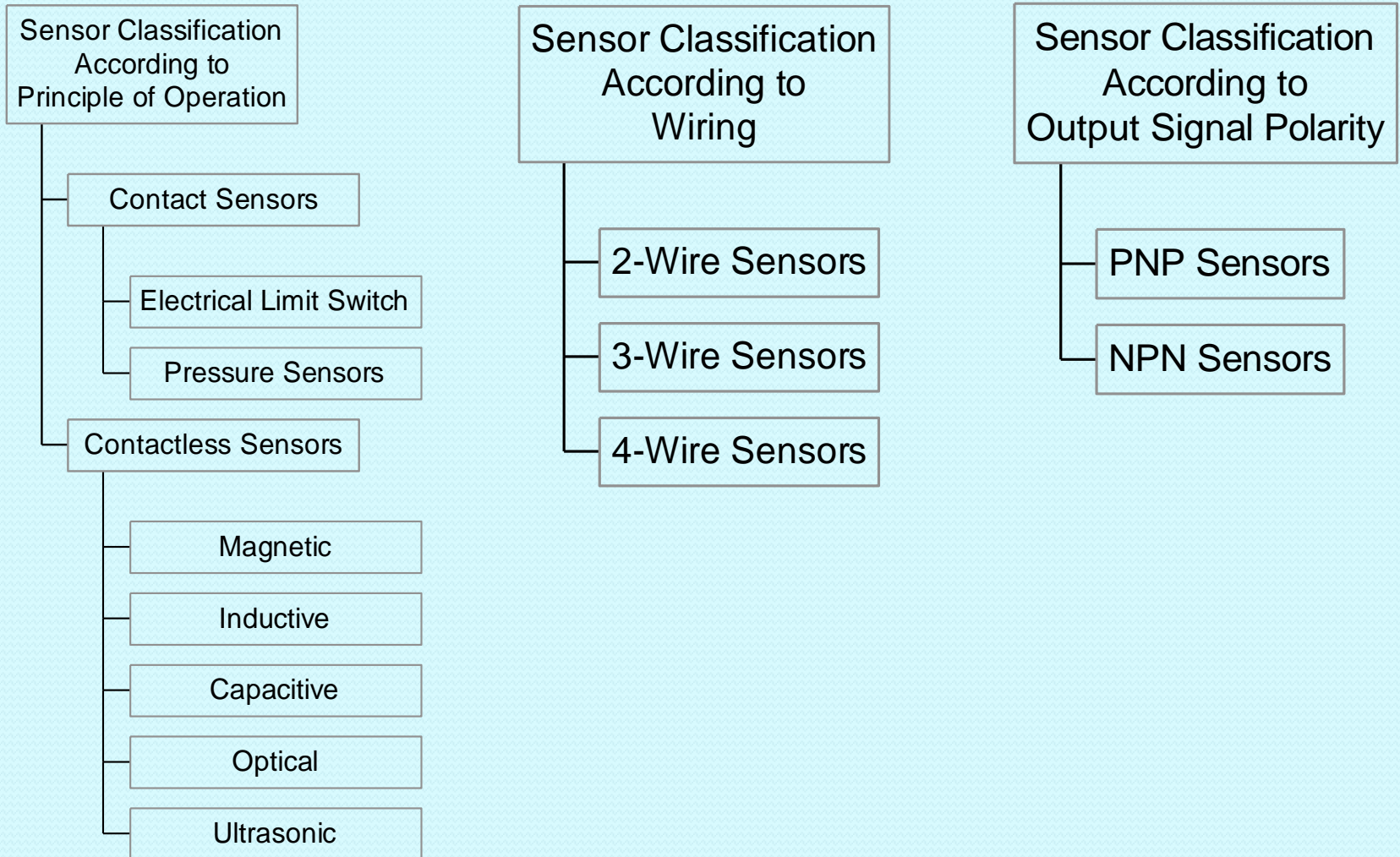


**Sensors**

# What are sensors?

A sensor is a technical converter, which converts a physical value such as temperature, pressure, flow, or distance, into a different value which is easier to evaluate. This is usually an electrical signal such as voltage, current, resistance or frequency of oscillation.

# Sensor Classifications



# SENSORS

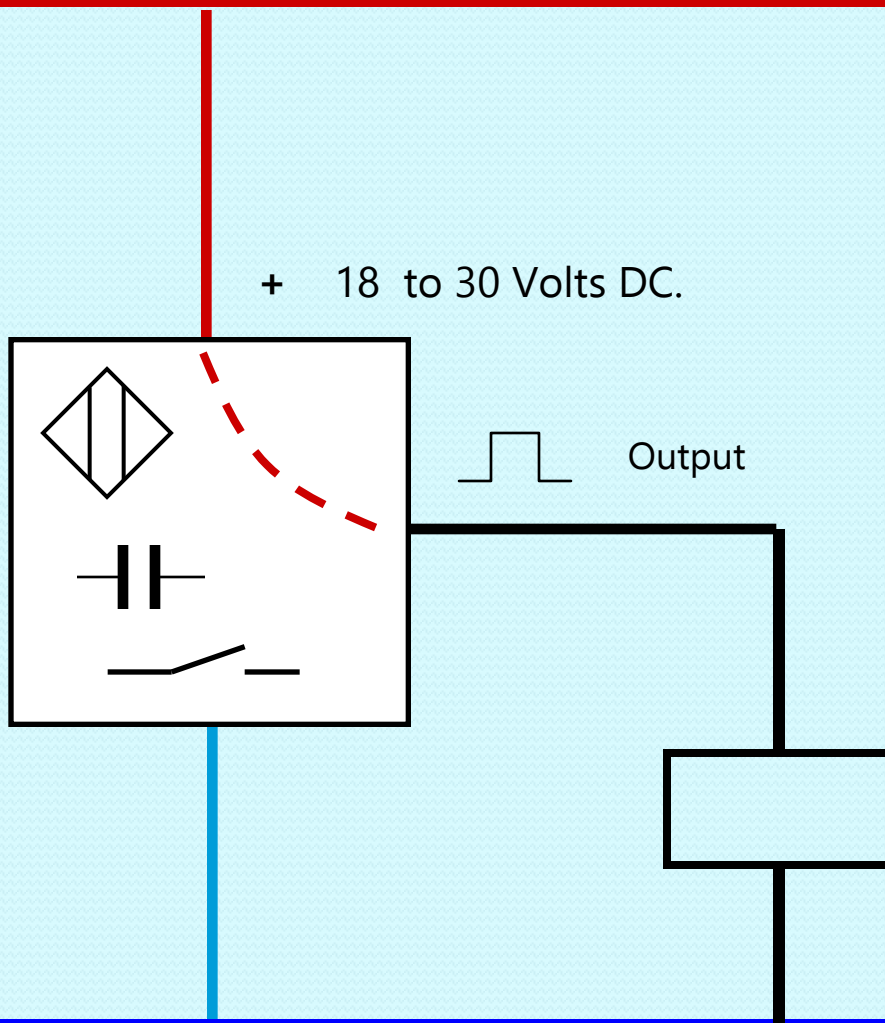
Devices which convert physical variables into form of electrical signals to gather data, monitor or control a process.

## TYPES:

**Contact Sensors** – mechanical in nature, subject to mechanical wear and with predictable failure rate. Contact sensors include limit switches, roller switches, and pressure sensors.

**Contactless Sensors** – Proximity sensors (reed switch, inductive, capacitive, and optical sensors).

24v DC



+ 18 to 30 Volts DC.

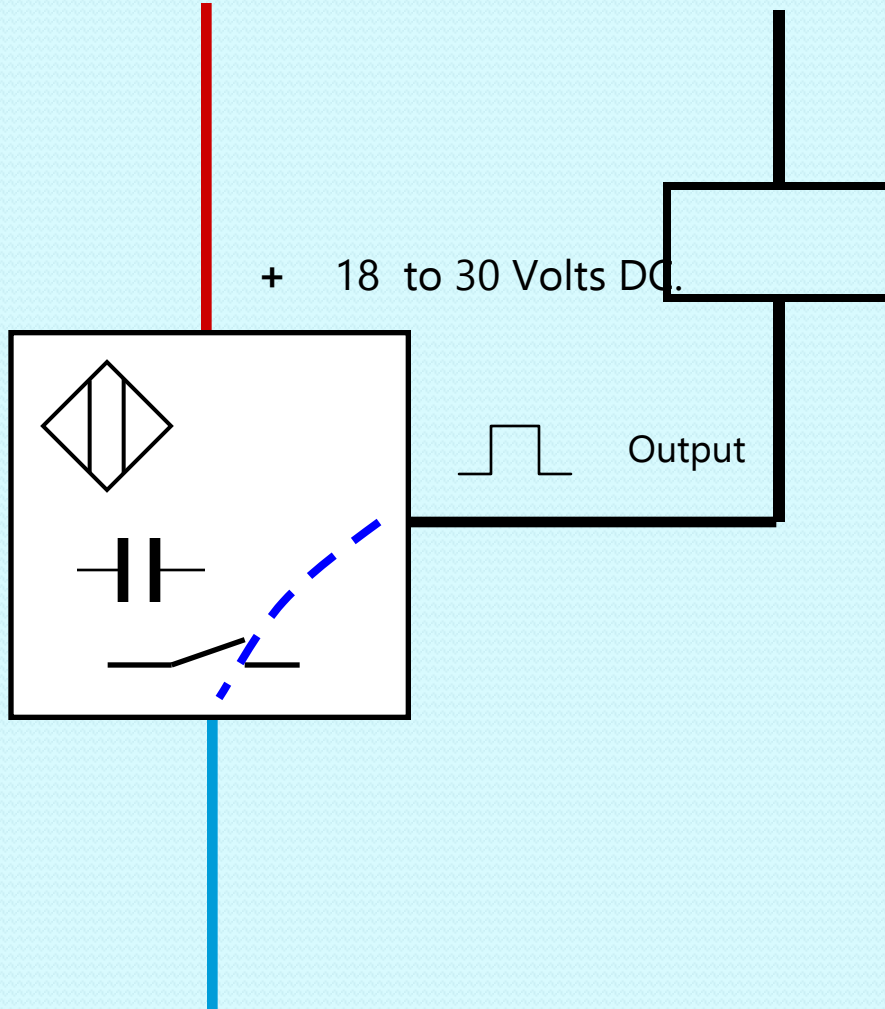
PNP Type

Output is Positive

Positive switching

0v

24v DC



NPN Type

Output switches through to 0v

Negative switching

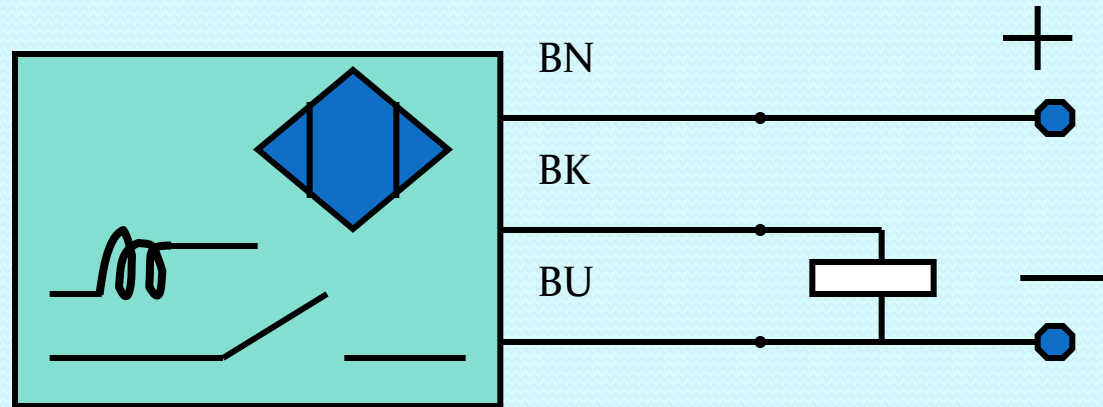
0v



# INDUCTIVE PROXIMITY SENSORS

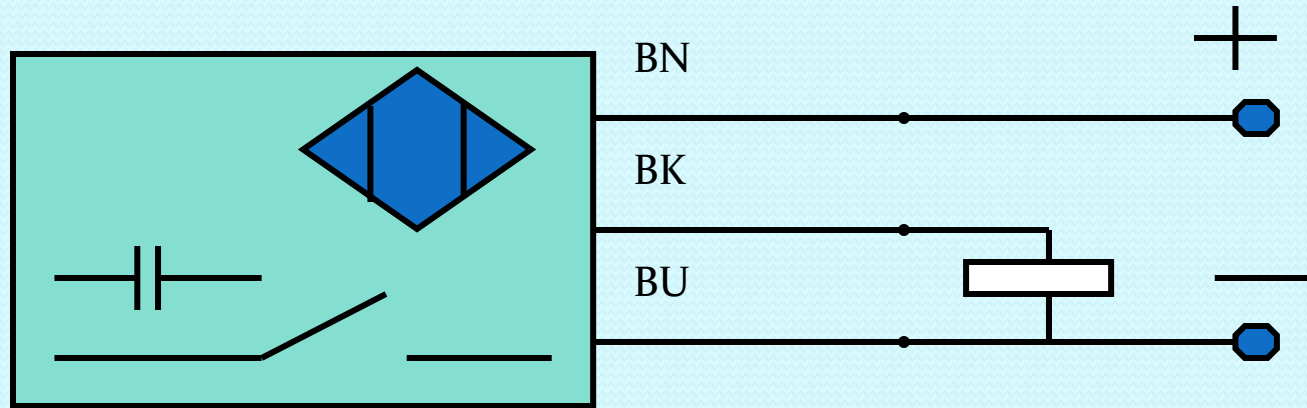
Note:

For metallic materials only



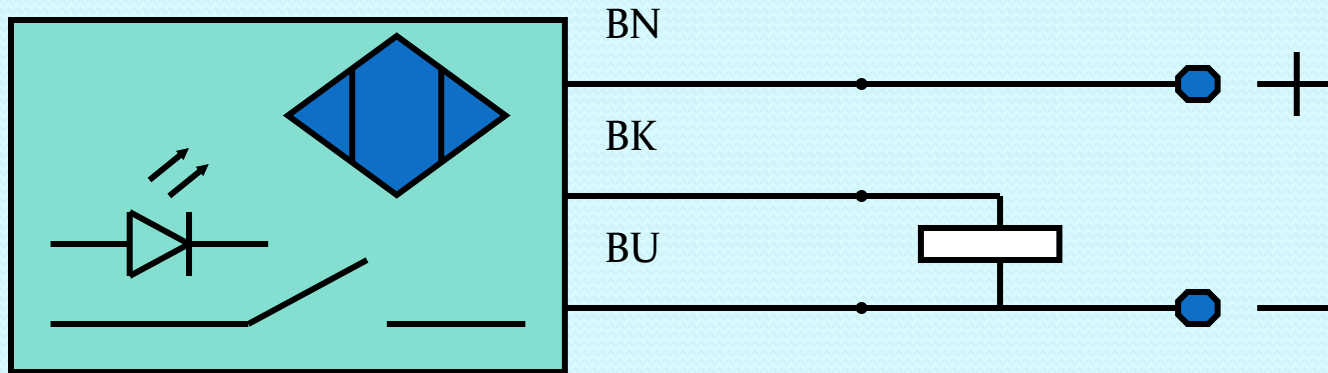
Switching Voltage	-----	10-30 V DC
Nominal switching distance	-----	4mm
Switching frequency	-----	800Hz (max)
Output function	-----	NO contact, PNP switching
Output current	-----	400 mA (max)

# CAPACITIVE PROXIMITY SENSORS



Switching Voltage ----- 10-30V DC  
Nominal switching distance ----- 4mm  
Switching frequency ----- 100 Hz (max)  
Output function ----- NO contact, PNP switching  
Output current ----- 200mA (max)

# OPTICAL PROXIMITY SENSORS



Switching Voltage	-----	10-30 V DC
Nominal Switching distance	-----	0-100 mm (adjustable)
Switching frequency	-----	200 Hz (max)
Output function	-----	NO contact, PNP switching
Output current	-----	100mA (max)

# SENSORS



Inductive Sensor



Optical Sensor



Optical Sensor

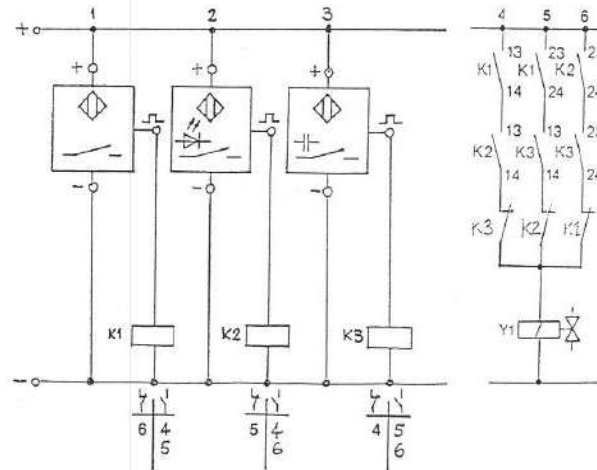
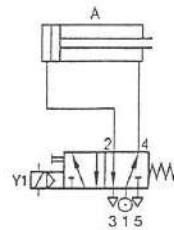


Magnetic Sensor

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Solution: 4 Punching device

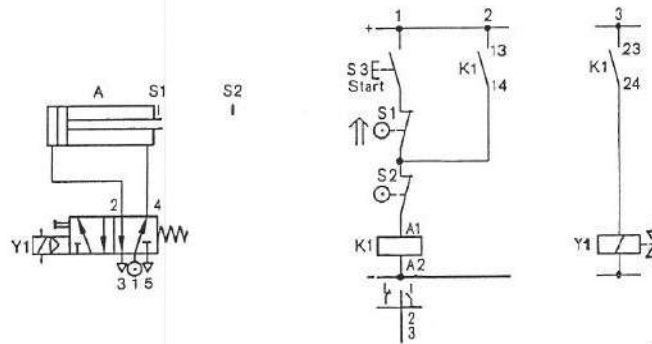
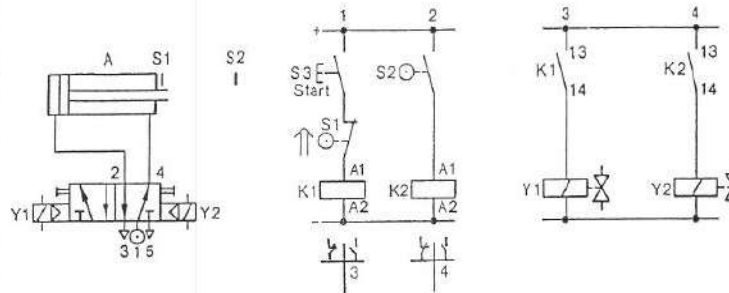


# Seminar EP 211

## Electro-Pneumatics Control



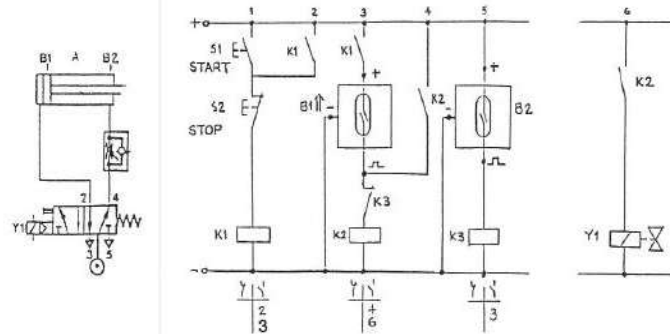
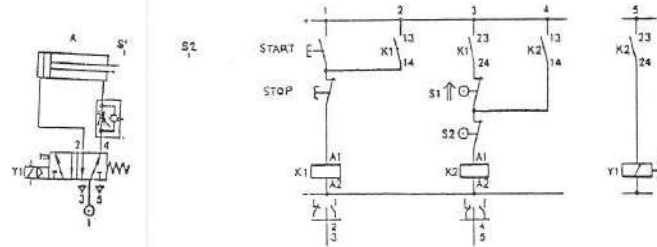
Solution: 7 Ejecting workpiece



# Seminar EP 211 Electro-Pneumatics Control



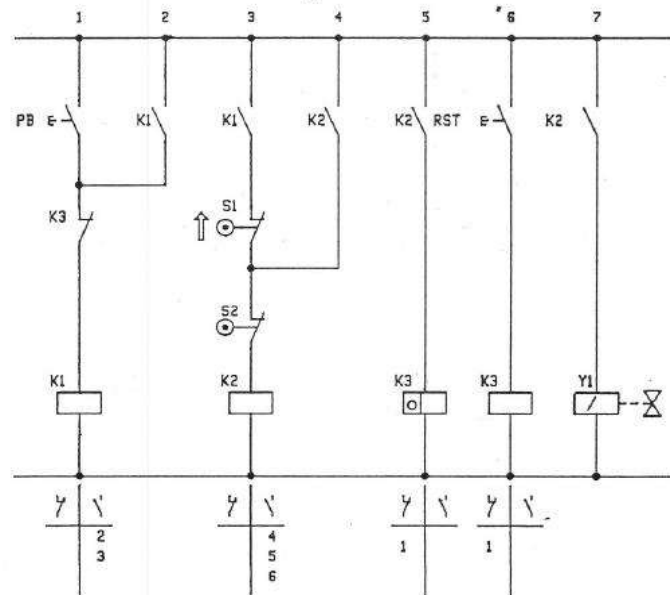
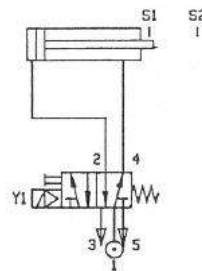
## Solution : 9 Automatic washing system



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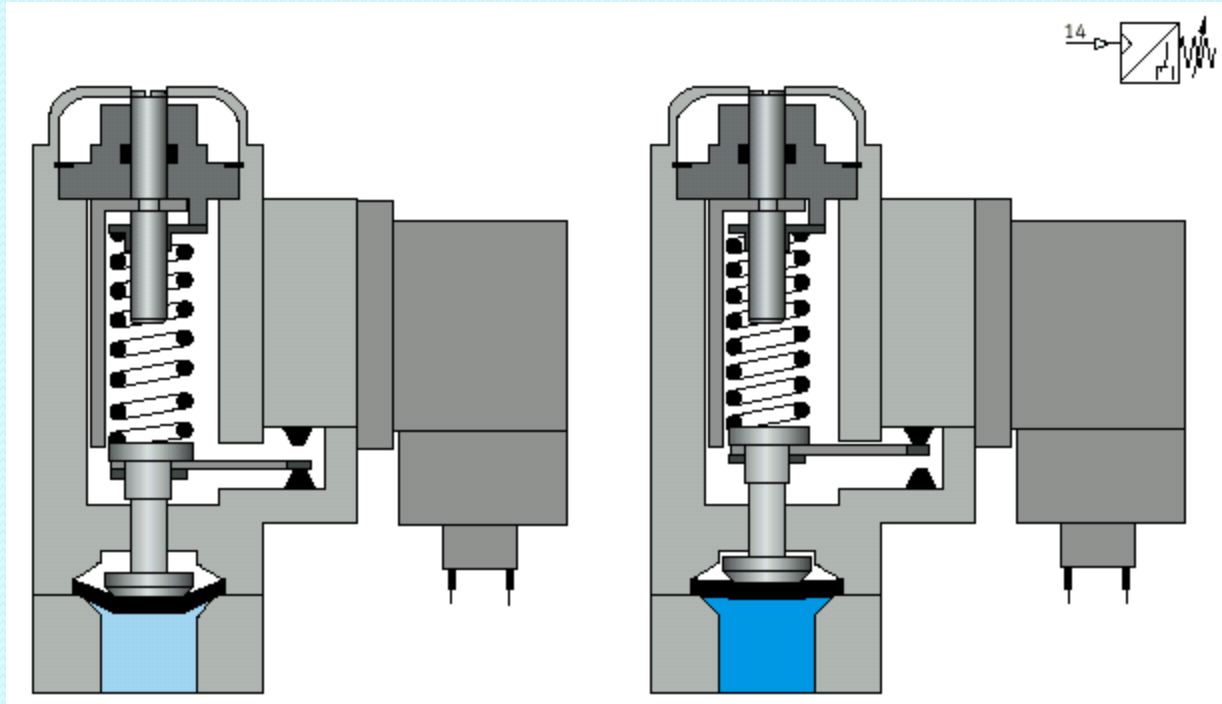
**FESTO**  
**DIDACTIC**

Solution: 12 Automatic Washing System (Counter)





## Pneumatic-Electric Converter



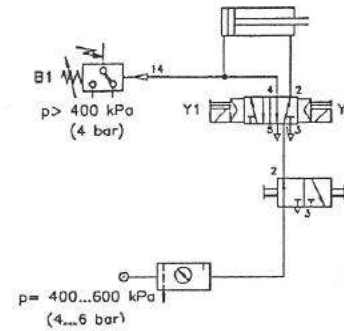
When a pneumatic signal of sufficient pressure to overcome the spring force is applied to the diaphragm, the resultant force operates the stem. The force required to operate the stem is controlled by the adjusting screw. Movement of the stem actuates a micro switch via a switching lever which results to switching of contacts.

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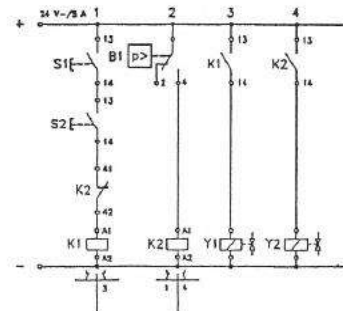
**FESTO**  
DIDACTIC

Solution: 10 Stamping device

Circuit design, pneumatic



Circuit design, electric

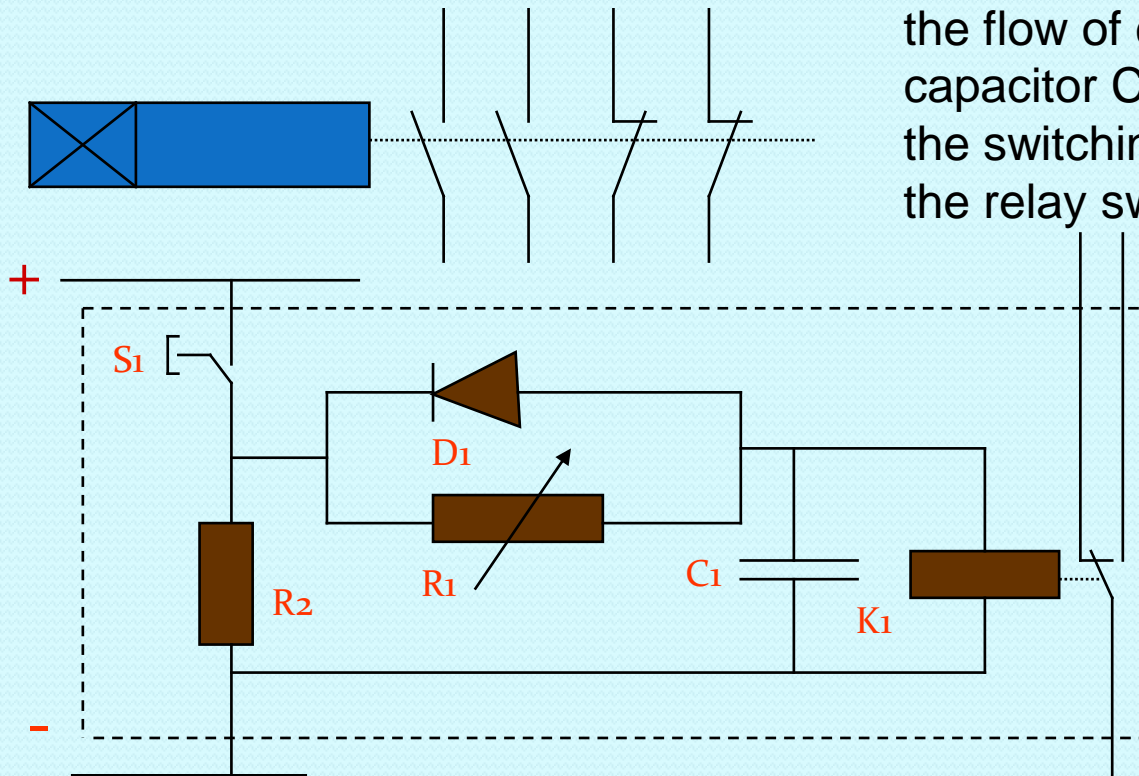


# ELECTRICAL TIMERS

- *Time relay with switch on delay*
- *Time relay with switch off delay*

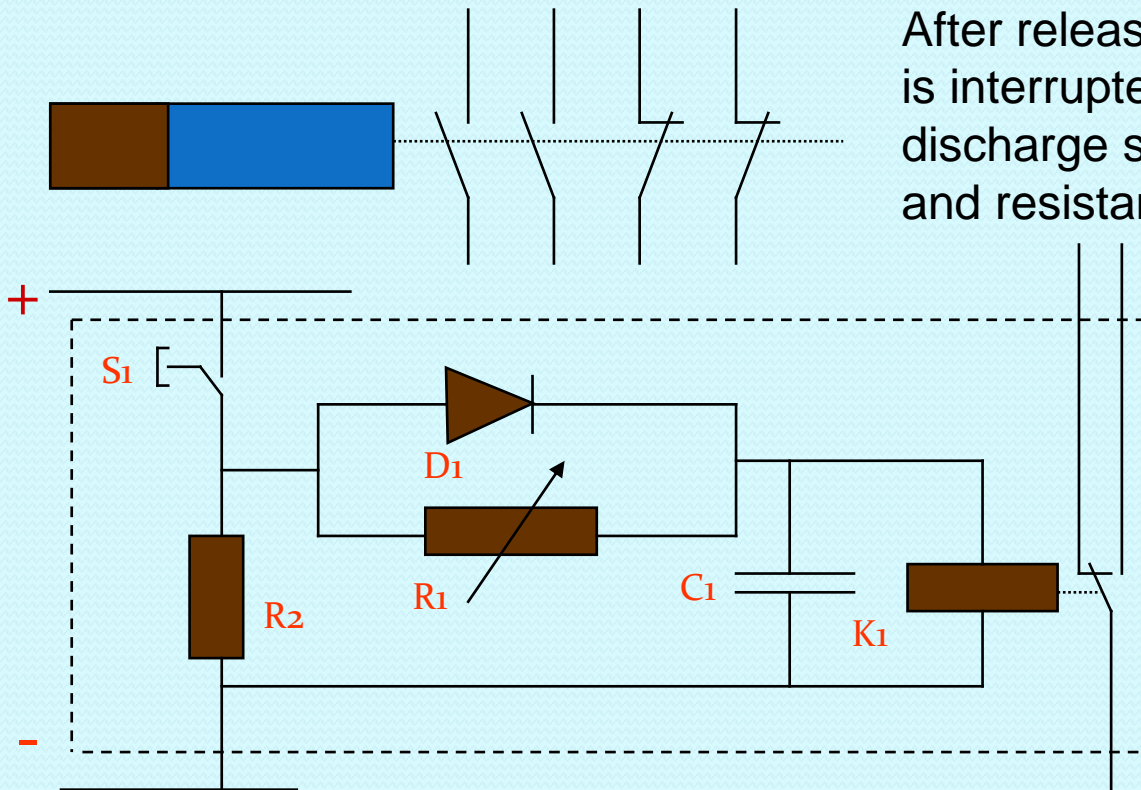
# Switch on Delay Timer

When S1 is actuated, current flows to capacitor C1 through adjustable resistance R1. Diode D1, which is connected in parallel, does not permit the flow of current in this direction. After capacitor C1 has become charged to the switching voltage of the relay K1, the relay switches.



# Switch off Delay Timer

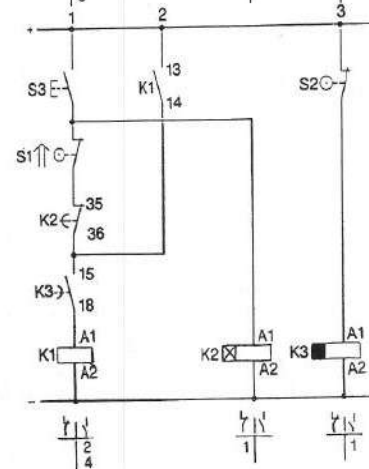
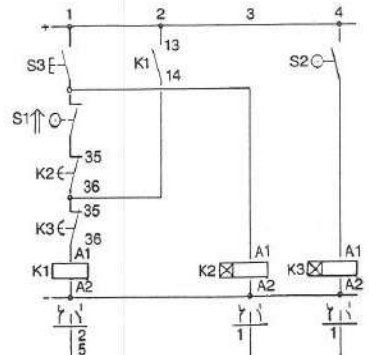
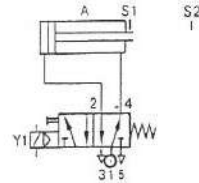
When S1 is actuated, the current flows through diode D1, which is connected in the free flow direction, to capacitor C1 and the relay K1. The relay switches at once. After release of pushbutton S1, the circuit is interrupted. Capacitor C1 can now discharge solely via adjustable resistor R1 and resistance R2.



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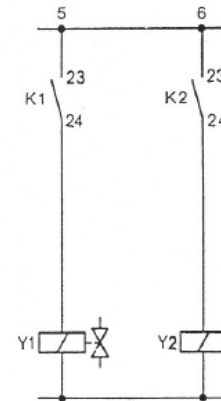
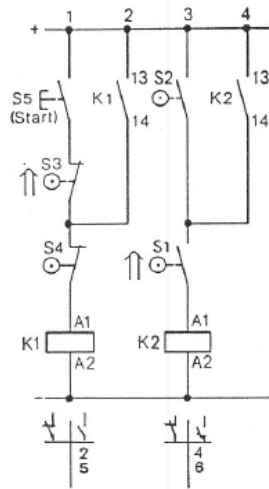
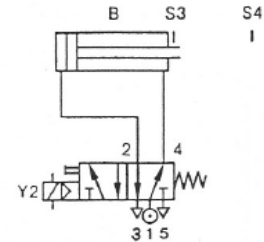
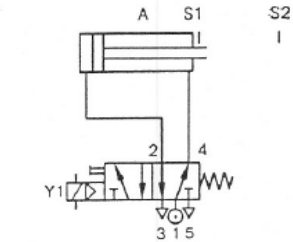
Solution: 11 Cementing press



# Seminar EP 211 Electro-Pneumatics Control

**FESTO**  
**DIDACTIC**

Solution: **13 Lifting device for boxes**

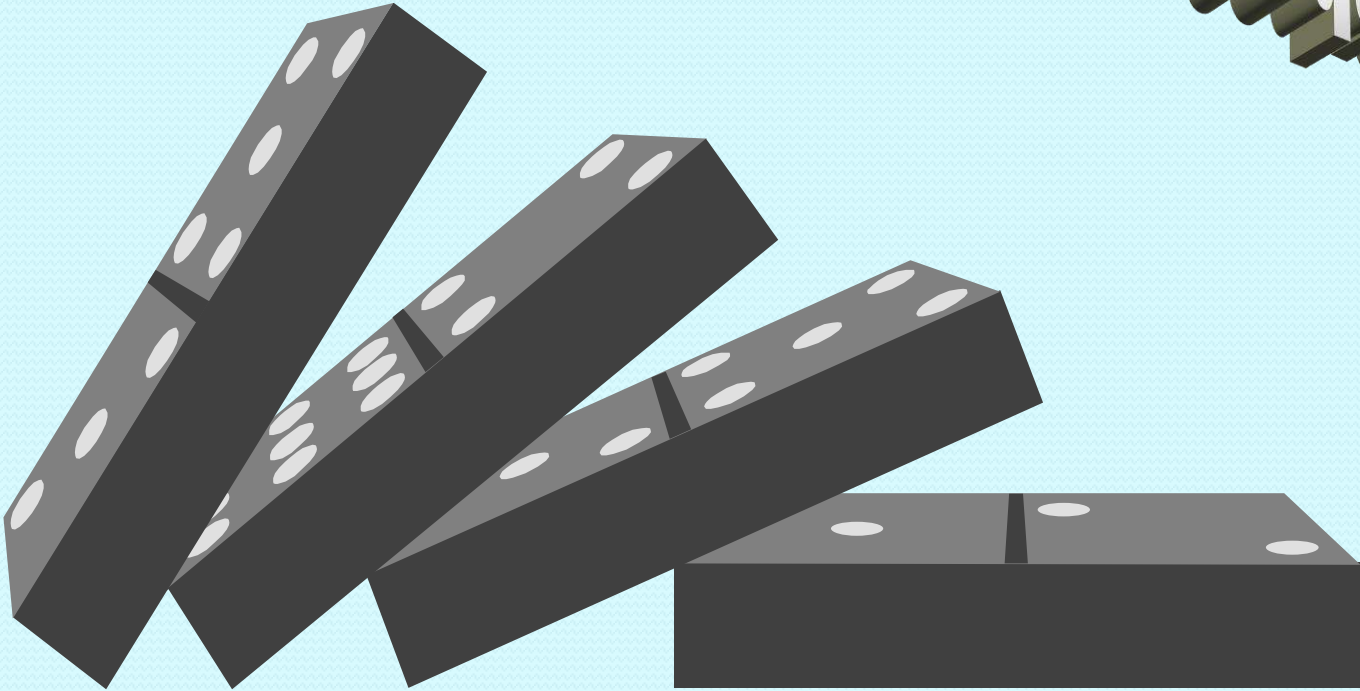


## **SUGGESTED PATTERN IN DESIGNING SEQUENCE CONTROL USING RELAYS**

1. The CONTROL CIRCUIT is the part of the relay ladder, which processes input signals.
2. The POWER CIRCUIT is the part of the relay ladder, which directly controls the electrical loads. (ie., solenoid coils, motors, lamps, buzzers)
3. In the control circuit, each working step is assigned its own STEP RELAY.
4. Each step relay, except the last step relay, employs a self holding contact.
5. A NO contact of the step relay N is placed in series with the first step relay.
6. A NC contact of the last step relay is placed in series with the first step relay.



# Motion Sequences



# Sequence Control System

This is a control system using a mandatory step by step sequence, in which the sequencing from one step to the next programmed step depends on certain conditions being satisfied.



# Representations

- Chronological Order

Cylinder 1.0 extends and lifts the box

Cylinder 2.0 extends and pushes the box

Cylinder 1.0 retracts, then

Cylinder 2.0 retracts

- Tabular Form


Work Step	Motion of Cylinder 1.0	Motion of Cylinder 2.0
1	out	-
2	-	out
3	in	-
4	-	in

# Representations

## - Vector Diagram

Extension represented by 

Retraction represented by 

1.0 

2.0 

1.0 

2.0 

## - Abbreviated Notation

Extension represented by : +

Retraction represented by : -

1.0 +

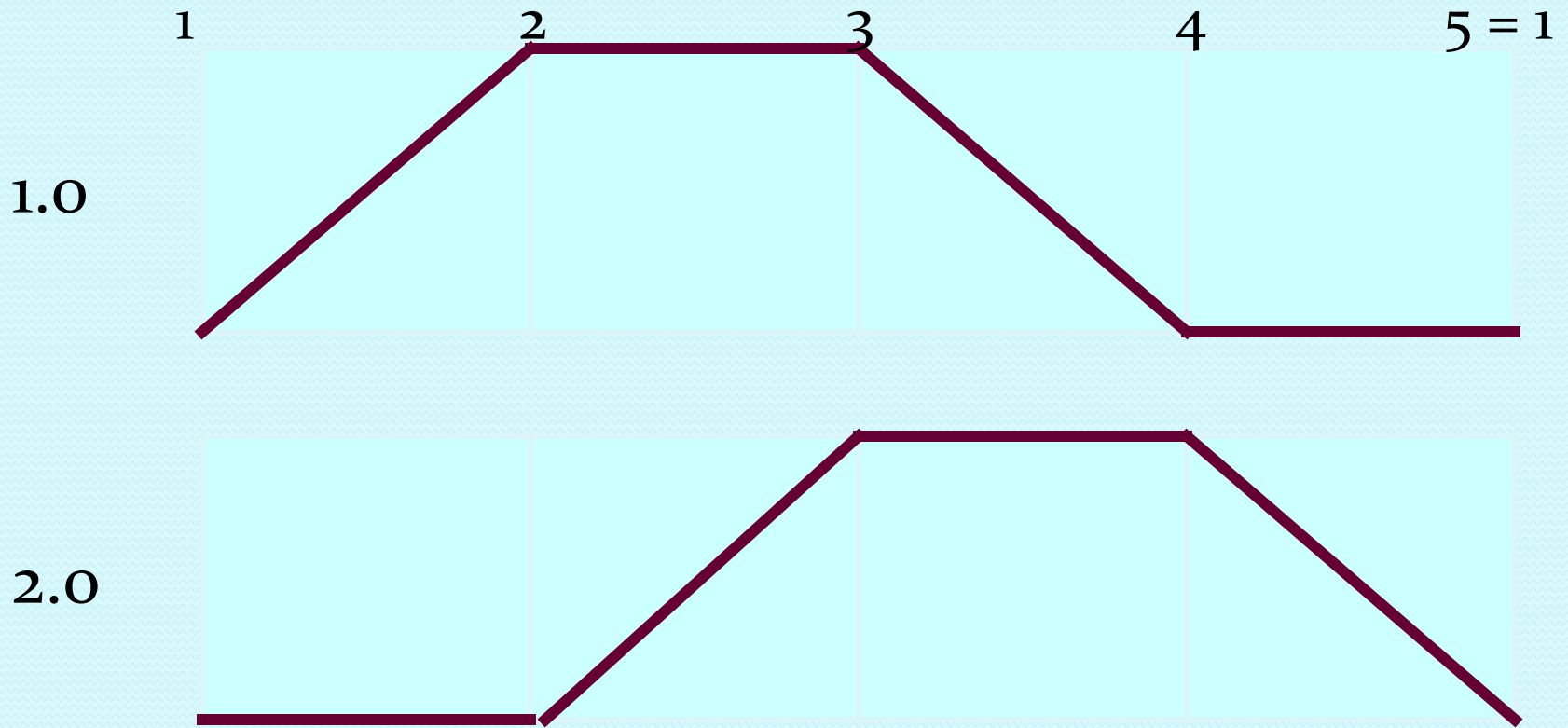
2.0 +

1.0 -

2.0 -

# Representations

- Motion Step Diagram



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**FESTO**  
DIDACTIC

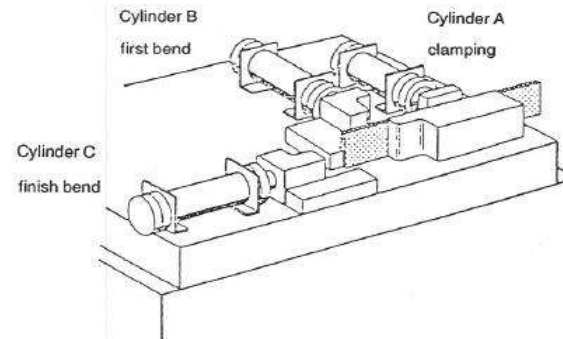
## Problem sheet 15 Bending device

### Problem:

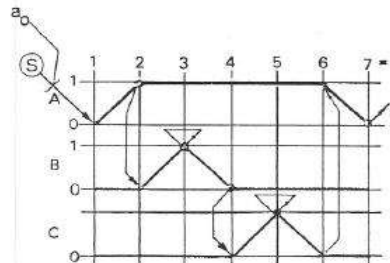
The bending tool is used to bend metal strips.

The strip is inserted manually. After pressing the START pushbutton, cylinder A clamps the workpiece, cylinder B bends the part and returns to its initial position, and cylinder C completes the bending operation. After cylinder C has returned to its initial position, cylinder A releases the part.

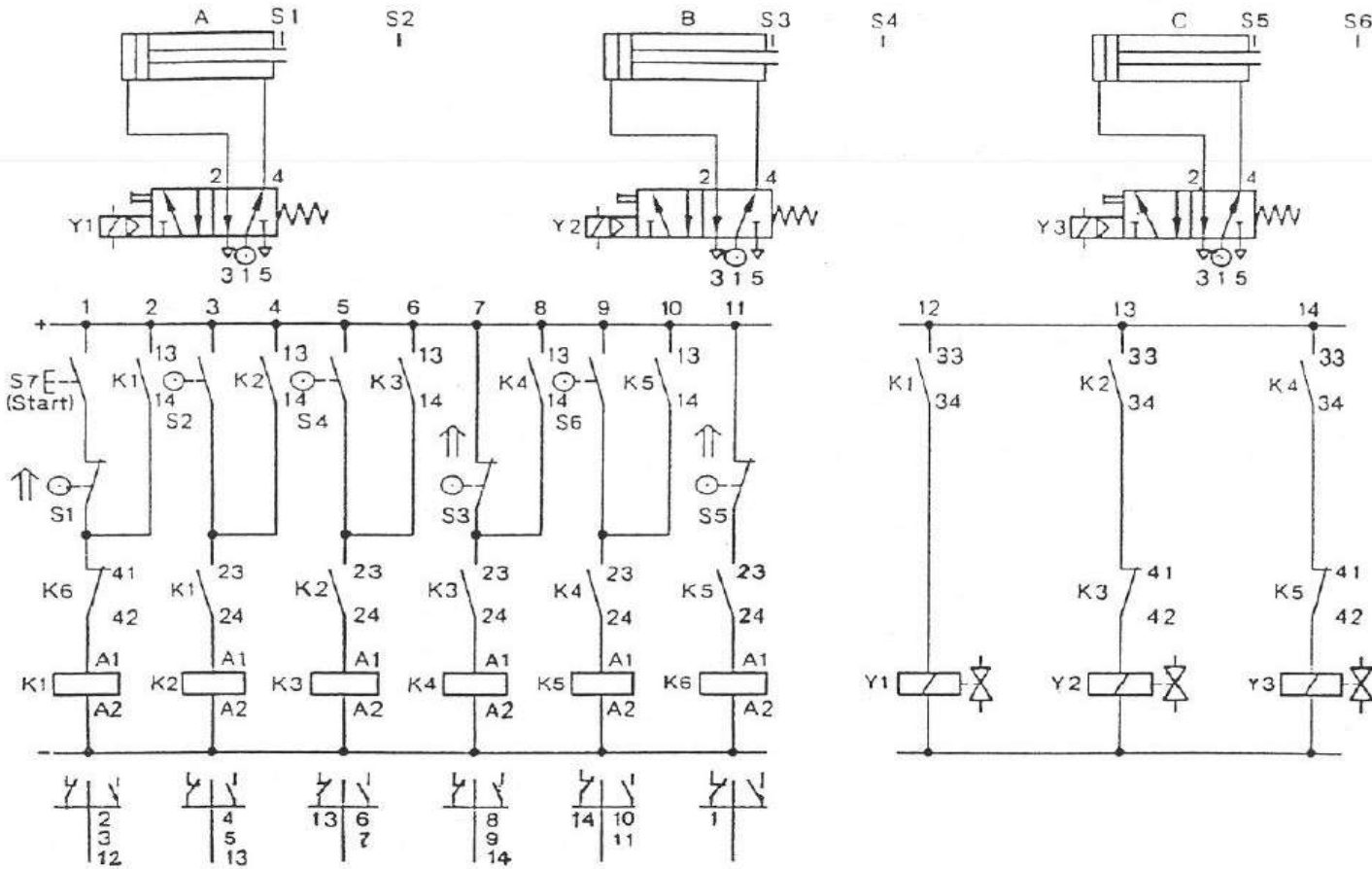
### Positional sketch:



### Motion-step diagram:



### Solution: 15 Bending device





# **Modular Production System MPS**



